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Beckhoff PLC Configuration Guide

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¹ <https://gitlab.eso.org/ifw/ifw-ll>



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1 Introduction

1.1 Scope

This document is a configuration guide for Beckhoff PLCs used for ESO projects. It details how to order PLCs and corresponding licenses as well as how to configure PLCs before connecting them to the control network.

1.2 Definitions, Acronyms and Abbreviations

This document employs several abbreviations and acronyms to refer concisely to an item, after it has been introduced. The following list is aimed to help the reader in recalling the extended meaning of each short expression:

TBC	To Be Clarified
TBD	To Be Defined
PLC	Programmable Logic Controller
TwinCAT	The Windows Control and Automation Technology



2 Related Documents

Non applicable

3 Buying a PLC

3.1 TwinCAT 3 Platform Level (performance level)

TwinCAT 3 Runtime components are available for different performance platforms (performance levels, platform levels). Performance levels currently range from 40 to 94. The TwinCAT 3 license price depends on the platform level and the level has to be specified in the license order number.

Examples of TwinCAT 3 platform levels are shown in Fig. 3.1.

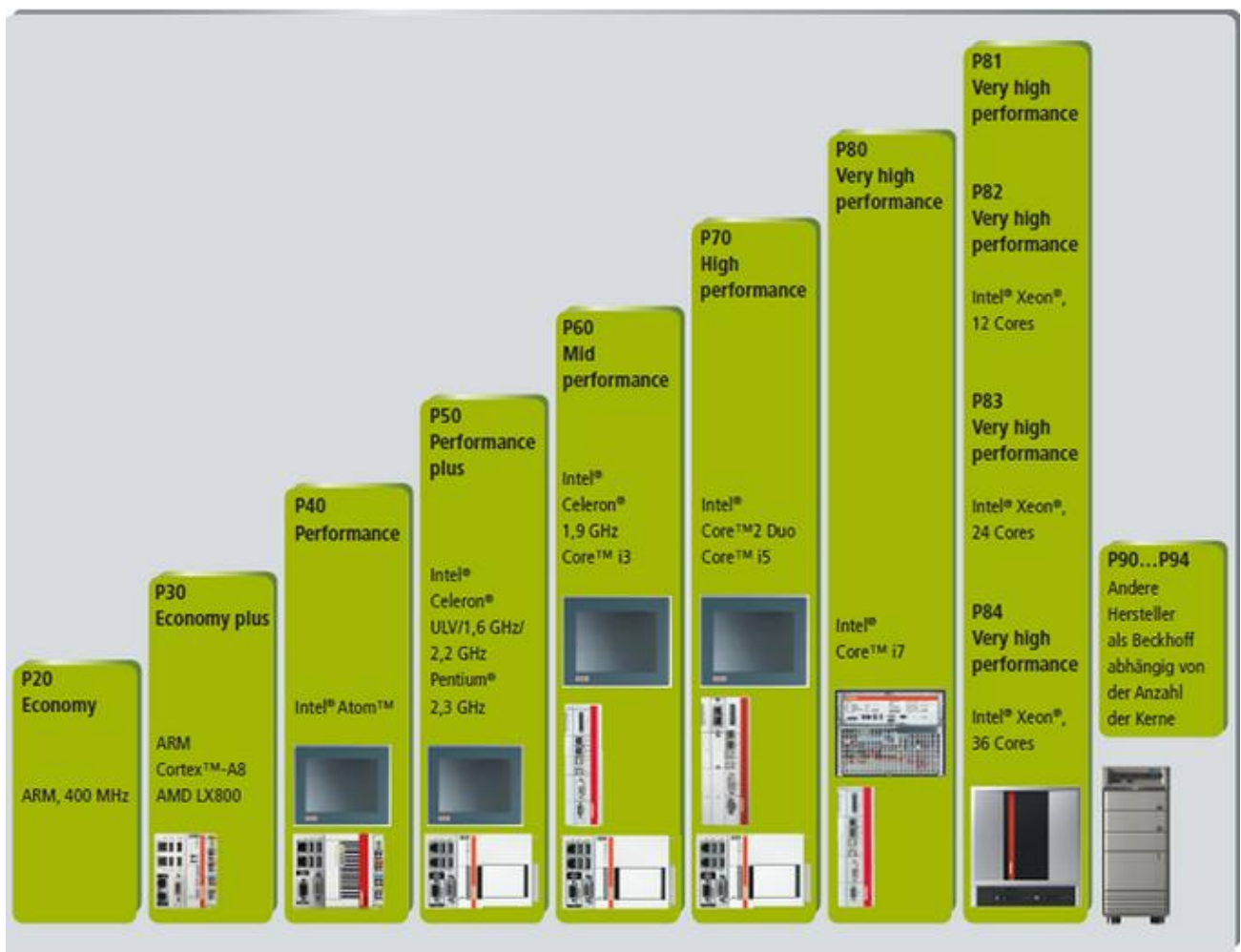


Fig. 3.1: TC3 Performance Platforms (source: Beckhoff Info System)



3.2 Standard PLC

Currently, the standard PLC for ESO instruments is CX2030-0125 with 16 GB of CFast disk (CX2900-0033) instead of the default 8 GB disk. The performance level of this unit is 60. The option 0125 means that the system comes preinstalled with:

- Windows Embedded Standard 7 P 32-bit OS and
- TwinCAT3 Runtime (XAR).

The CX2030 also requires a Power Supply unit CX2100-0004.

3.3 PLC Licenses

Each PLC needs run-time licenses. The simplest way is to order licenses together with the PLC in the same purchase order. This way the PLC comes preconfigured by Beckhoff and the user doesn't have to handle the licenses himself. If additional licenses are needed later on, they can be purchased and then activated by the user.

The following sections describe each item in a purchase order and then give an example of a complete purchase order that includes both HW and licenses.

PLC licenses are one-off licenses tied to the HW and the performance platform. Licenses bought for a certain performance platform can be used for that platform or a lower one but not for a higher platform. For example, licenses bought for CX2030 (60) could be used for CX5120 (40) but not for CX2040 (70).

For more information about TwinCAT licenses, go to Beckhoff Information System and search for *Working with TwinCAT 3 license dongles*.

Ordering Standard Licenses

TwinCAT 3 standard licenses are always linked to specific hardware. This is usually a TwinCAT 3 license dongle (EL6070 License Key Terminal or C9900-L100 license key USB stick). In principle it is also possible to tie a TwinCAT 3 license to a specific Beckhoff PLC, e.g. CX2030. However, this has a severe disadvantage that, if the PLC is replaced, the TwinCAT 3 licenses are no longer valid for the new PLC. If, on the other hand, the TwinCAT 3 licenses are tied to a TwinCAT 3 license dongle, the PLC can easily be replaced. In addition, spare PLCs that are kept in stock as replacement units don't need additional licenses.



Fig. 3.2: License Dongles (source: Beckhoff Info System)

It is recommended to order licenses on the License terminal EL6070-0033.

It is also recommended that the EL6070 terminal is placed as the very first terminal after the CX2100-0004 Power Supply, so its presence is clear when replacing a broken PLC (see Fig. 3.3).

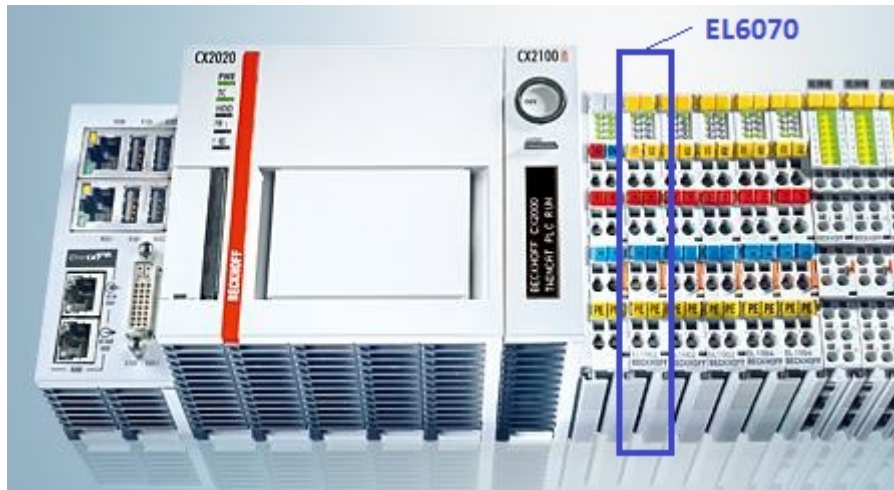


Fig. 3.3: Recommended Position for License Dongle EL6070

Mandatory Licenses

There are two runtime licenses that are mandatory for each PLC. One is needed for the PLC Runtime and the other one for the communication with the PLC. The designation pp in the license catalogue number stands for Performance Platform and is 60 for the standard CX2030. When ordering, pp should be substituted with the correct performance platform, e.g. 60.

