

carmenes

Searching for Habitable Planets around M Dwarfs



Andreas Quirrenbach
and the CARMENES Consortium

The 3.5m Telescope on Calar Alto (Southern Spain)



Goals and Plan for CARMENES



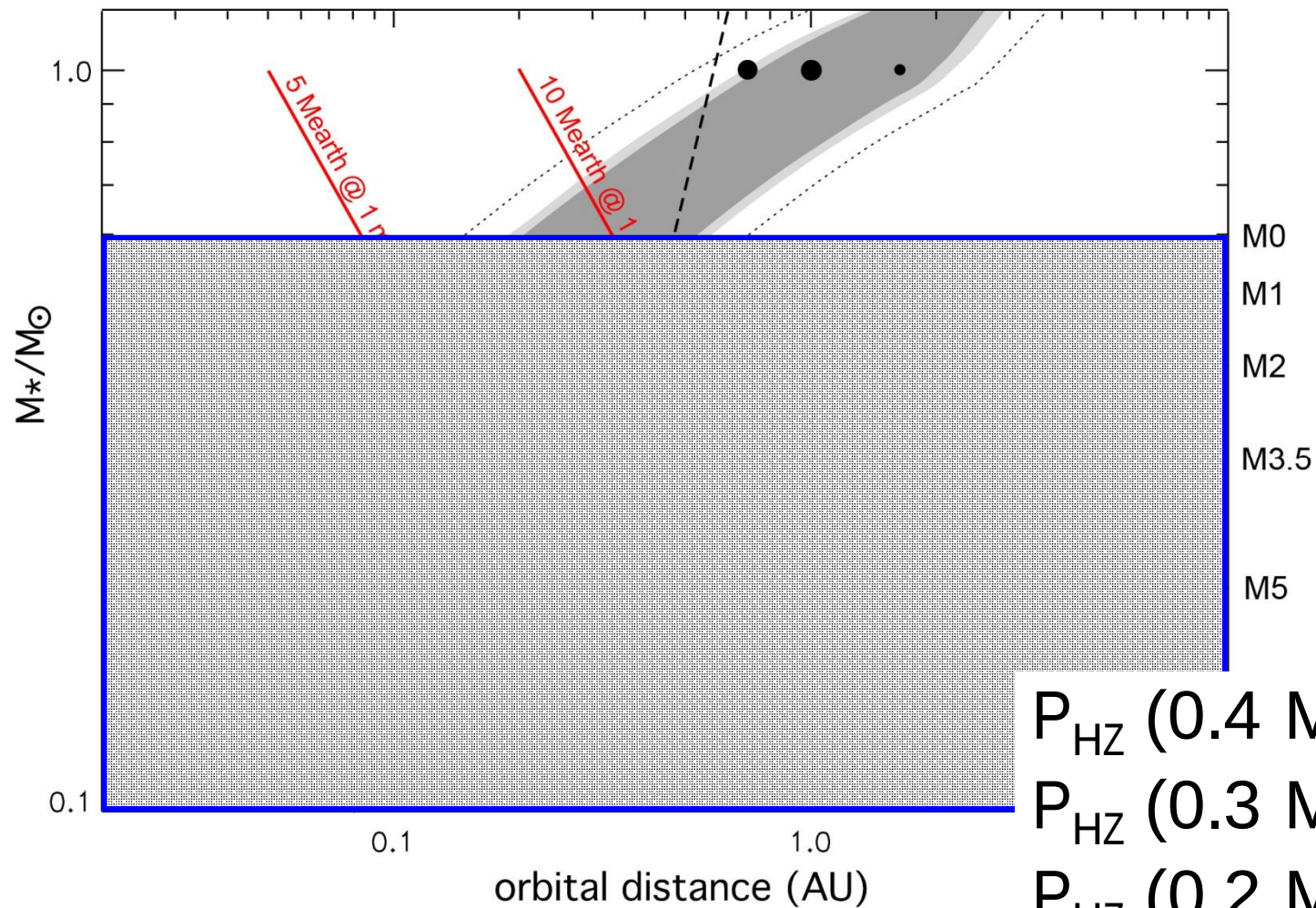
- Search for Earth-like “habitable” planets around low-mass stars (M-stars)
 - Number and formation mechanisms
 - Properties and “habitability”
- Survey of 300 M stars
 - Simultaneously in visible light and near-infrared
- 10 data points per star and year
 - 600 to 750 nights needed
 - Guaranteed in contract with CSIC and MPG



Why M Dwarfs?

- M dwarfs are very abundant (almost 2/3 of all stars) and thus nearby
 - Excellent targets for follow up
- M dwarfs are small ($\leq 0.5 M_{\odot}$) and faint
 $\Rightarrow$ “habitable zone” is close to star $\Rightarrow$ relatively large signal $\Rightarrow$ good chance to find Earth-like planets
- Currently no instrument optimized for M stars exists

