



[VLT Software Workshop - April 1999](#)

[Event Handler \(EVH\)](#)

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INTRODUCTION

The Event Handling Toolkit is a set of C++ classes to develop event driven applications on workstations.

Development of applications requires a knowledge of concepts for event driven programs and object-oriented programming techniques.

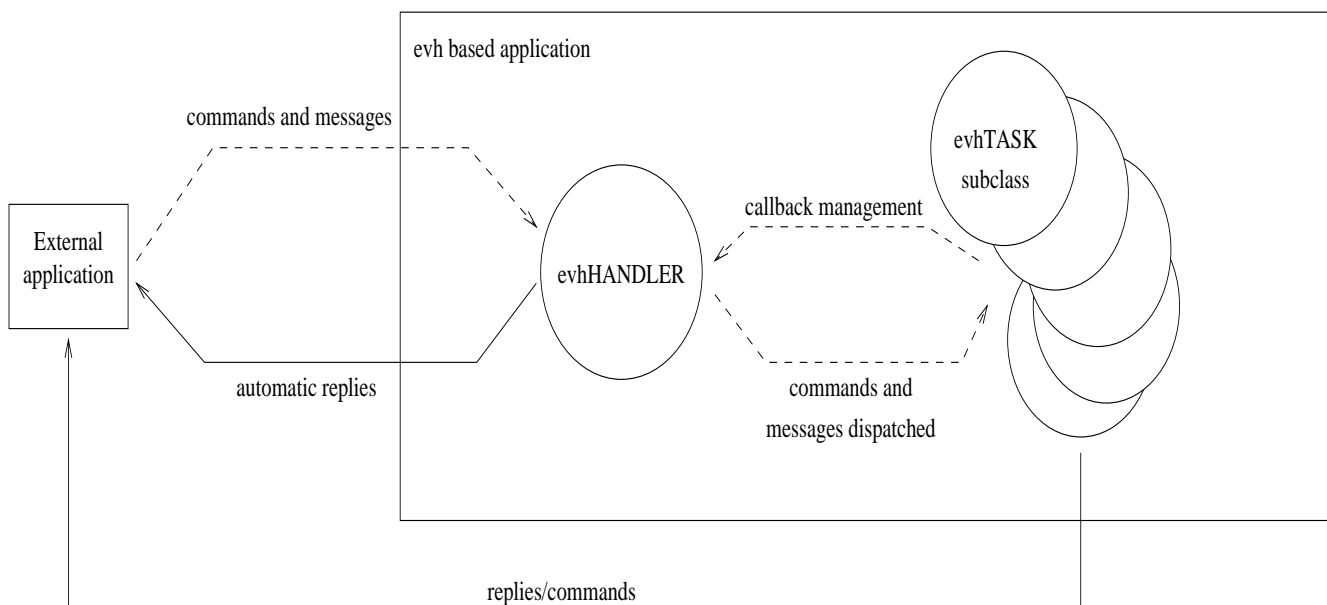
It runs only on Workstation.

Purpose of EVH is:

- Provide a framework to implement easily workstation applications that receive and send commands and messages.
- Implement in a standard way common application patterns
- Prevent common errors in applications
- Support object-oriented design and development
- Provide tools for testing and debugging of applications.

The main loop

- Processes are designed in an **event driven** way
- The implementation is based around the *evhHANDLER* class



**The design of every process consists mainly
in the design of the independent objects
providing
the methods to be attached
as callbacks to the events**