Table 3.1: Mandatory PLC Licences

License Order #	Description	Note
TC1200-00pp	TC3 PLC	This is a license to run PLC programs
TF6100-00pp	TC3 OPC UA	This is the license for the OPC UA, the standard communication interface between the PLC and the outside world.



Additional Licenses

Depending on the PLC application, additional licenses might be needed. The most common licenses are for the motion control and for the communication via serial port or TCP/IP. We also use C++ for some code that has been ported from VxWorks systems.

Table 3.2: Most Common Additional PLC Licences

License Order #	Description	Note
TF5000-00pp	TC3 NC PTP 10 Axes	Motion control for up to 10 axes.
TF5010-00pp	TC3 NC PTP Axes Pack 25	Motion control for up to 25 axes. This license is in addition to TF5000-00pp! Essentially it adds 15 axes to the system.
TC1300-00pp	TC3 C++	Programming in C++
TF6311-00pp	TC3 TCP/UDP Realtime	TCP/UDP communication
TF6340-00pp	TC3 Serial Communication	RS-232, 422 & 485

License Bundles

License bundles are just a simplified way of ordering licenses since one license catalogue number can contain two or more licenses. For example, TC1250-00pp (TC3 PLC/C++) contains both licenses TC1200-00pp and TC1300-00pp. From the cost point of view there is no advantage in ordering licenses in a bundle. The total cost of licenses is always the same regardless of if they were purchased in a bundle or individually.

Ordering TwinCAT 3 Standard Licenses with and without Pre-activation

To enable unambiguous assignment of TwinCAT 3 licenses for pre-activation and the required licensing platform (dongle or PLC) in the purchase order, please refer to Table 3 when ordering. The order number of the TwinCAT 3 license dongle indicates whether or not to pre-activate licenses for the dongle.



Table 3.3: Purchase Order Information for License Dongles

Order number	Description
EL6070-0033 or C9900-L100-0033	TwinCAT 3 dongle with pre-activated TwinCAT 3 licenses
EL6070-0000 or C9900-L100-0000	Empty TwinCAT 3 dongle (without pre-activated TwinCAT 3 licenses)

The order number of the TwinCAT 3 license is important for pre-activation of TwinCAT 3 licenses for a type ...-0033 dongle. In this case, the third last digit of the TwinCAT 3 product number must be “1”. When reordering licenses for a TwinCAT 3 license dongle that is already with the customer, the license must be activated by the customer. In this case, the third last digit of the TwinCAT 3 product number must be “2”.

Examples of the two above cases are given in Table 4. License order is for performance platform 60, i.e. for CX2030.

Table 3.4: Order Number for Licenses Linked to Dongles

License Order #	Description
TC1200-0160	Pre-activation by Beckhoff for a TwinCAT 3 license dongle in the same purchase order.
TC1200-0260	No pre-activation by Beckhoff (license activation by customer)

Quotation/Purchase Order Examples

In this section we provide examples of possible ways to order a PLC CX2030 including the licenses for PLC programming, OPC UA communication, up to 25 motor axes and the support for C++ programming. Note that the option given in *Option with EL6070 License Terminal EL6070-0033 (recommended)* is the recommended one.

Licenses Linked to the PLC (not recommended)

CX2030-0125	Industrial PC with pre-installed TwinCAT 3 Runtime
CX2100-0004	Power supply for PC
CX2900-0033	16 GB CFast card, instead of 8 GB CFast card
TC1250-0060	TC3 PLC / NC PTP 10
TC1300-0060	TC3 C++
TF5010-0060	TC3 NC PTP Axes Pack 25
TF6100-0060	TC3 OPC UA



Option with USB License dongle C9900-L100-0033

CX2030-0125	Industrial PC with pre-installed TwinCAT 3 Runtime
CX2100-0004	Power supply for PC
CX2900-0033	16 GB CFast card, instead of 8 GB CFast card
C9900-L100-0033	License dongle with pre-activated TwinCAT 3 licenses
TC1250-0160	TC3 PLC / NC PTP 10
TC1300-0160	TC3 C++
TF5010-0160	TC3 NC PTP Axes Pack 25
TF6100-0160	TC3 OPC UA

Option with EL6070 License Terminal EL6070-0033 (recommended)

CX2030-0125	Industrial PC with pre-installed TwinCAT 3 Runtime
CX2100-0004	Power supply for PC
CX2900-0033	16 GB CFast card, instead of 8 GB CFast card
EL6070-0033	License Key Terminal with pre-activated TwinCAT 3 licenses
TC1250-0160	TC3 PLC / NC PTP 10
TC1300-0160	TC3 C++
TF5010-0160	TC3 NC PTP Axes Pack 25
TF6100-0160	TC3 OPC UA

Adding USB License to UserMode Runtime (4026)

Note: Tested on TwinCAT 3.1.4026.22.

Warning: The Beckhoff documentation for UserMode Runtime states that USB access is not supported. However, Beckhoff support has confirmed that USB access works despite this statement. The documentation is expected to be updated in the future.

To add a USB key license to an IPC or non-Beckhoff PLC on a Windows 11 system, you can use the UserMode Runtime.

Install the following packages:

- TwinCAT.Standard.XAR
- TwinCAT.XAR.UserModeRuntime



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These packages should also pull in the dependencies `TwinCAT.XAR.USB.UM` and `TwinCAT.XAR.UsbService`.

Verify installed packages with:

```
tcpkg list -i
```

This allows you to use, for example, a Scope View (TE1300) license in an engineering PC.



4 PLC Configuration

PLCs are normally placed on the control network. Therefore, they should be assigned a name and the IP address. The following sections describe how to configure a newly arrived PLC. Please note that **ALL** configuration steps are needed for correct configuration. Most of the configuration steps include a link to the corresponding videos of the procedure executions.

New PLCs arrive with factory preset names and IP addresses that do not match the control network. This makes it difficult to remotely connect to the PLC. The easiest way to start working with a new PLC is to connect a screen, a mouse and a keyboard directly to the PLC. This way the PLC is seen as any other Windows PC.

4.1 Backup of Delivered System

The first and very important step is to make a backup of the hard disk (CFAST SSD) of the delivered system, just in case something goes wrong, and the user has to recover the system.

Backup can be done using freeware program [Clonezilla](http://clonezilla.org/downloads.php)¹. However, it is recommended to use Beckhoff Service Tool C9900-H377 that is based on Acronis and is delivered on a bootable USB stick. Around 5GB of storage is needed for the complete backup of the system. The USB stick has enough space for two or three PLC backups.

Insert the USB stick into one of the available USB ports on the PLC and reboot the PLC. Select Backup and follow the instructions. Once the backup is complete, transfer the backup (*.tib) file to a safe place on a PC.

4.2 Setting IP address

If possible, plug in one side of a network cable to the upper network port of the PLC and the other side to a PC or some network. This will help to easily identify the network connection in the Control Panel. The unused port should display "Network cable unplugged". Normally, the upper connection has a name with higher number in it than the lower port, e.g. Local Area Connection 2.

The procedure is the following:

- Go to: *Start\Control Panel\Network and Sharing Center*
- Select: *Change adapter settings*
- Right-click on the network to configure and select *Properties*.
- Scroll down to *Internet Protocol Version 4 (TCP/IPv4)*, click on it and then press the *Properties* button.

A dialog shown in Fig. 4.1 will pop up. Enter the required configuration and press OK.