A “shortcut”: M-type dwarfs

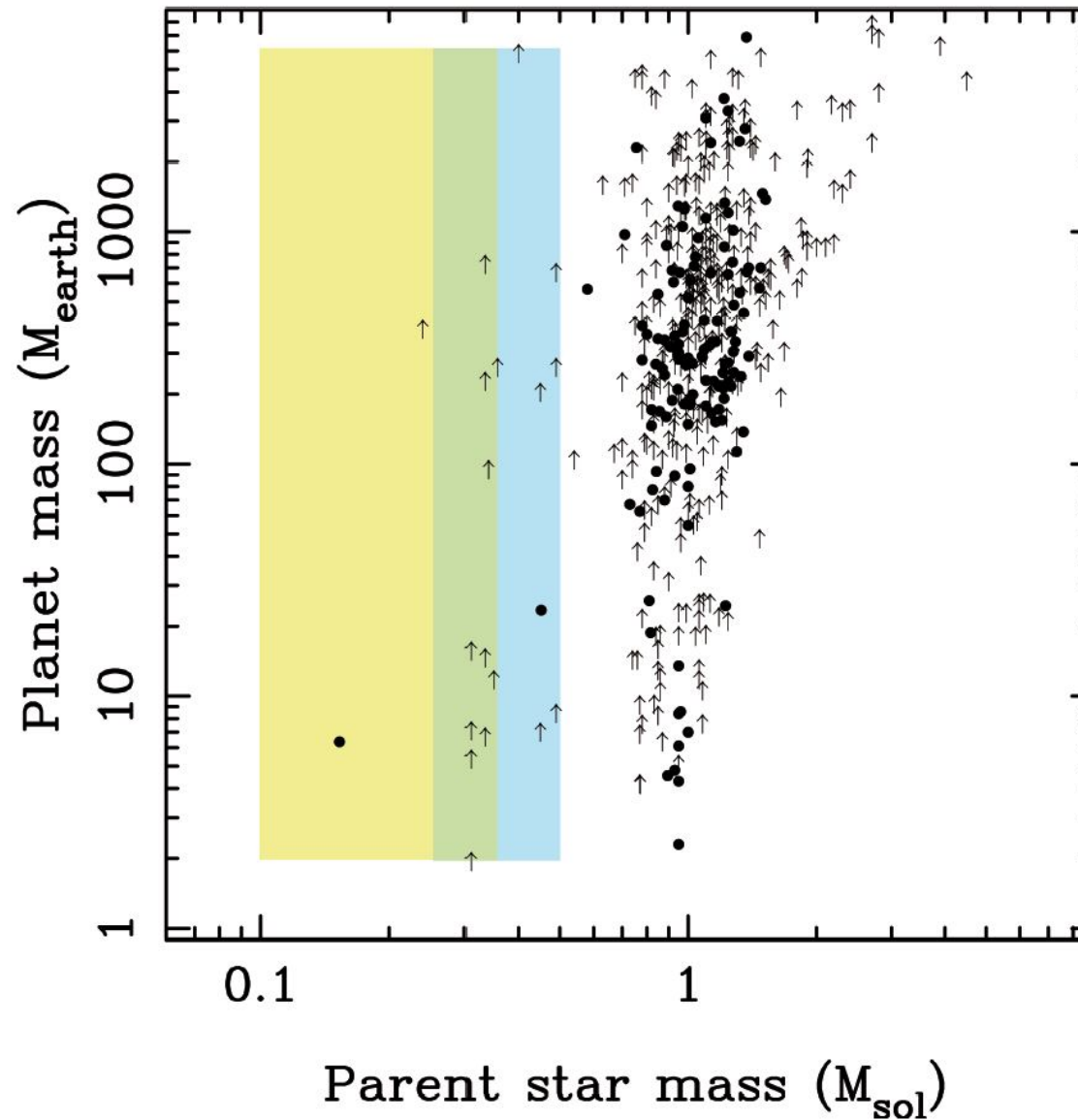


$$P_{\text{HZ}} (0.4 M_\odot) = 25 \text{ d}$$

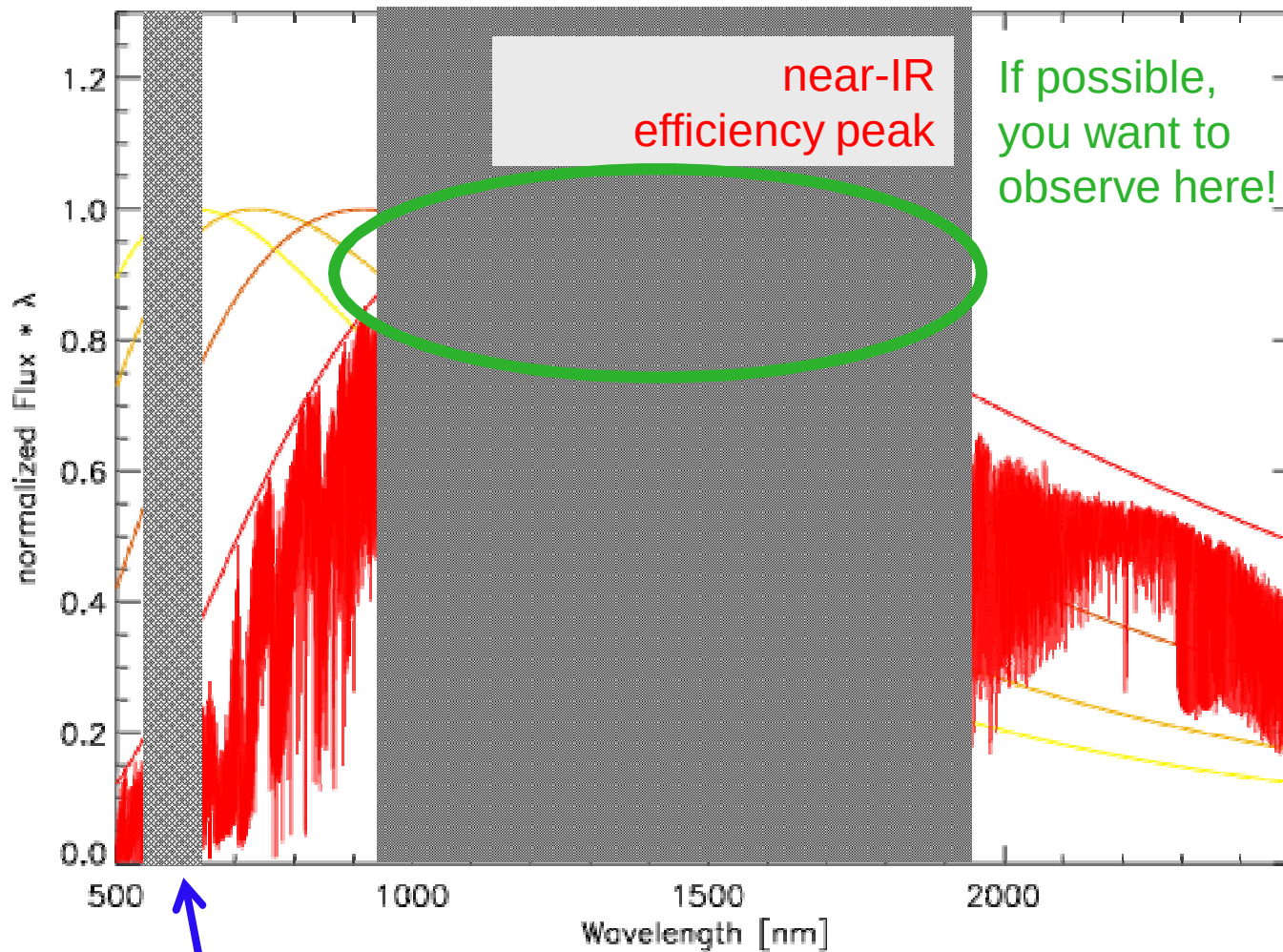
$$P_{\text{HZ}} (0.3 M_\odot) = 18 \text{ d}$$