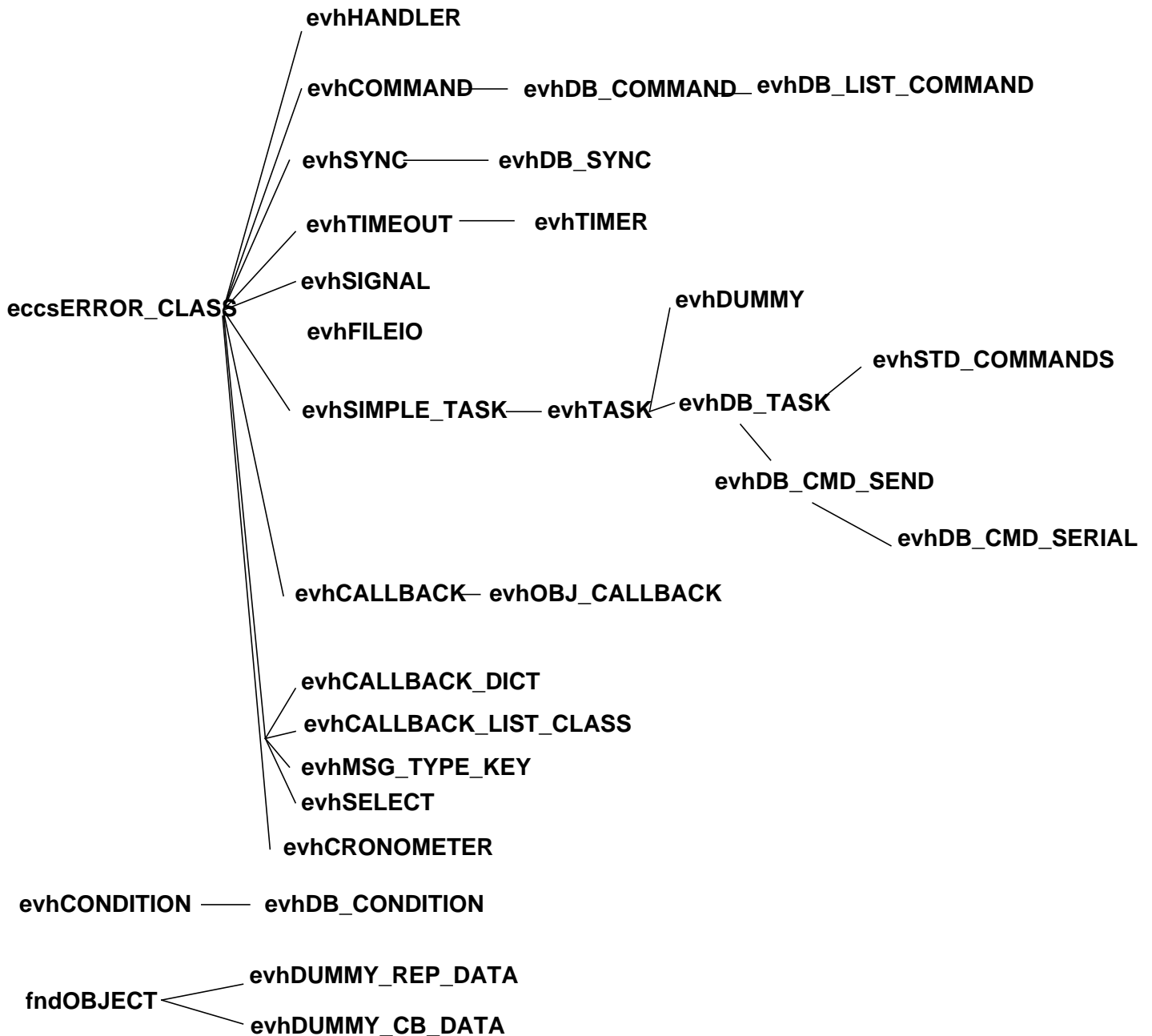


evh features

- The following events are handled:
 - commands
 - replies and error replies
 - time out notifications
 - cyclic timers
 - data base events
 - alarms
 - signals
 - file input
- callbacks are stored in a dynamic dictionary
- callbacks must return within a “command response time” of 1 second
- a wide set of ready-made classes implements standard behaviors and event handling protocols



evh class hierarchy





Using EVH

In the Makefile:

- link the CCS standard libraries
- link the C++ standard libraries (the `vltMakefile` define C++ should be used)
- link the required support library `fnf`
- link the ECCS library `eccs`
- link the EVH library `evh`

Example:

```
EXECUTABLE=evhTest
```

```
evhTest_OBJECTS= eccsTest  
evhTest_LIBS    = evh eccs fnf C++ CCS
```

In the code:

```
#include "evhHANDLER.h"  
int main(int, char *argv[])  
{  
    ccsCOMPL_STAT stat;  
    stat = ccsInit(argv[0]);  
    eccsErrLog(stat, "Error in Init ");  
  
    evhHandler->MainLoop();  
  
    stat = ccsExit();  
    eccsErrLog(stat, "Error in ccsExit");  
}
```



The standard VLT application

A standard VLT application can be implemented based on the `evhSTD_COMMANDS`, that provides:

- Standard commands:
 - PING
 - INIT
 - STATE,STATUS
 - STANDBY,ONLINE,OFF
 - SELFTEST, TEST
 - SIMULAT, STOPSIM
 - VERBOSE
 - VERSION
 - STOP
 - EXIT, KILL, BREAK
- Standard database point:

```
CLASS evhSTD_COMMANDS
BEGIN
    ATTRIBUTE INT32 state evhSTATE_OFF
    ATTRIBUTE LOGICAL simulation
    ATTRIBUTE LOGICAL verbose
END
```



The example application

The following example is a typical WS coordination application base on the `evhSTD_COMMANDS` class.