¹ <http://clonezilla.org/downloads.php>

A video showing how to set the IP address can be found [here](https://europeansouthernobservatory-my.sharepoint.com/personal/jhaucke_eso_org/CSE/cins/cins_public/Shared%20Documents/PLC%20Material/Videos/PLC_Setup_Set_IP_Address.mp4)².

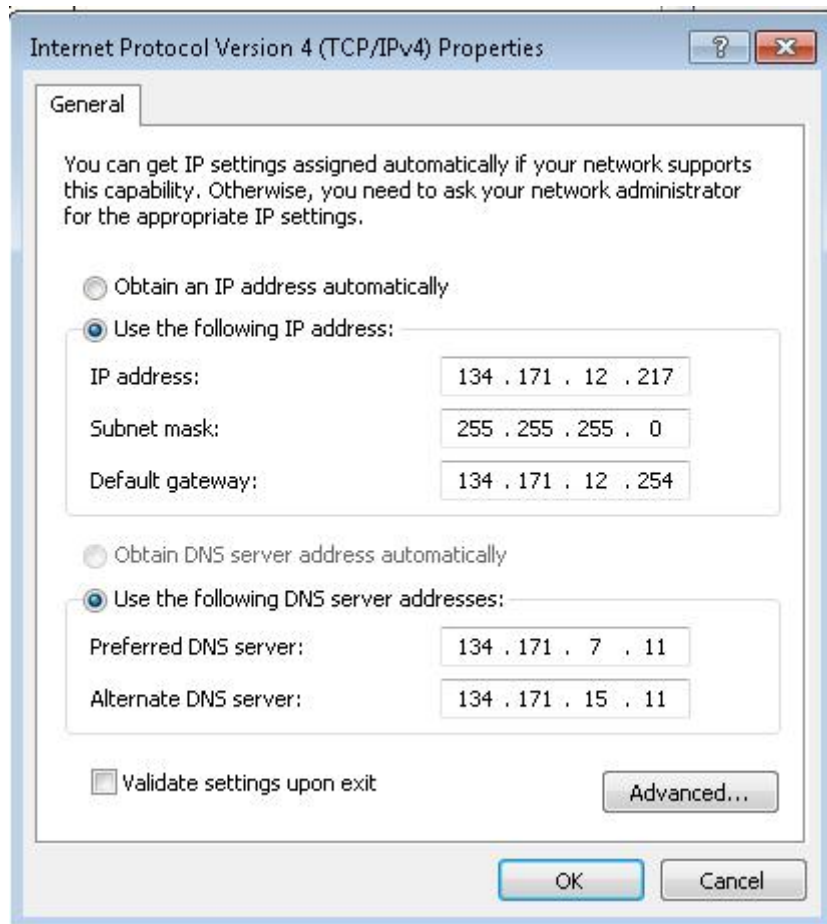


Fig. 4.1: Setting of IP Address

4.3 Changing PLC Name

The procedure is the following:

- Go to: *Start\Control Panel\System*
- Select: *Change settings* in the lower right side of the screen.
- Under the *Computer Name* tab press the *Change...* button.
- Enter the new name in the “*Computer name*” input field and confirm with OK.

Once the name has been changed, the PLC has to be rebooted for the change to take effect.

² https://europeansouthernobservatory-my.sharepoint.com/personal/jhaucke_eso_org/CSE/cins/cins_public/Shared%20Documents/PLC%20Material/Videos/PLC_Setup_Set_IP_Address.mp4

A video showing how to change the name of the PLC can be found [here](https://europeansouthernobservatory-my.sharepoint.com/personal/jhaucke_eso_org/CSE/cins/cins_public/Shared%20Documents/PLC%20Material/Videos/PLC_Setup_Set_PLC_Name.mp4)³.

4.4 Enabling Firewall

Firewall for both network ports should be active, i.e. turned ON, as shown on Fig. 4.2.

The procedure is the following:

- Go to: *Start\Control Panel\Windows Firewall*
- Click on: *Turn Windows Firewall on or off* in the upper left side of the screen.
- *Turn on Windows Firewall* for both networks and confirm with OK.

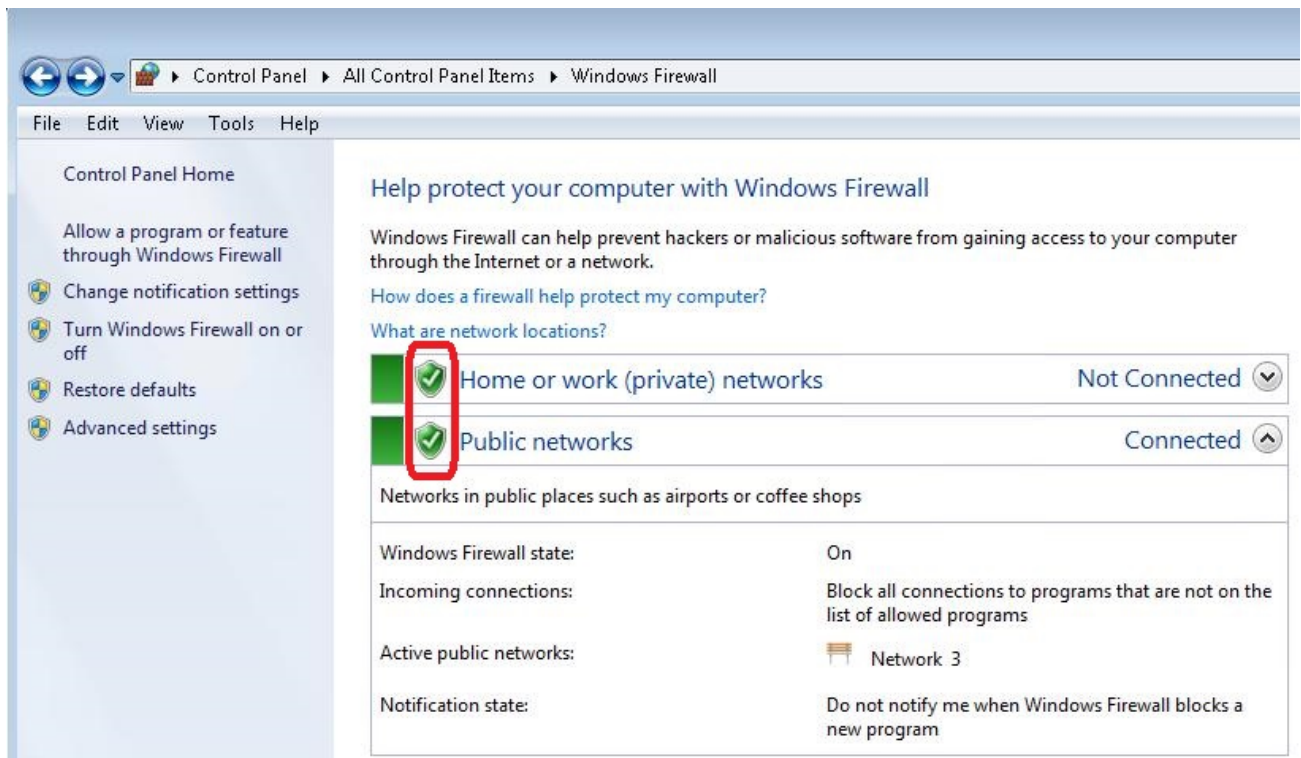


Fig. 4.2: Both Networks with Firewall ON

³ https://europeansouthernobservatory-my.sharepoint.com/personal/jhaucke_eso_org/CSE/cins/cins_public/Shared%20Documents/PLC%20Material/Videos/PLC_Setup_Set_PLC_Name.mp4



4.5 Opening OPC UA Port 4840

Due to the active firewall, in order to be able to communicate with the PLC from the high-level software, a special port 4840 will have to be open.

The port is open from the Control Panel Firewall Advanced settings by defining a new inbound rule.

A video showing how to open OPC UA port 4840 can be found [here](#)⁴.

4.6 Enable *ping* Service

The ping service can be enabled from the Control Panel Firewall Advanced settings by reconfiguring one of the existing *Inbound* rules for *File and Printer Sharing (Echo Request – ICMPv4-In)* for *Private, Public* Profile. The *Remote Address* must be changed from *Local subnet* to *Any*.