$$P_{\text{HZ}} (0.2 M_\odot) = 12 \text{ d}$$

A new niche

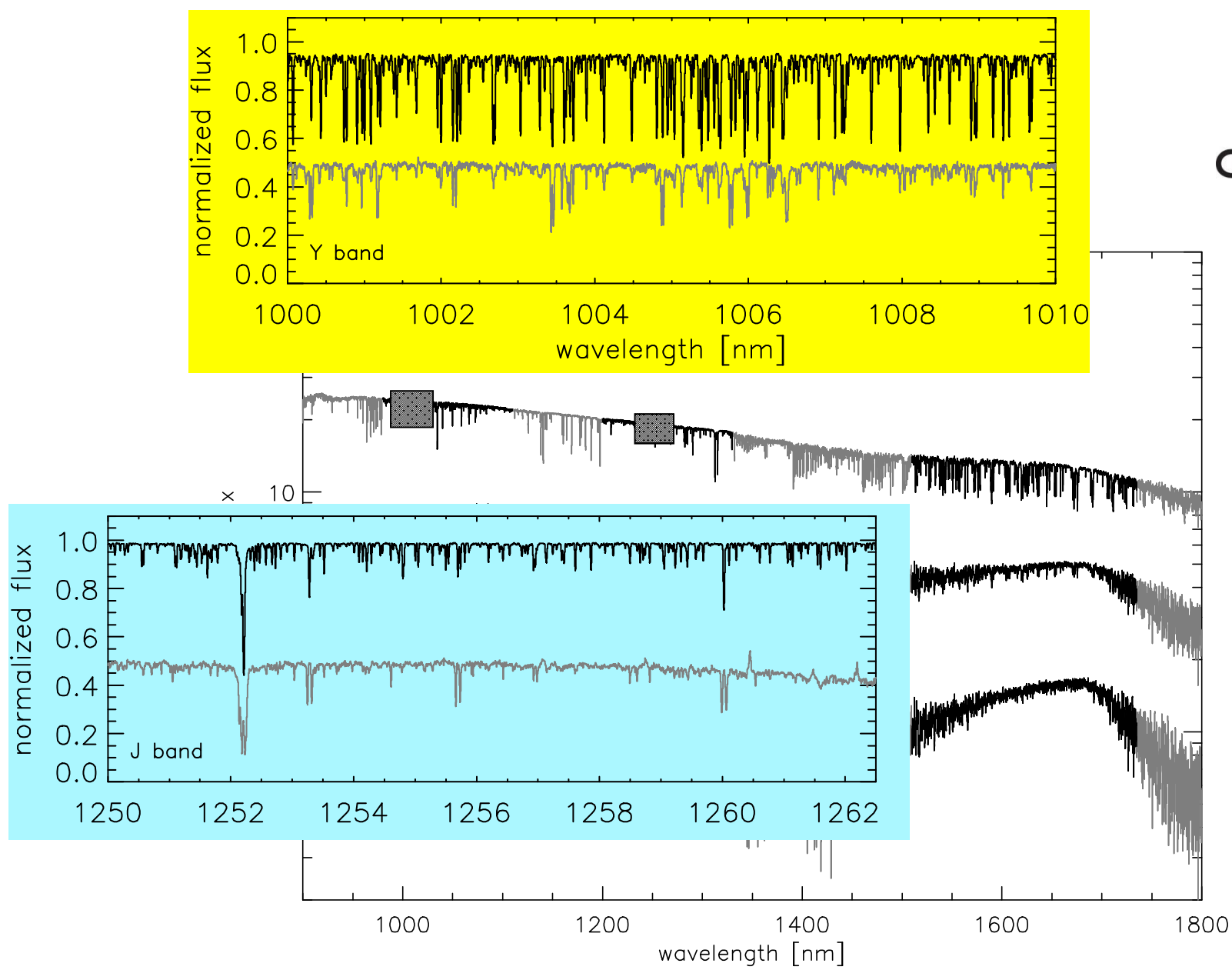


The SED of M-type stars



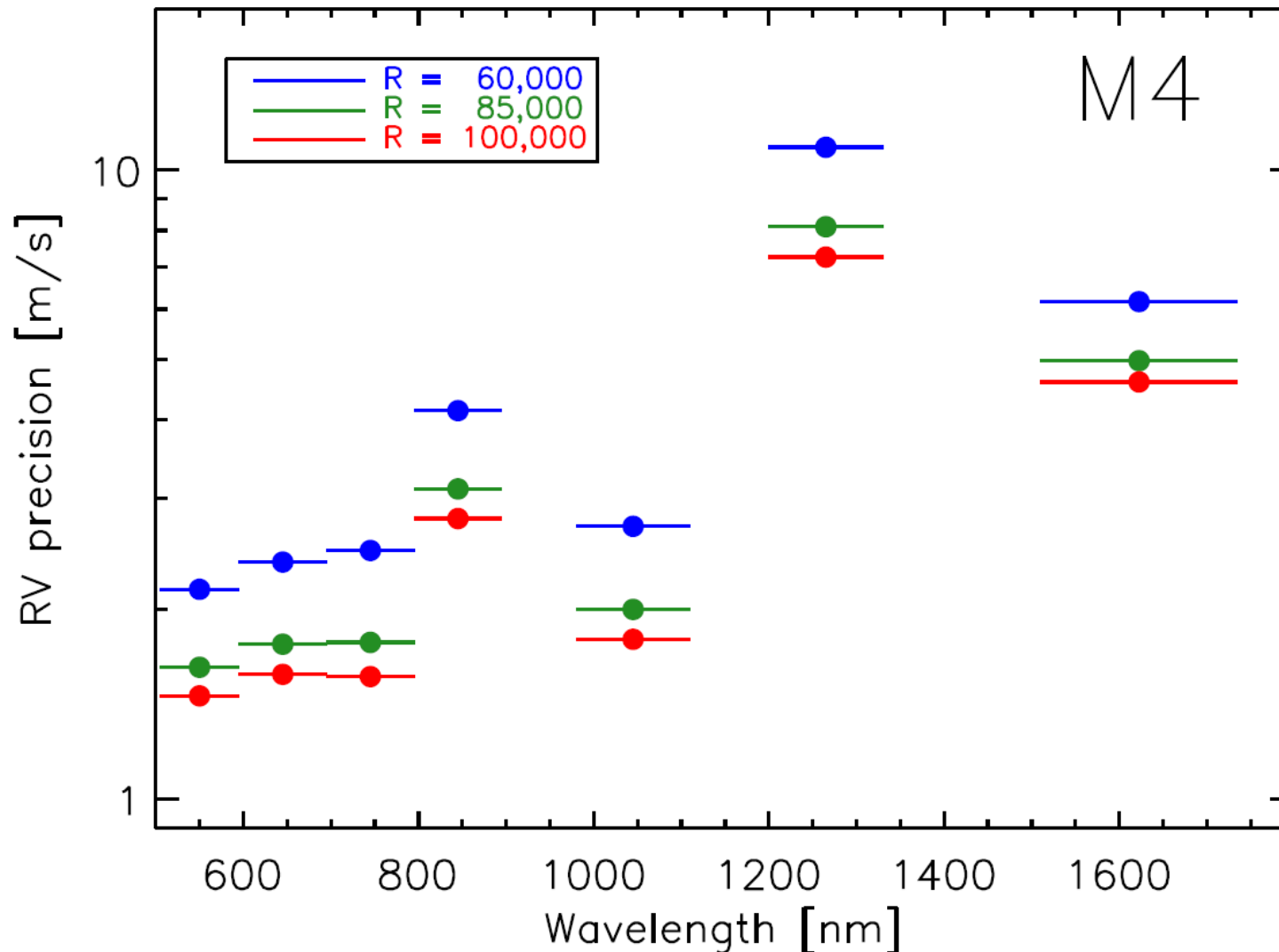
If possible,
you want to
observe here!