It can:

- Receive SETVAL and GETVAL commands. They are re-routed to another application, on LCU, for processing.
- Handle the TEST command. It is processed internally.
- Handle all VLT standard commands

It is a fully compliant VLT application and all commands are handled asynchronously.

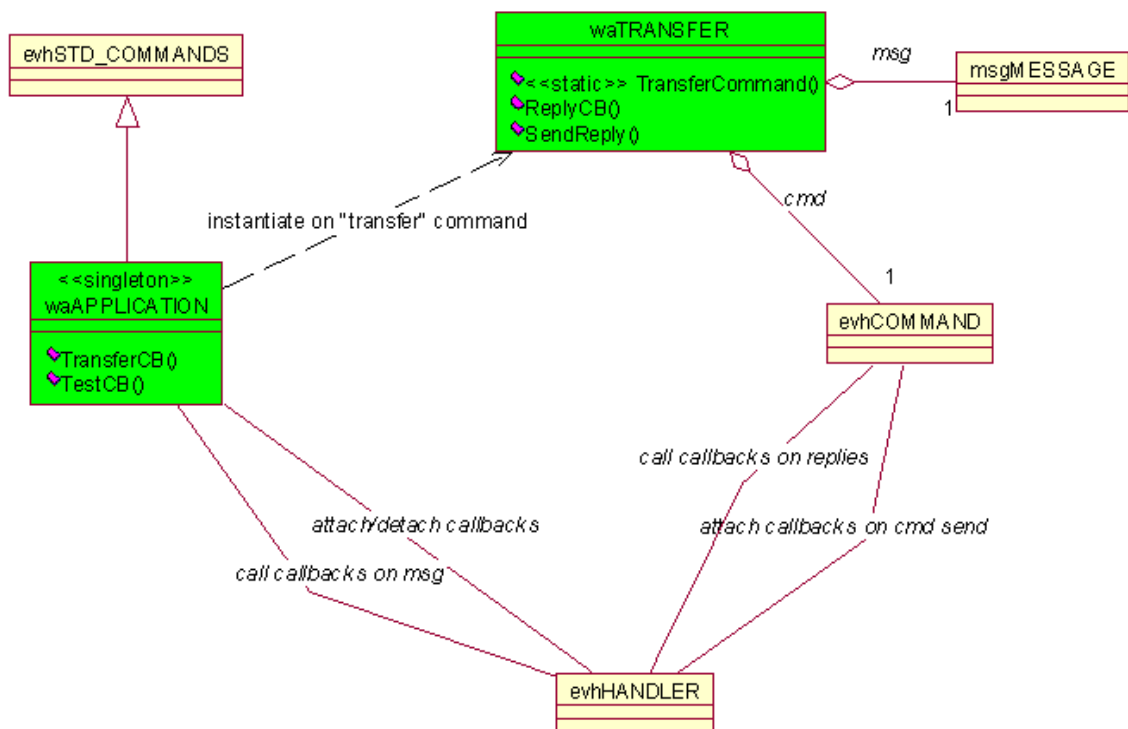
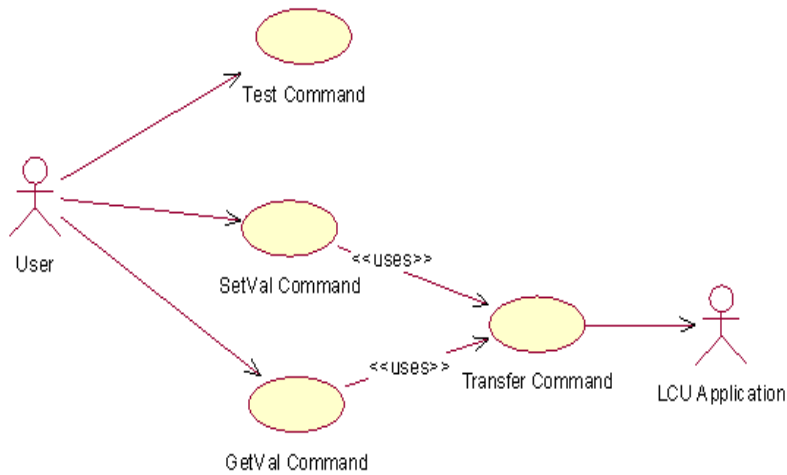
In this session we show:

- The structure of the application
- The typical design patterns used
- Testing and debugging using VLT development tools (in particular the usage of `ccseiMsg` and `evhDummy` for manual testing).

Actual code is provided in appendix.