A video showing how the *ping* service is enabled can be found [here](#)⁵.

Note: From this point on, the PLC can be put on the network and accessed via *Remote Desktop*.

4.7 Install and Configure OPC UA Server v5

Since version 4.4.0, the TwinCAT OPC UA Server has added some complexity to the installation and initialization process to increase security. This chapter describes the entire process of installing a new Server version with the additional security but allowing the OPC UA Server to be back compatible with the less secure communication methods.

⁴ https://europeansouthernobservatory-my.sharepoint.com/personal/jhaucke_eso_org/CSE/cins/cins_public/SharedDocuments/PLCMaterial/Videos/PLC_Setup__Opening_OPC_UA_Port.mp4

⁵ https://europeansouthernobservatory-my.sharepoint.com/personal/jhaucke_eso_org/CSE/cins/cins_public/SharedDocuments/PLCMaterial/Videos/PLC_Setup__How_to_Enable_ping_Service.mp4

Install OPC UA Server v5 and OPC UA Configurator

- Login to PLC using the *Remote Desktop*.
- Double-click the downloaded binary for the *OPC UA Server* and start the installation process.
- A popup will come up with an option of installing a *none/none endpoint*, this should be selected.

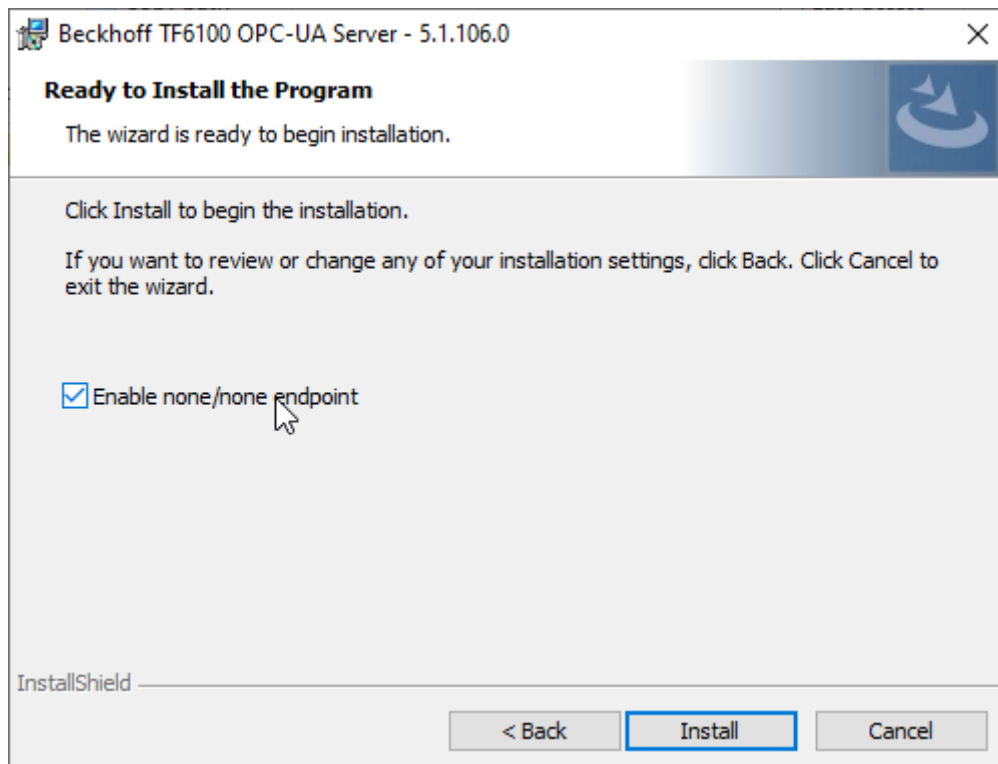


Fig. 4.3: . .

- Complete the installation.
- Double click the downloaded binary for the *OPC UA Configurator* and complete the installation.
- Reboot the PLC.



Connecting for the First Time

- Using *UAExpert* connect to the PLC using the *Basic256Sha256* method and Anonymous user.

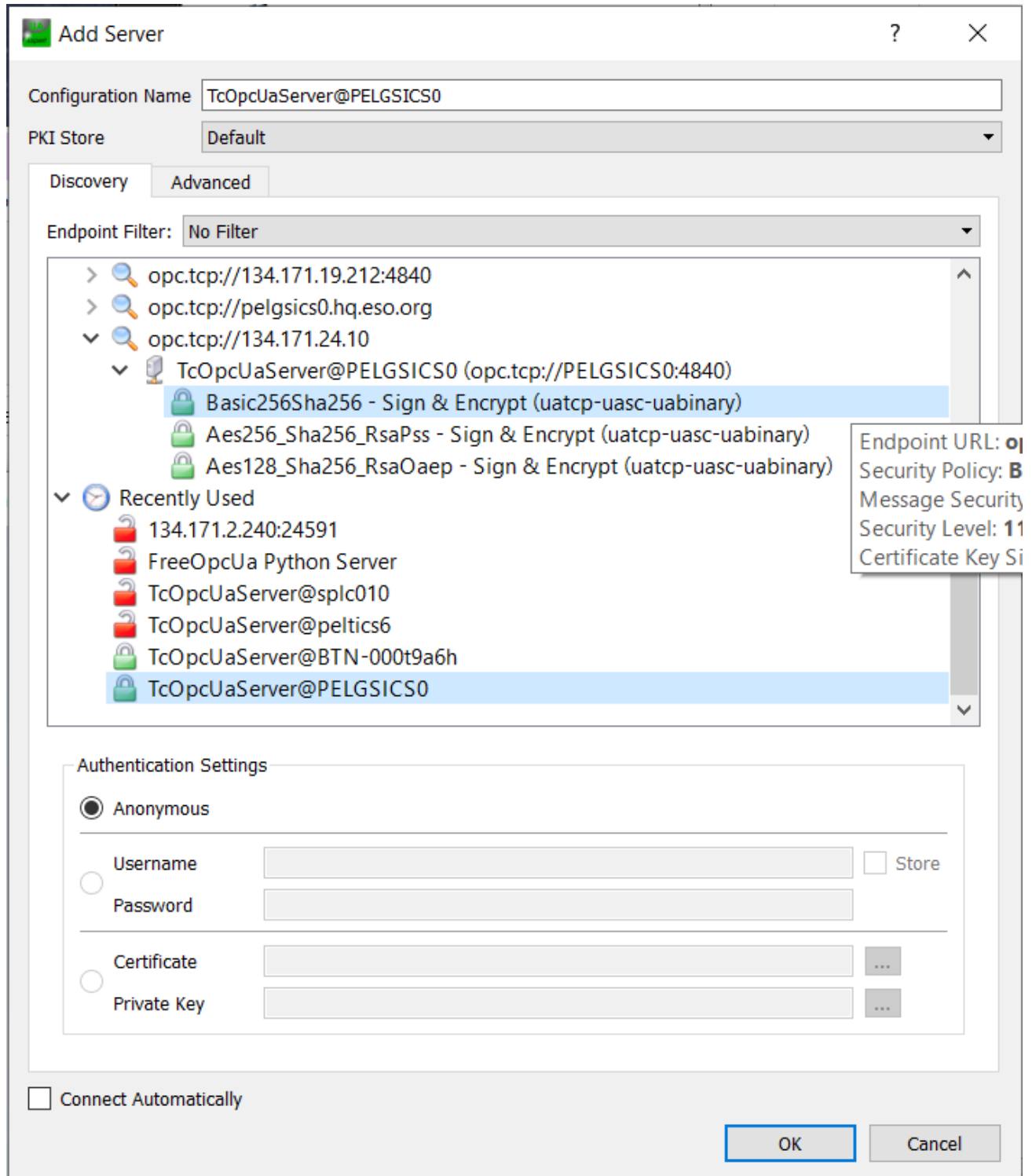


Fig. 4.4: . . .

- Ignore any error.

- Temporarily accept the server certificate and press *Continue*.