"classical" *visible light* RV instruments

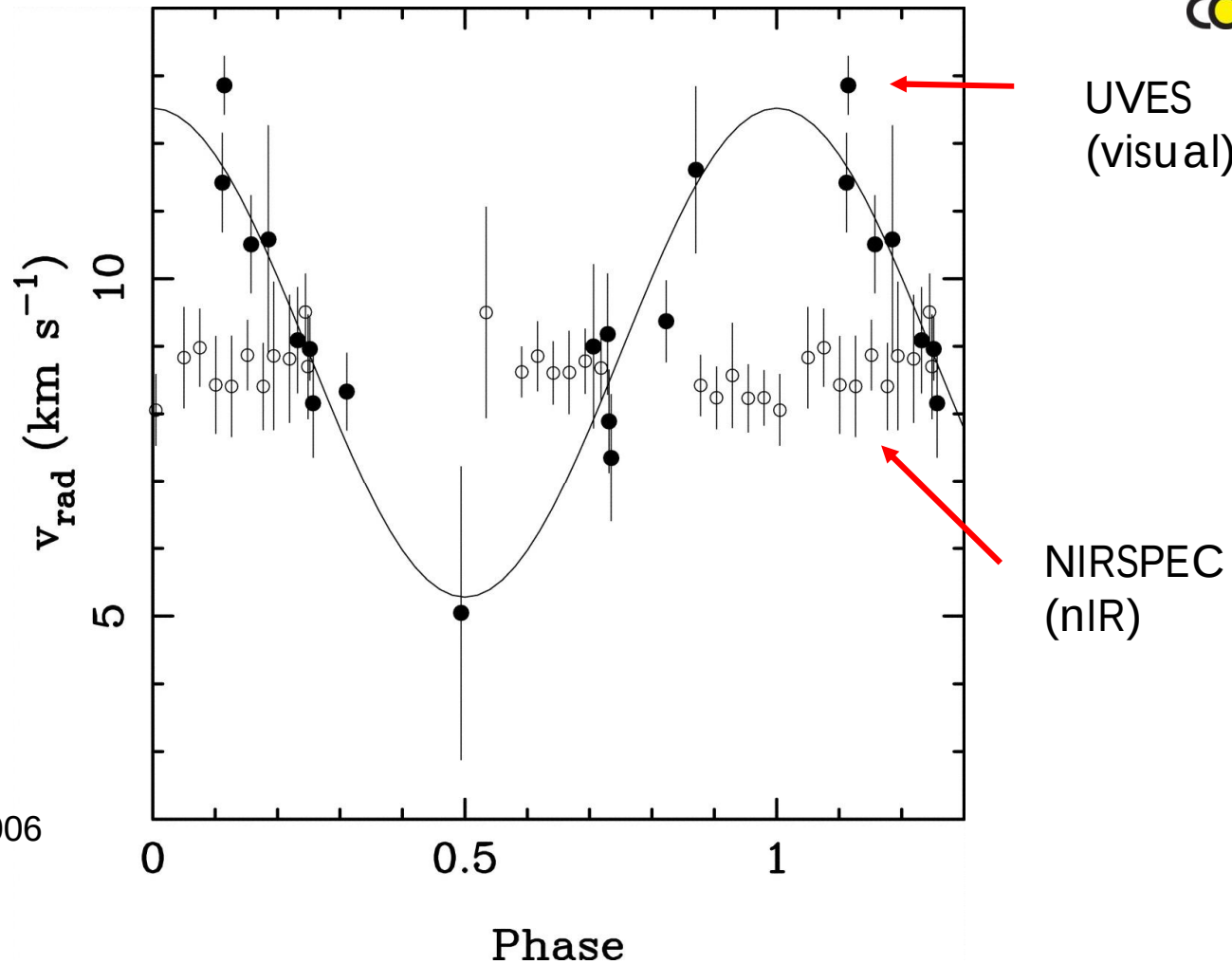


PHOENIX models

Relative Precision Achievable for M4 Star in Visible and near-IR



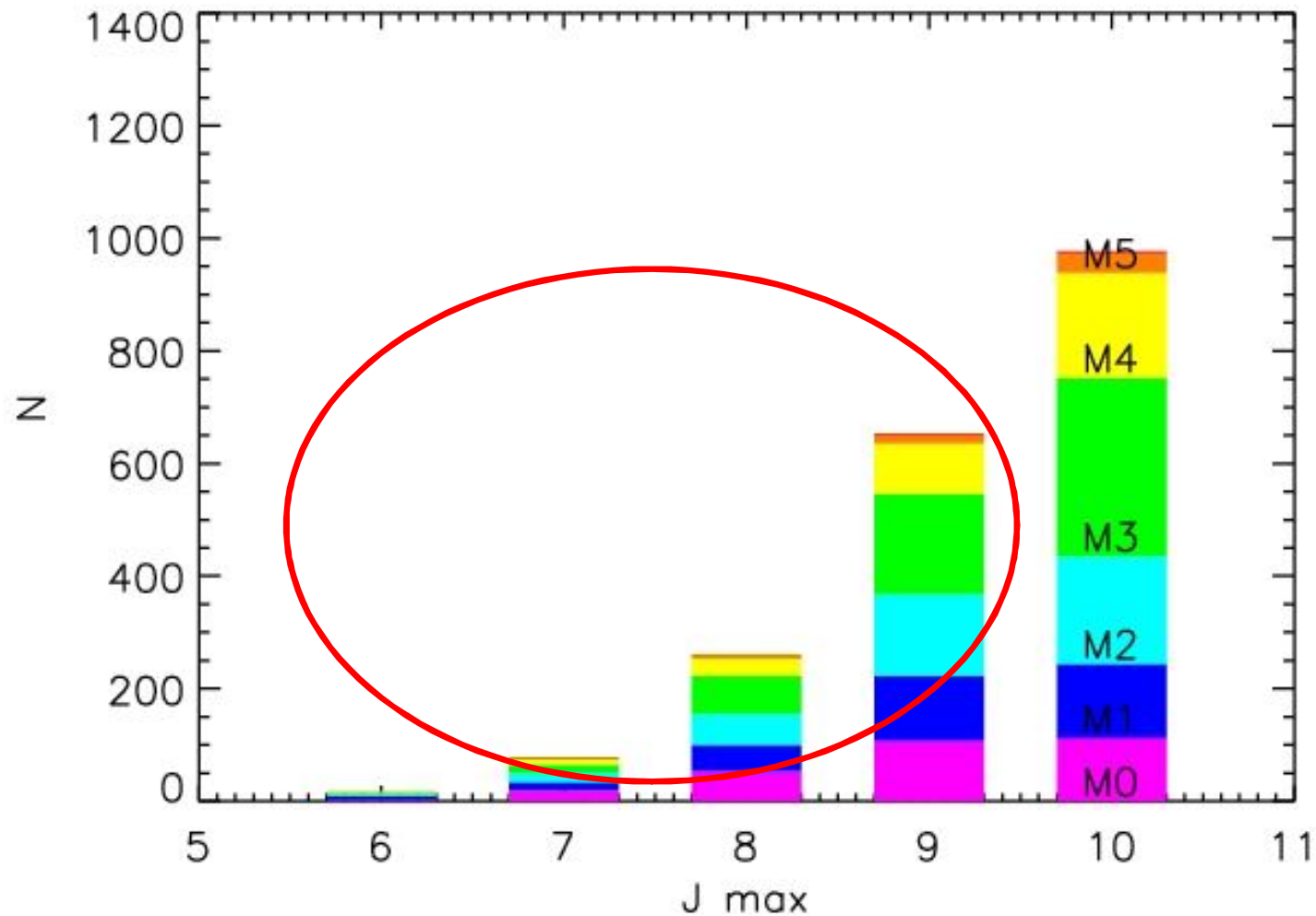
Let's talk about $jitter_{\text{er}}$



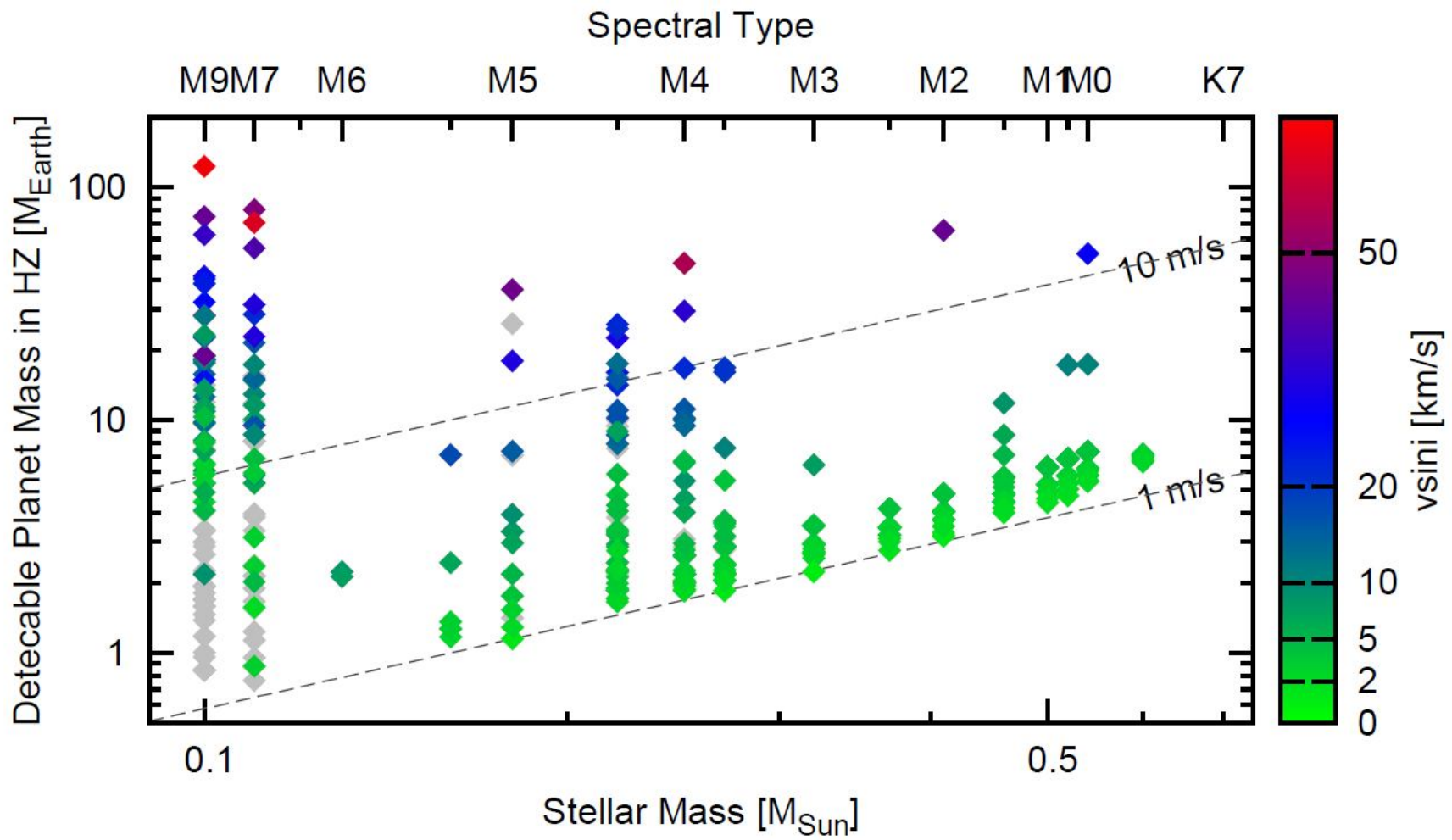
Martin et al. 2006

RV curve of the active M9 dwarf LP-944 20

Stellar sample



Detectability simulations

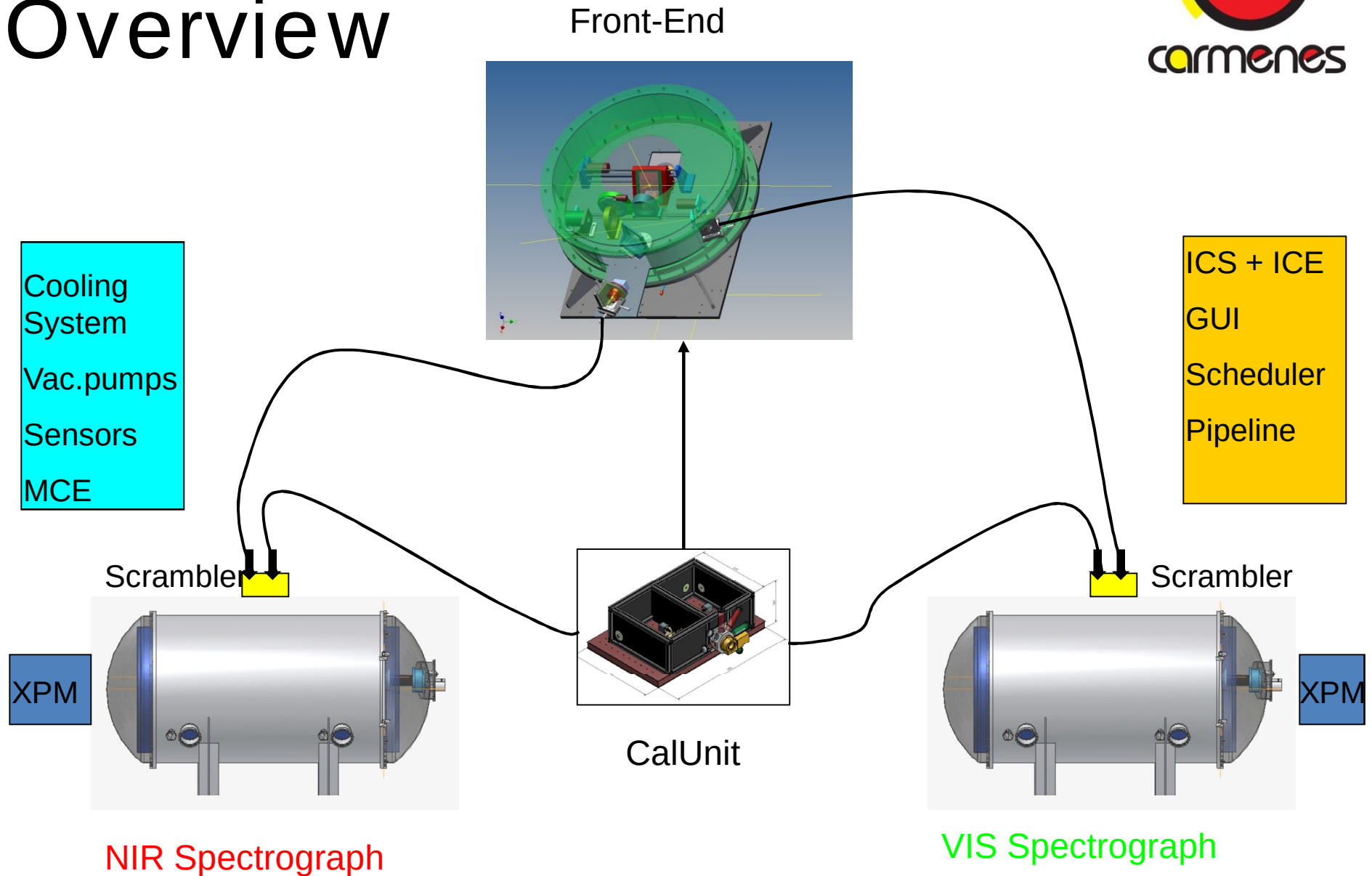


Guiding Principles for Instrument



- Single-purpose instrument