Example application architecture



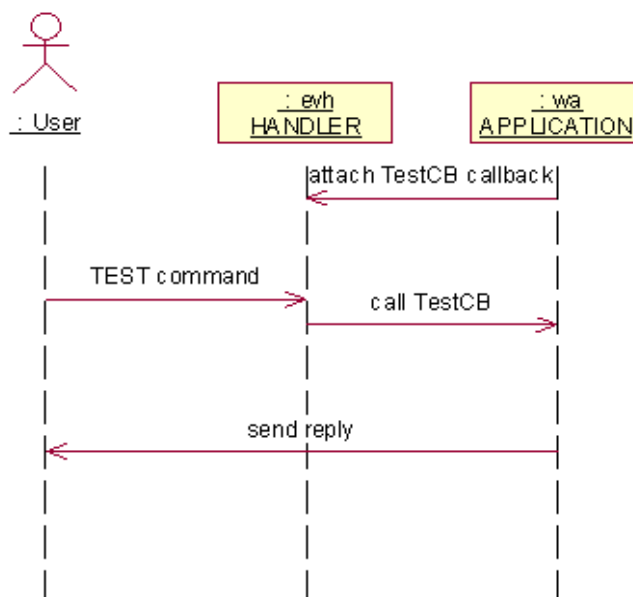


Handling "immediate" commands

"Immediate" commands are the simplest case: an application receives a command, deals with it and sends an immediate reply to the originator.

"Immediate" commands are implemented writing just one callback to receive the command.

In the example, TEST is an immediate command

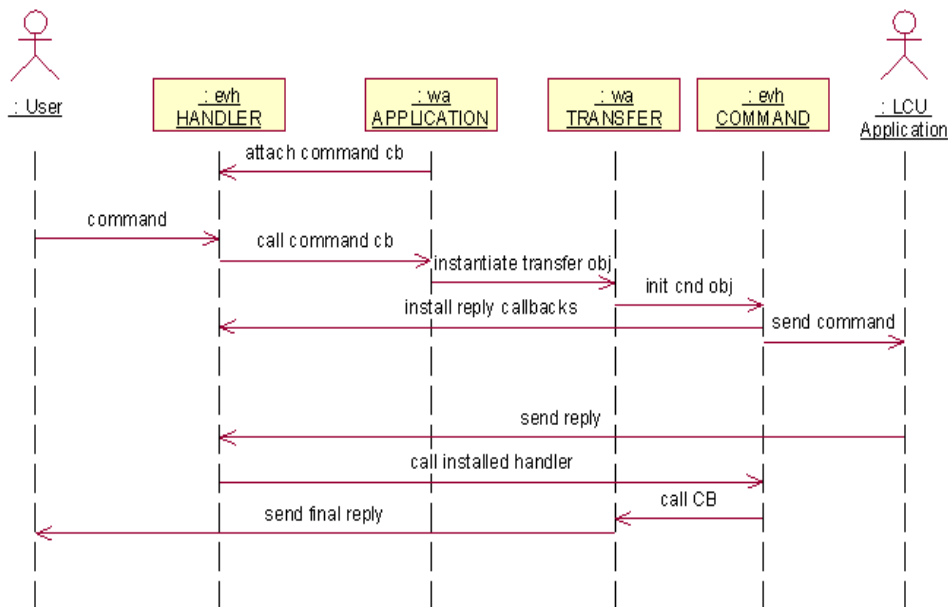




Handling "transfer" commands

"Transfer" commands are a typical case for workstation coordination applications: an application receives a command, deals with it and send one sub-command to the controlled processes. When they are done it must sends the final reply to the originator.