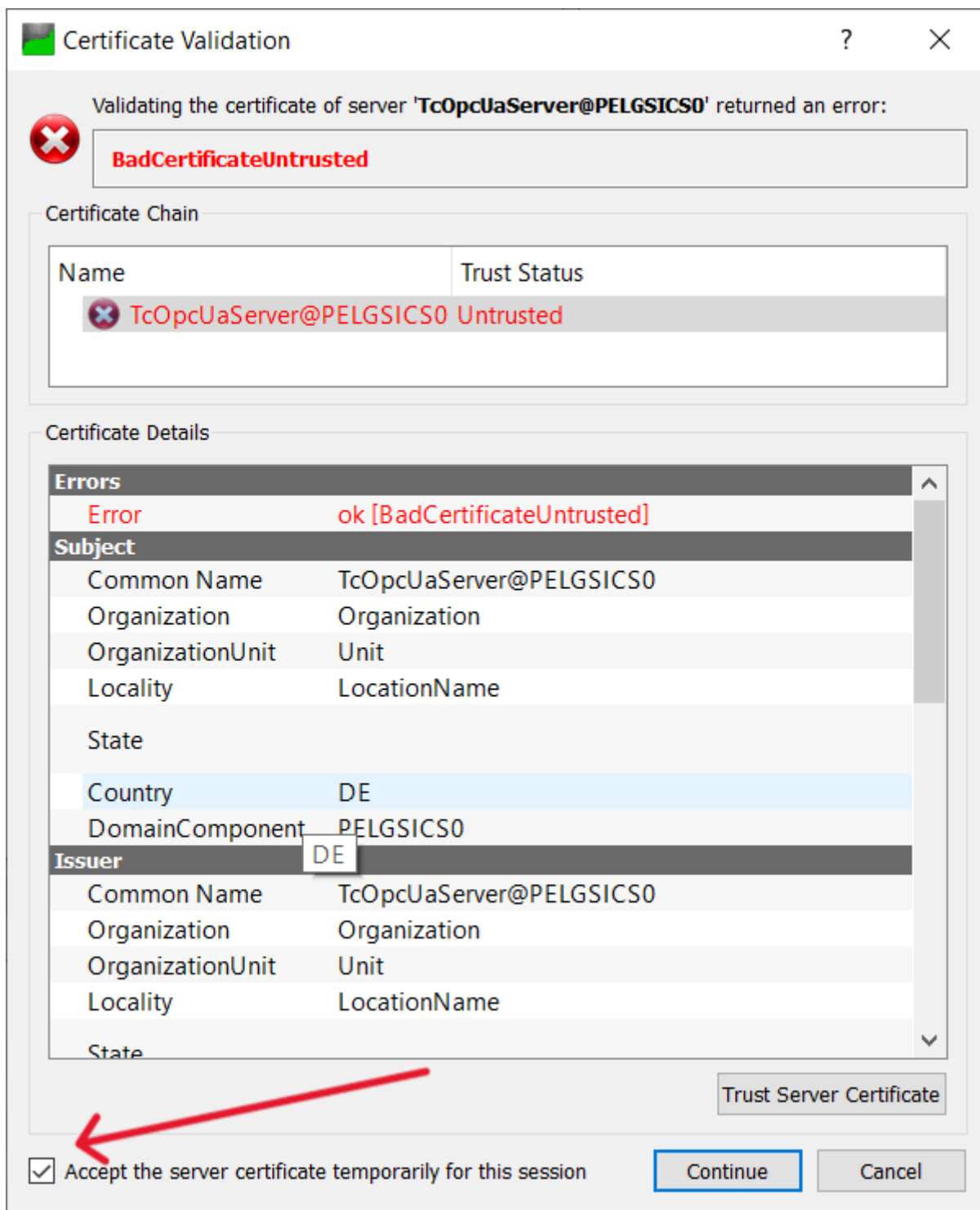


Fig. 4.5: . .

- Find the RPC call *TrustOnFirstUse* and call it by right-clicking on the name.

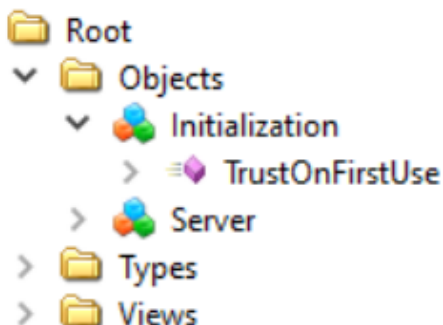


Fig. 4.6: . .

- The values for Username: *opcua_user* and Password: *pass4u!* should be filled in. This user will be created as a Windows user and will become the administrator user for the OPC UA Server.

Call TrustOnFirstUse on Initialization

Input Arguments			
Name	Value		Data Type Description
Username	opcua_user	... Load file...	String
Password	pass4u!	... Load file...	String
Output Arguments			
Name	Value		Data Type Description
AddStatus	0 (Succeeded)	▼	CreateUserResult
LogonResult	☒		Boolean
Result			
Succeeded			

Call Close

Fig. 4.7: . .

- Press the *Call* button. The *Result* should be *Succeeded*, and the *AddStatus* value should be “**0 (Succeeded)**”. Then, after a couple of seconds, the OPC UA Server should reset.
- If the *AddStatus* is not as expected (see example in Fig. 4.8), most likely the *OPC UA Server* and the *Configurator* will have to be uninstalled, and the user *opcua_user* deleted from the system, before the complete process is repeated. Chapter *Uninstalling Existing OPC UA Server* describes this procedure.

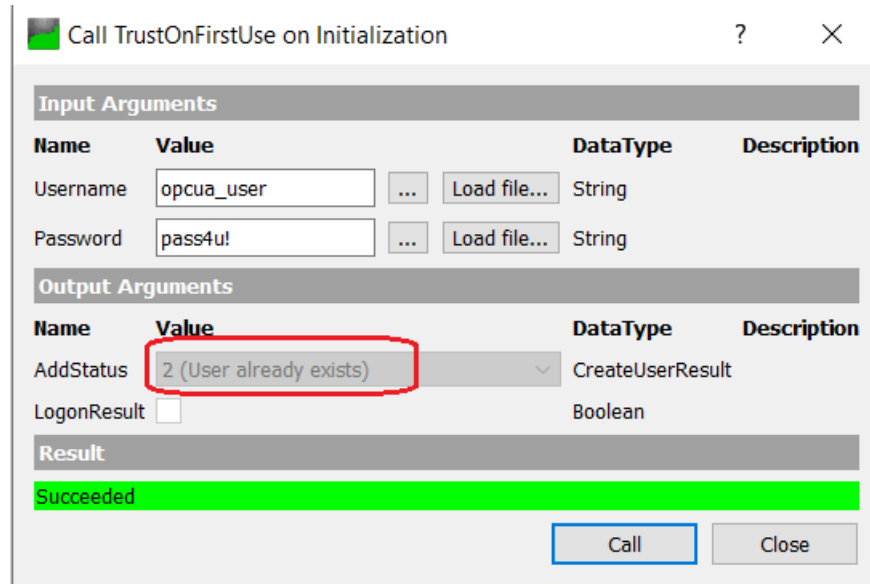


Fig. 4.8: . .

- If there is a *Connect Error*, *Ignore* it to continue.
- Disconnect from the Server.
- Now, you should be able to reconnect to the server again using *Basic256Sha256* but now using the *Username* and *Password* that was entered in the previous step. Please note that in case you were using *Custom* discovery in *UaExpert*, you should *Rebrowse* to have the client request for *Username* and *Password*, as it's shown in Fig. 4.9.