 - Design driven by survey requirements
- High stability for terrestrial planet detection
 - Thermal and mechanical stability
 - Stable input
 - No moving parts in spectrographs
- High resolution for slow rotators
- Large wavelength coverage for discrimination against intrinsic variability
- High efficiency for faint stars

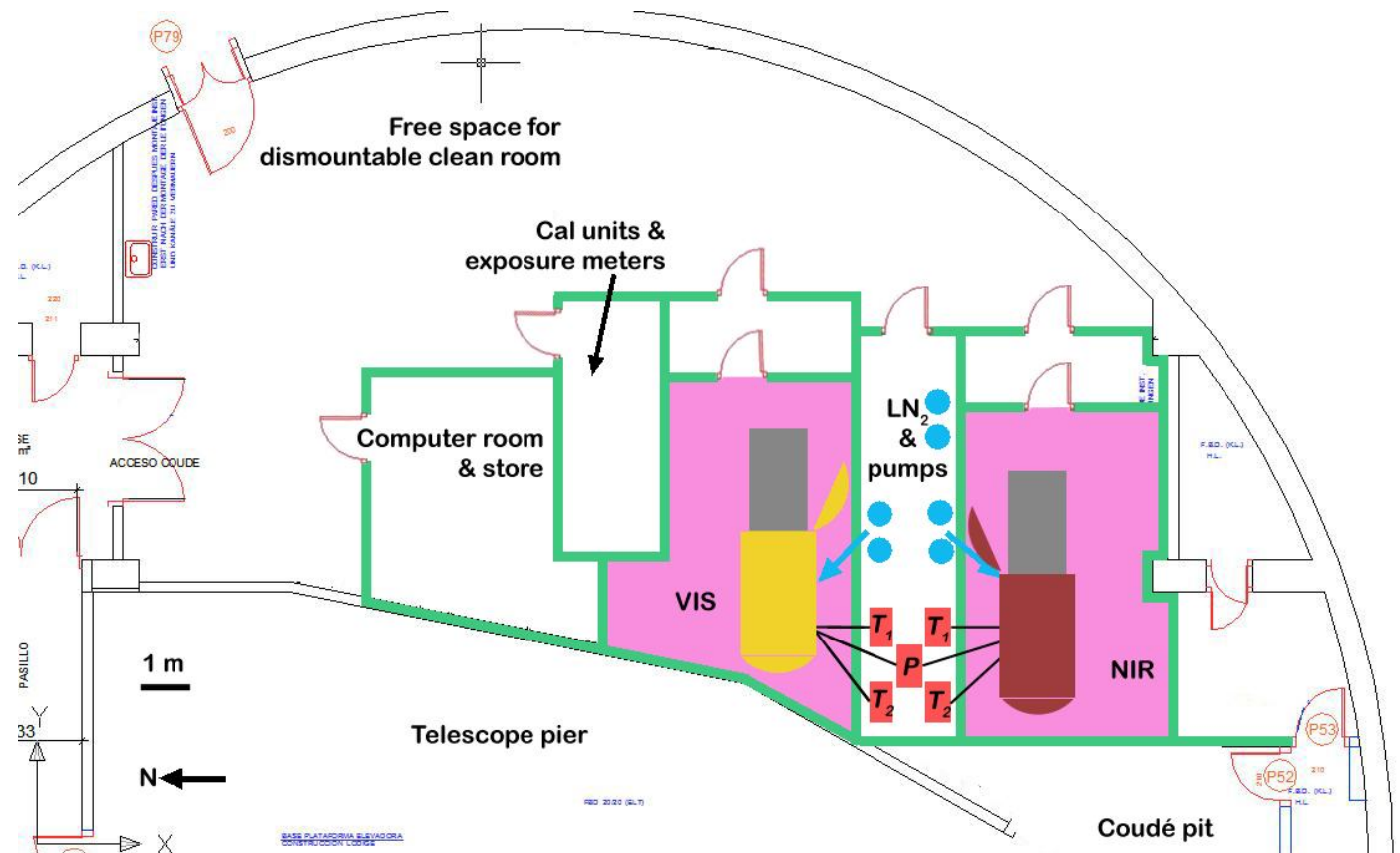
Instrument Overview



Instrument Location



- 1 Climatic room for each channel.
- Environmental conditions:
285-288 ± 1 K.