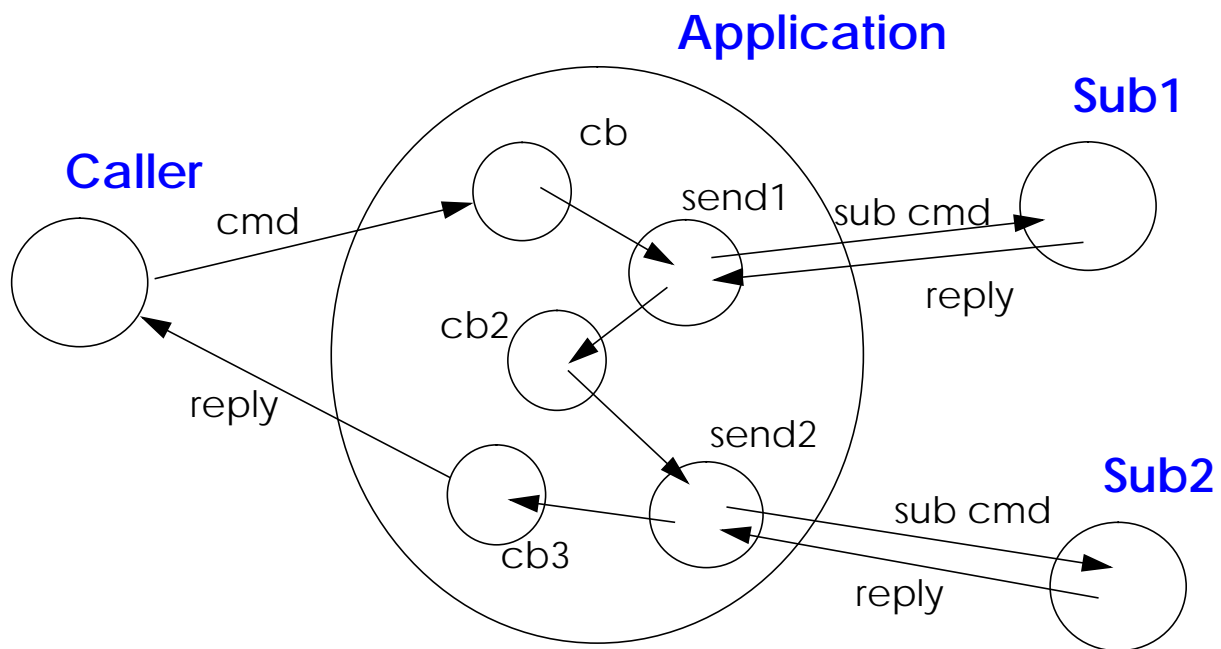
In the example, SETVAL and GETVAL are transfer commands.





Multi step commands

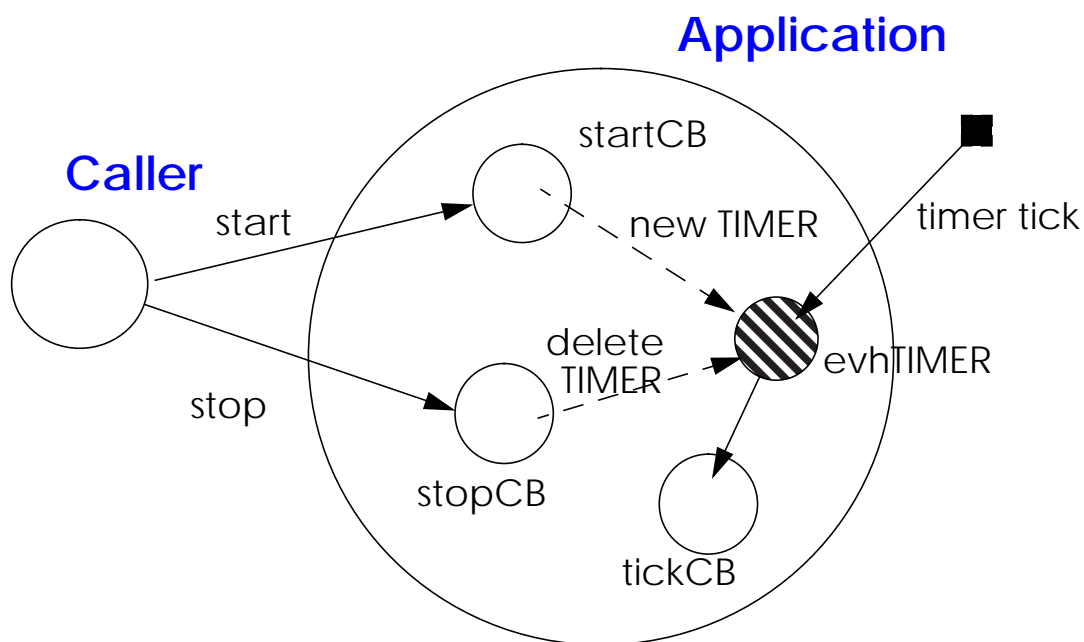
In “multi step” an application receives a command, deals with it and send one sub-command a controlled processes. When the reply comes, some new elaboration is done and a new command is sent and so on for as many steps are needed.



Cyclical timers

Another typical design pattern involves starting and stopping (for example via commands) a cyclical timer.

“Cyclical timers” are implemented using the evhTIMER class.





Conclusion

This presentation has shown only some of the most important aspects of the library.

For more details look at:

- [VLT Software - CCS Event Tool Kit User Manual \(VLT-MAN-ESO-17210-0771\)](#)
- [Guidelines for the Development of VLT Application Software \(VLT-MAN-ESO-17210-0667\)](#)
- Code examples in `evh <mod>/test` directory