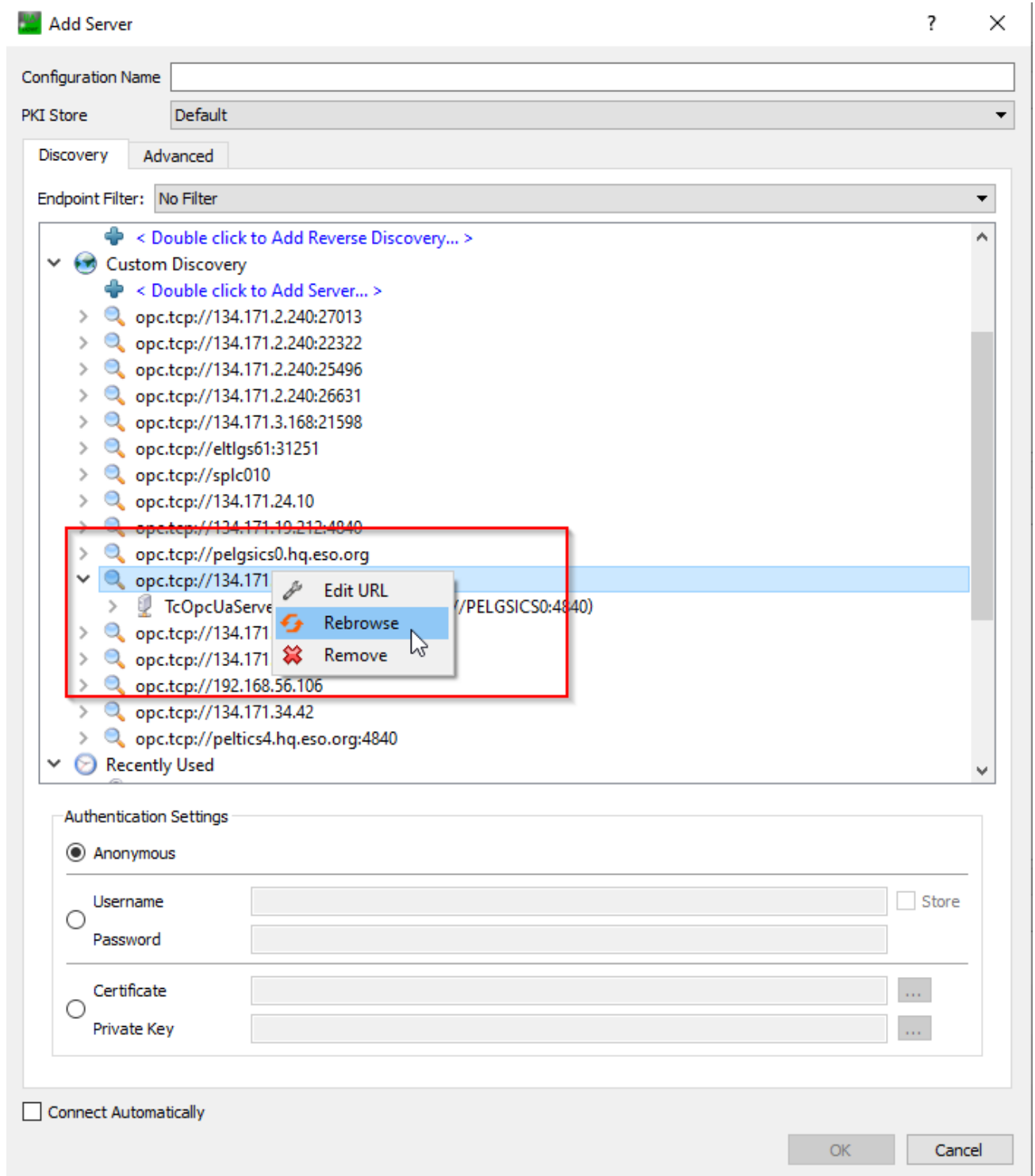
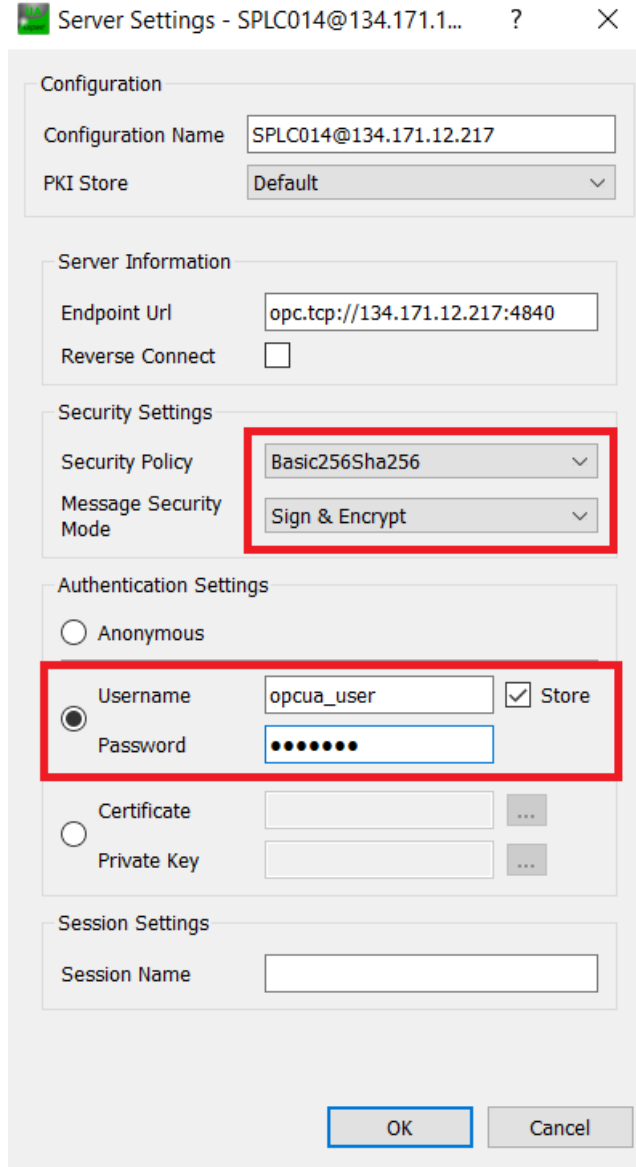


Fig. 4.9: . .



Server Settings - SPLC014@134.171.1... ? X

Configuration

Configuration Name:

PKI Store:

Server Information

Endpoint Url:

Reverse Connect: ☐

Security Settings

Security Policy:

Message Security Mode:

Authentication Settings

☐ Anonymous

☒ Username: ☒ Store

Password:

☐ Certificate:

☐ Private Key:

Session Settings

Session Name:

OK Cancel

Fig. 4.10: . .

- Connect again.
- If there is a *Connect Error*, *Ignore* it to continue.
- Press the *Trust Server Certificate* button and then check the *Temporarily accept* the server certificate checkbox. Press *Continue*.

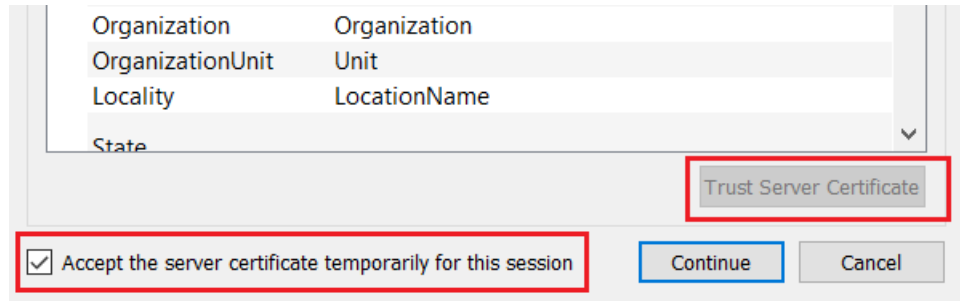


Fig. 4.11: . .

- If there is a *Connect Error*, *Ignore* it to continue.
- Disconnect from the Server.

Allow Anonymous Connections to the Server

- Connect to the PLC via Remote Desktop.
- Open the TwinCAT OPC UA Configurator via *Start > BECKHOFF > TF6100 OPC-UA Configurator*.
- Press *Edit* to configure the server to connect to. It is better to use the real PLC name in *Server URL* rather than *localhost* to avoid some nagging popups.