Properties of Spectrographs



- Optical spectrograph
 - 0.53 ... 1.05 μm , $R = 82,000$
 - Precision ~ 1 m/s
 - Vacuum tank, temperature stabilized
 - 4k x 4k deep depletion CCD detector
- Near-Infrared spectrograph
 - 0.95 ... 1.7 μm , $R = 82,000$
 - Vacuum tank, cooled to 140K, stabilized
 - Precision goal 1 m/s
 - Two 2k x 2k Hawaii 2.5 μm detectors

Spectrograph Layout



**White pupil fiber-
fed echelle
spectrograph**

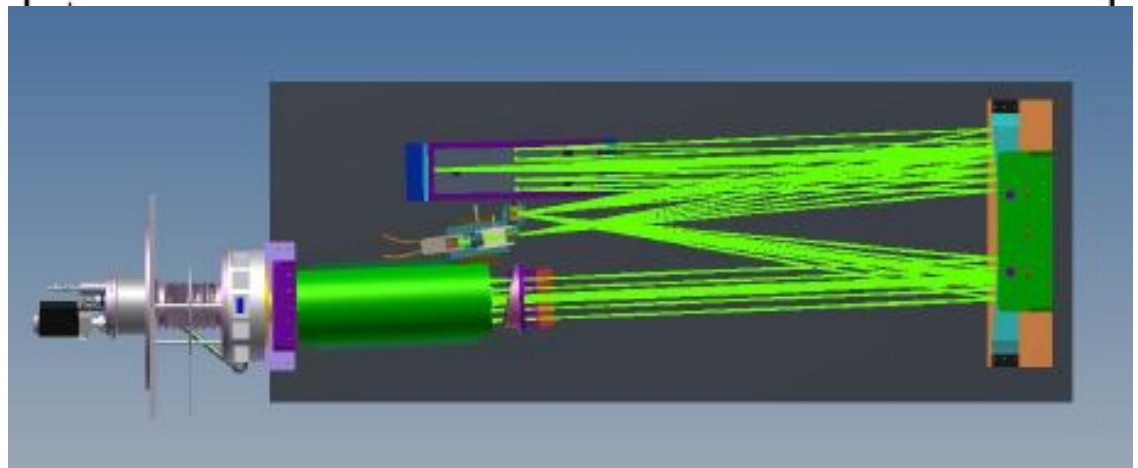
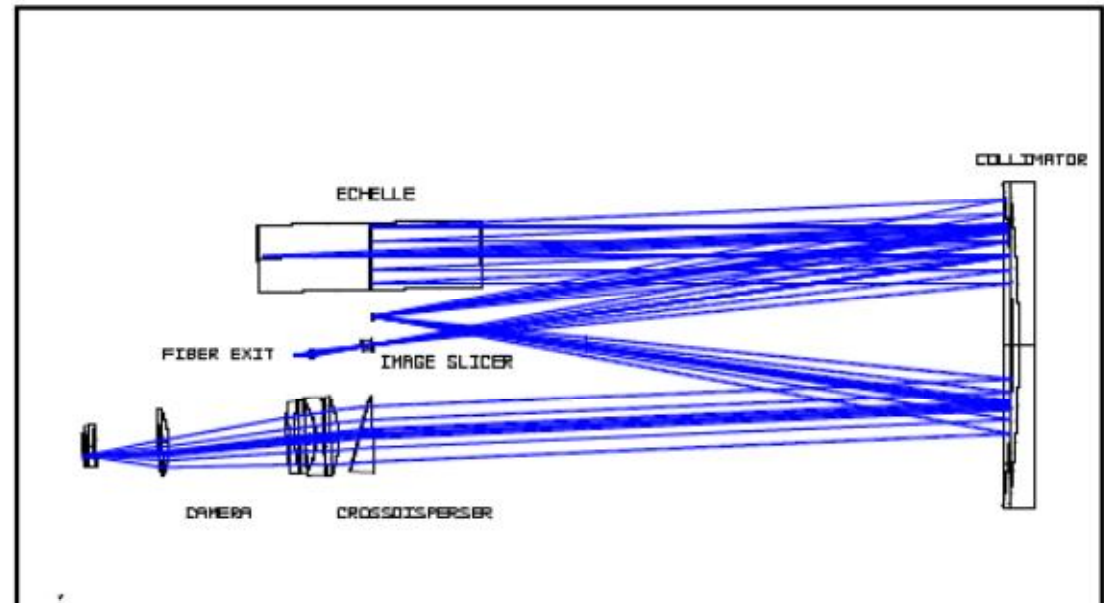
FiberExit-FNoptics-
Slicer

Single-piece
Collimator (3passes)