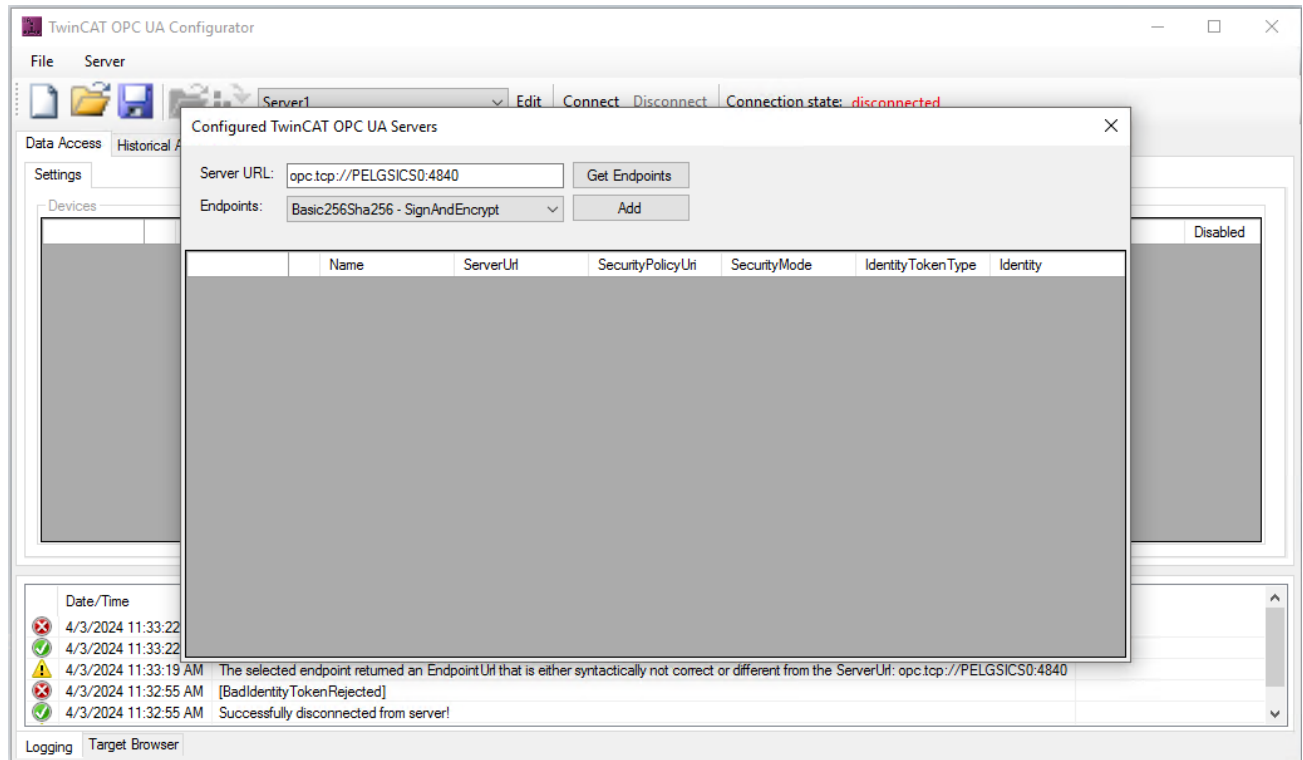


Fig. 4.12: . .

- Click on *Get Endpoints*, a certificate will need to be created and a popup will emerge. Accept the defaults and press *Create* to continue.
- Click on *Add*, this will add a line to the bottom table.

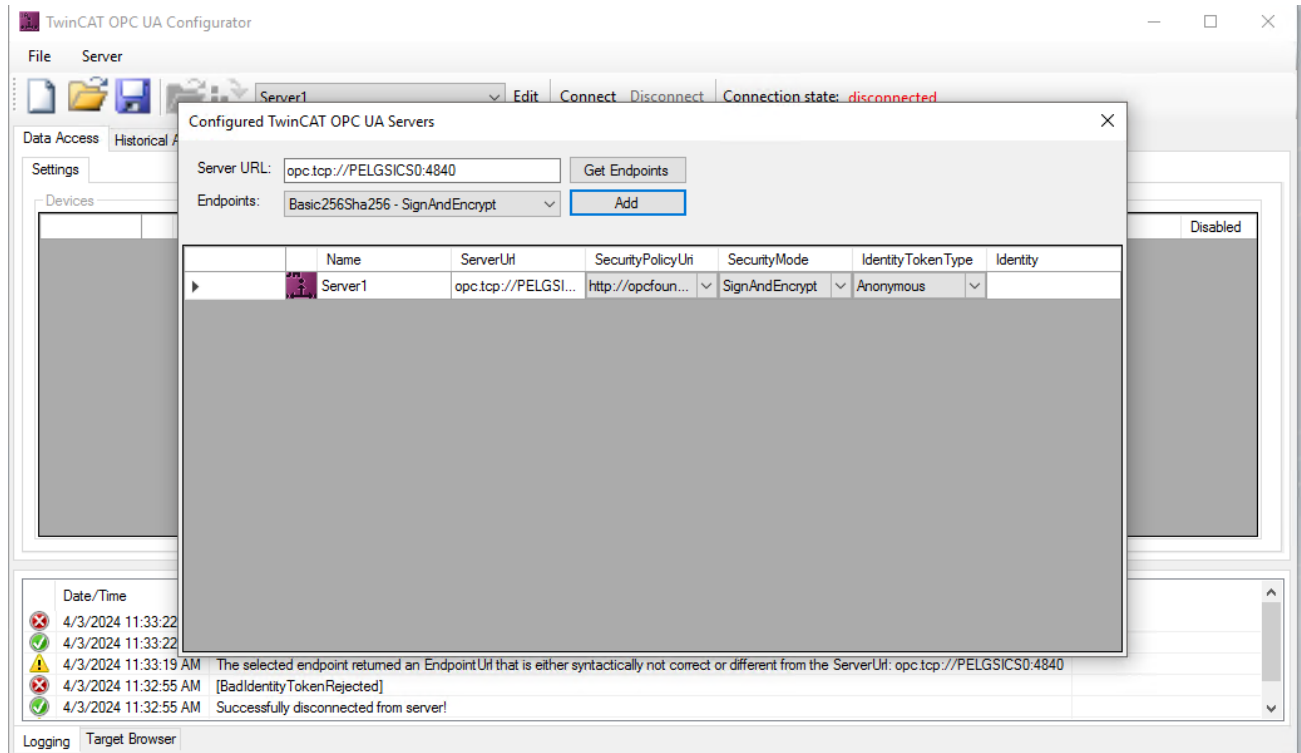


Fig. 4.13: . .

- Double click on the server line and a popup will emerge with the details of the connection.
- On the popup, you can change the *Name* of the server and in *Identity Token Type* select *User-Name*, then in *Identity* please write the *UserName*, i.e., *opcua_user*, from the *TrustOnFirstUse* Call in the previous step.