R4 Echelle grating

Grism cross-
disperser

Dioptric camera



Spectrograph and Vacuum Tank Layout

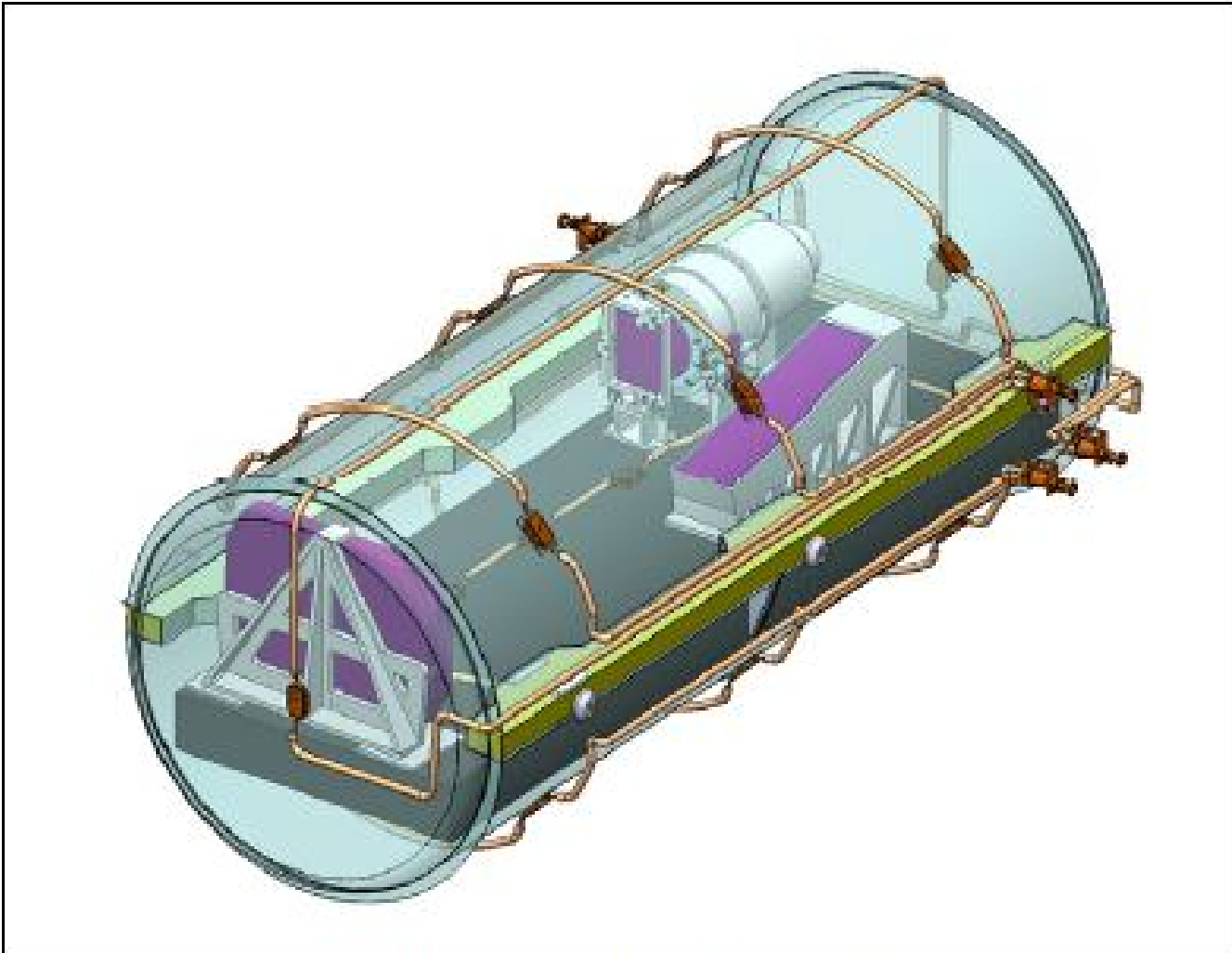
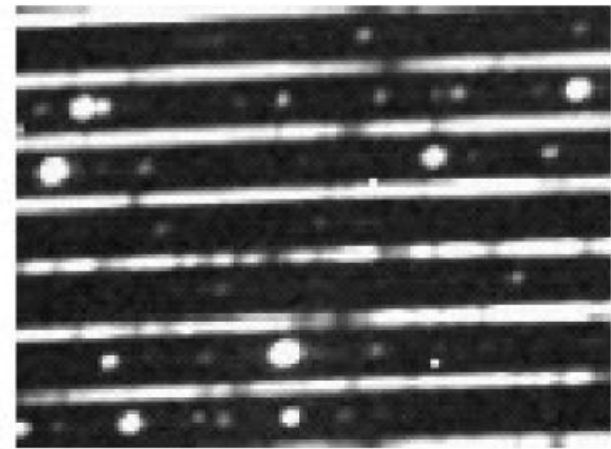
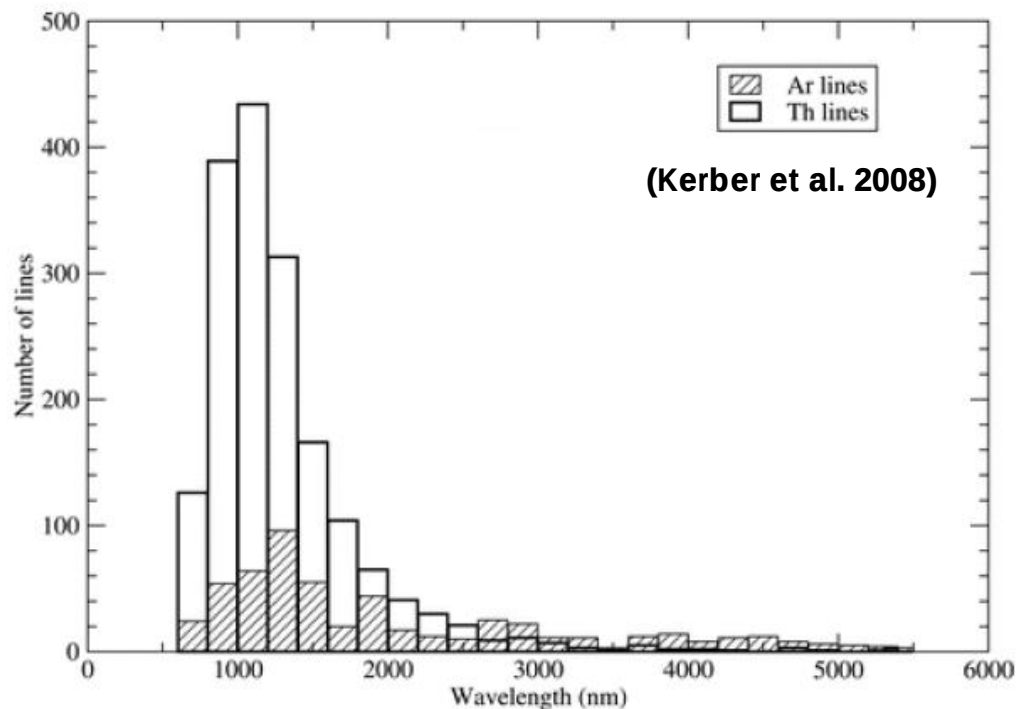


Figure 2. General view of the CARMENES NIR Optical Bench fully assembled.

Calibration: Wavelength reference

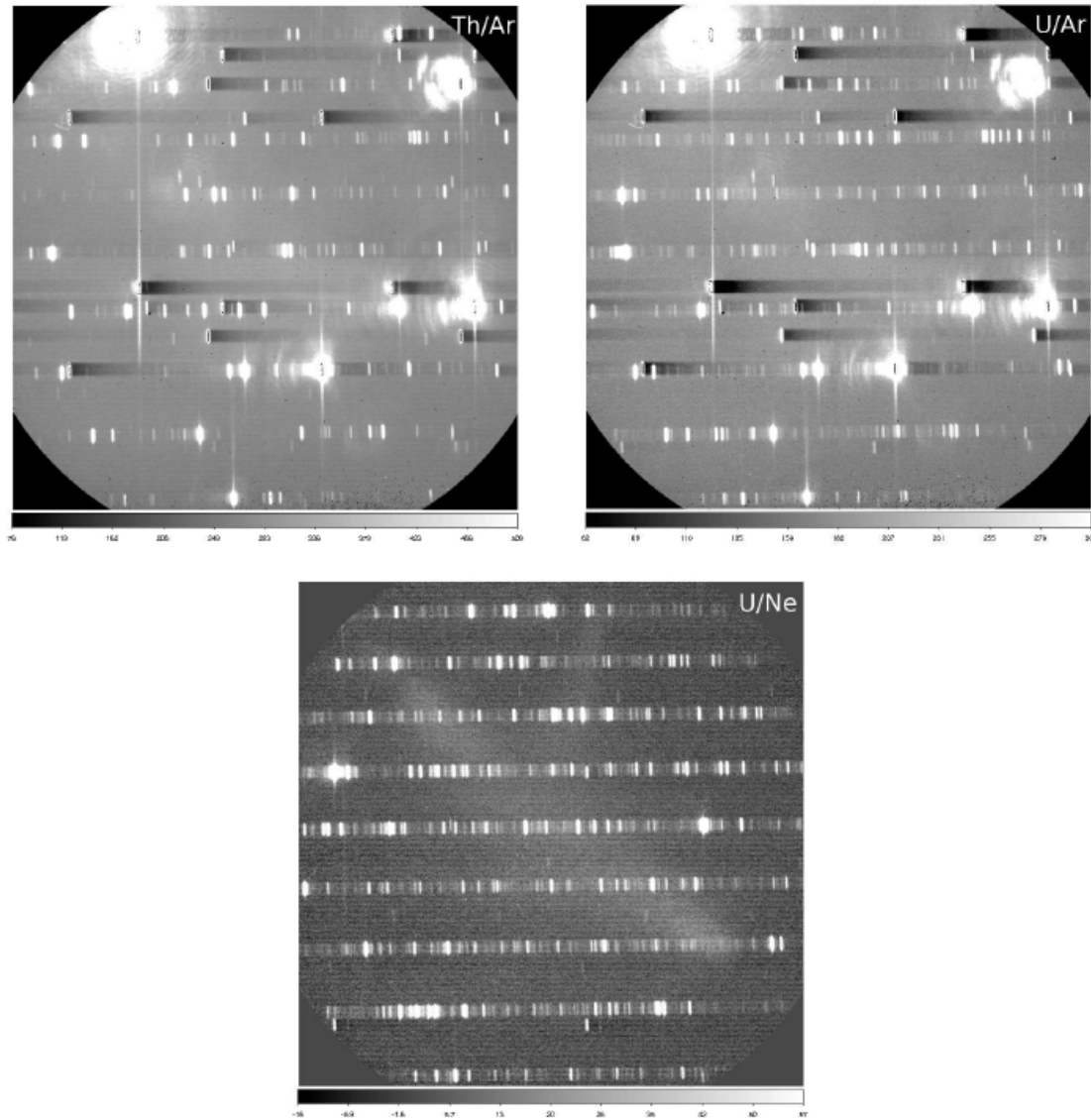


- Hollow cathode lamps: Thorium-Argon-Neon for daily and master calibrations.



Enough suitable Th-Ar lines in the NIR range

Comparison of Th/Ar, U/Ar and U/Ne Lamps

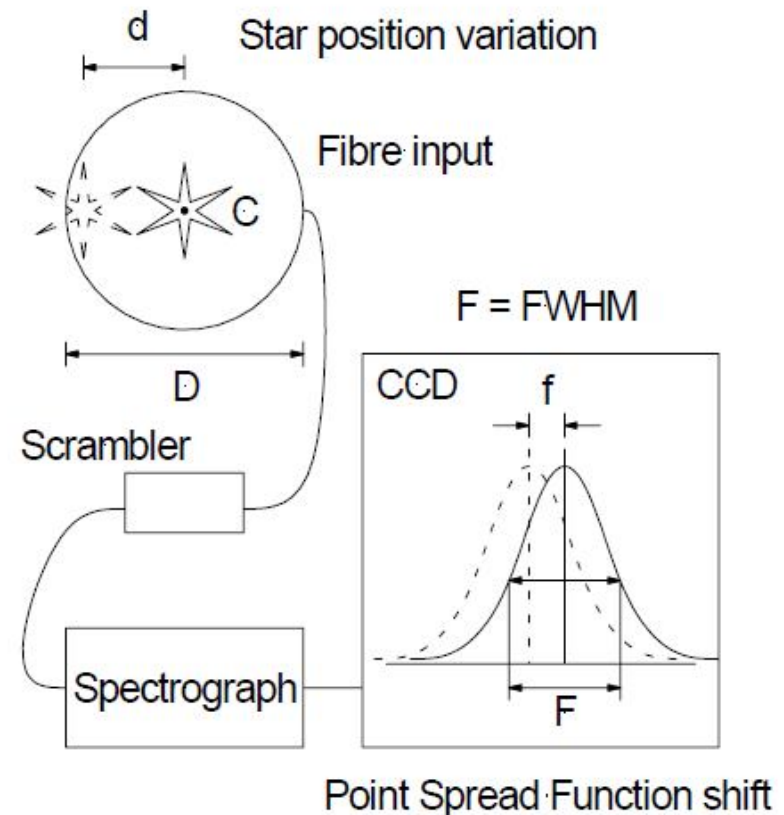


Redman et al. 2011

Requirements for RV precision



- Stability of slit illumination and instrument are requirements for high RV precision.
- Current solutions for this unavoidable problem are:
 - Highly stable injection of light in the fibre (only possible with precise guiding $\sim 0.1''$)
 - Image scrambler



Avila & Singh (2008)

Near field and far field scrambling

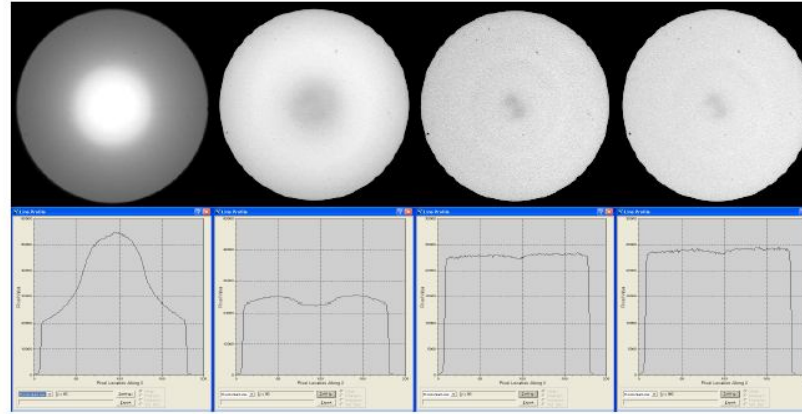


Figure 3. Near field scrambling patterns in a 600 μm , 3 m FVP fibre. From left: a 250 μm spot is centred on the fibre. The spot is shifted by 175 μm . The spot is in the centre but the fibre is squeezed with $\Delta\text{FRD} = 20\%$. The spot is shifted by 175 μm and fibre squeezed.

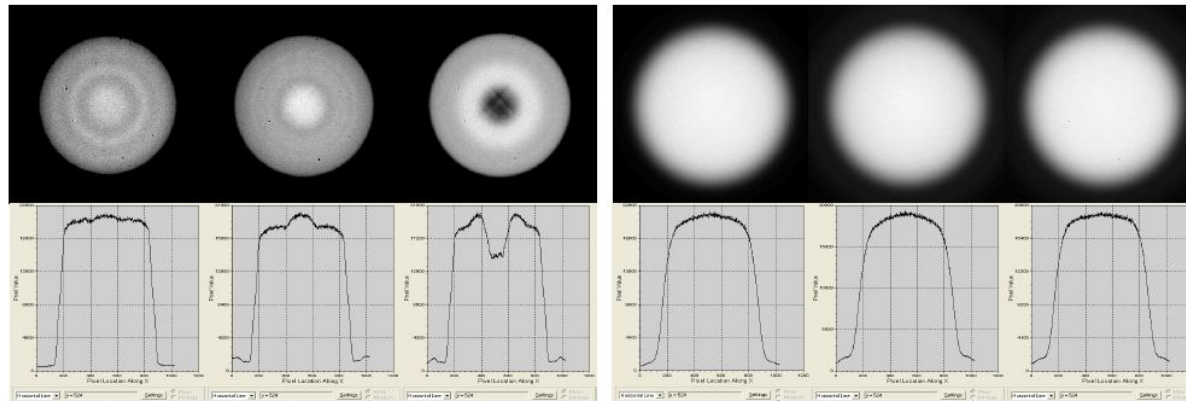


Figure 13. Far field patterns from a WF 200x200/420 N CeramOptec 3 m fibre. Spot size: 150 μm , input aperture beam: F/2.3. Three pictures left: the fibre is free and the spot is at the centre, +50 μm and -50 μm . The three on the right, the fibre is squeezed ($\Delta\text{FRD}=5\%$) and the spot is at the centre, +50 μm and -50 μm

RV error sources

Error source	Contribution	Comment
Drift measurement with sim. arcs	< 0.2 m/s	~ 300 arc lines typically > 60 s
Wavelength calibration	< 0.1 m/s	> 1000 arc lines during daytime calibration
Instrument SRF measurement	< 0.3 m/s	> 1000 arc lines during daytime calibration
Photon-weighted centre of integration time	< 0.1 m/s	Median sky conditions (1m/s corresponds to 30s)
Opto-mechanical stability	< 0.3 m/s	< 0.1 pixel drift during an observation
Centring and guiding	< 0.3 m/s	Spatial scrambling of fibre and CCD guiding
Background subtraction	< 0.1 m/s	Stability of background, dark current, bias etc.
Total non-source noise	< 0.6 m/s	RMS
Source photon noise	0.8 m/s	$m_V=10.5$ M6 V ($v \sin i=5$ km/s) at 10 pc S/N=150 in 14 min
Source radial velocity jitter	(0-20 m/s)	Sources will be selected for minimum radial velocity jitter
Atmospheric noise	~0.5 m/s	
Total noise (1σ)	1.1 m/s	For typical M6 V star at 10 pc (no radial velocity jitter)

Wavelength calibration

Exposure meter

Current approach: do the best

Scrambling

Reduction strategy

Scrambling

RV error sources from Barnes & Jones, UKIRT planet finder.

The CARMENES Consortium



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- Centro Astronómico Hispano-Alemán

Time Line



Official Start	11/2010
Preliminary Design	to 07/2011
Final Design	07/2011 – 07/2012
Construction	07/2012 – 10/2013
Commissioning	11/2013 – 02/2014
Data Taking	03/2014 – 12/2018