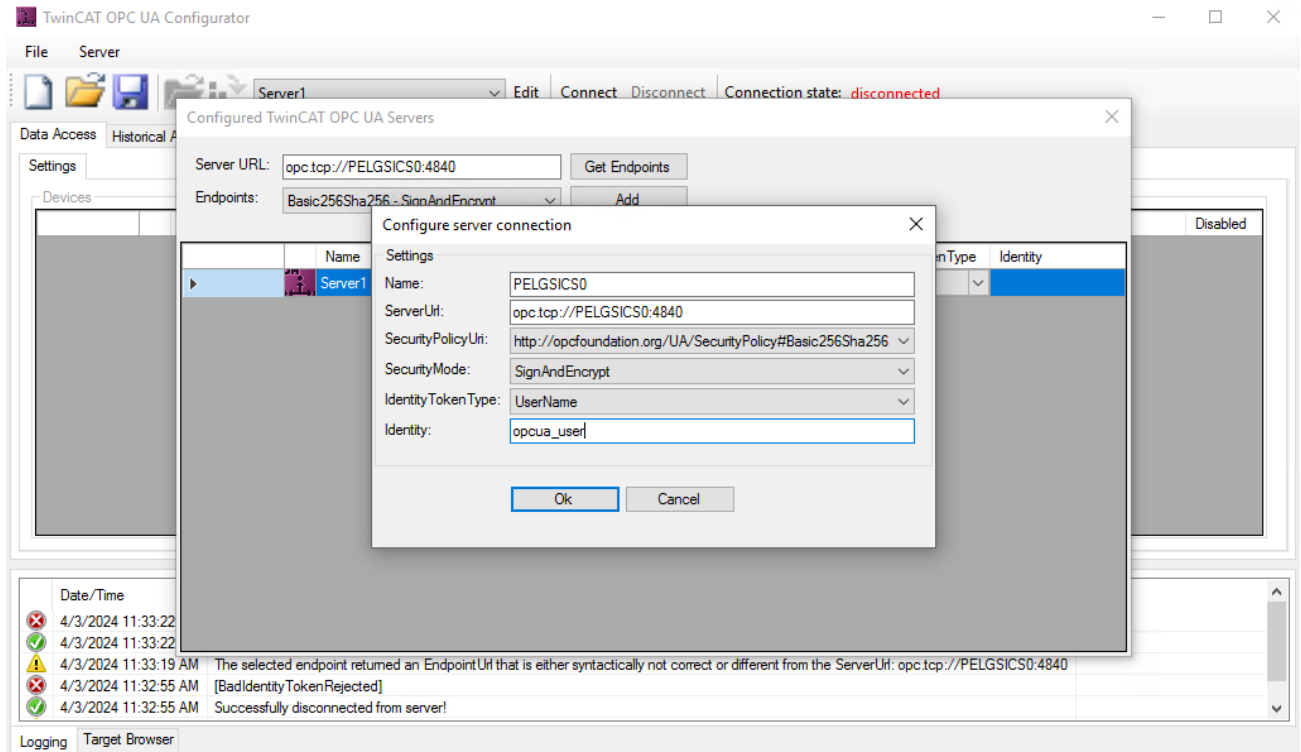


Fig. 4.14: . .

- Click on Ok and then close the Configured TwinCAT OPC UA Servers window. You will be back to the configurator, and the name of the connection will be displayed.



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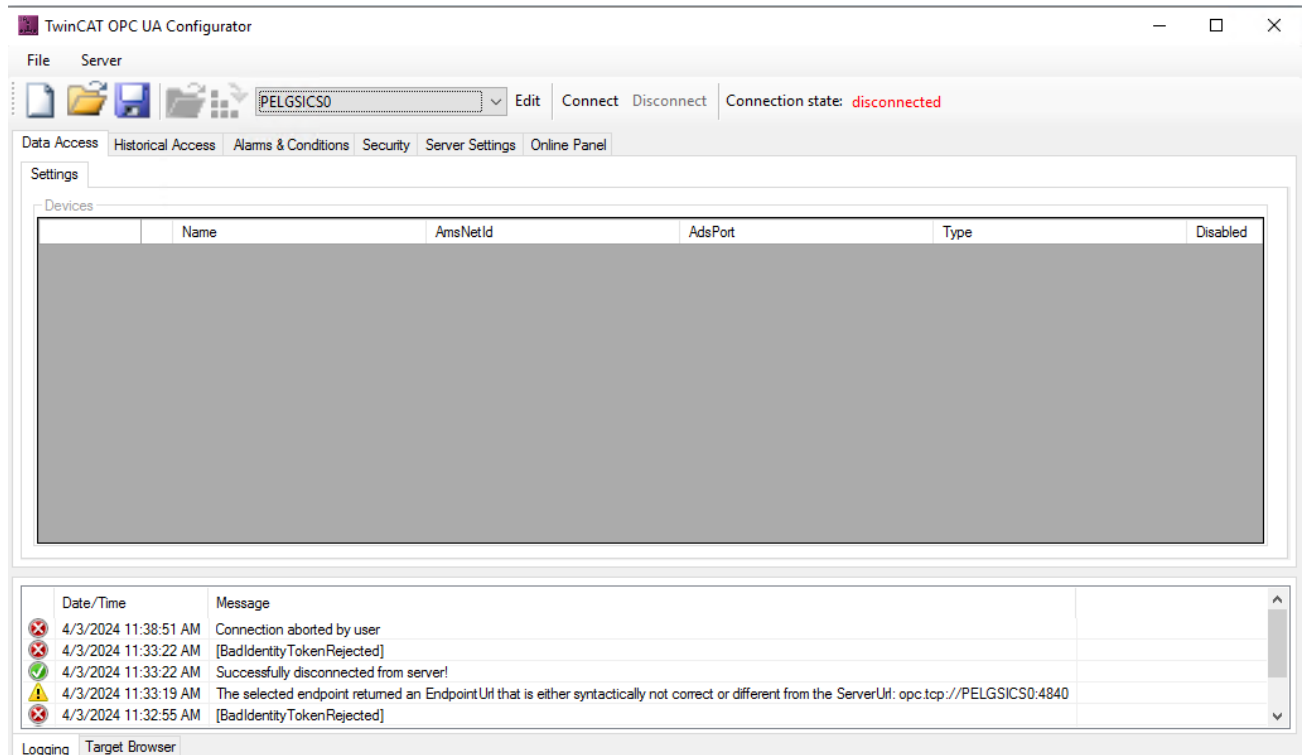


Fig. 4.15: . .

- Click on *Connect*, a popup will appear. Write the *Password* for the user. Press OK.
- The status *connected* should appear at *Connection state*.
- Click on *Server > Open from target* to load the current configuration from the OPC UA Server.
- Click on the *Security* tab.



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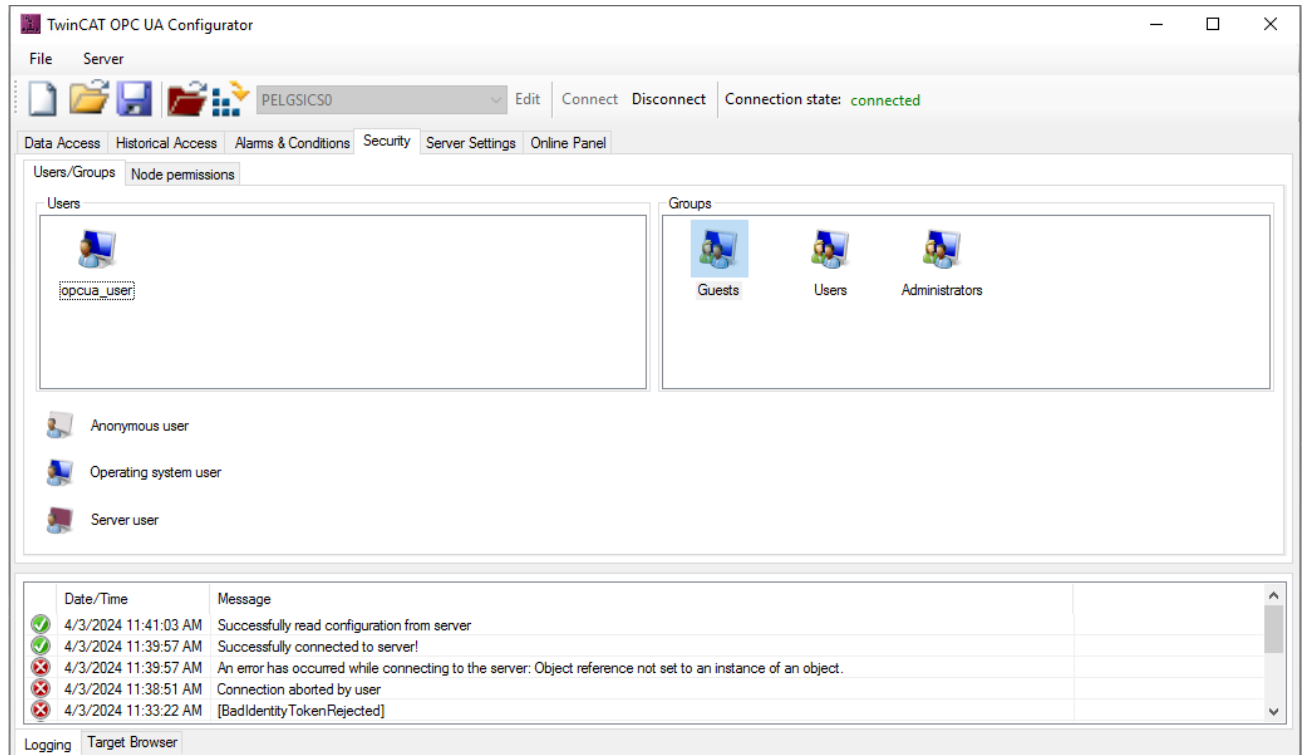


Fig. 4.16: . .

- Right click on the *Users* box and select *Add*.
- The *User details* popup emerges. Select *None* in *Authentication Provider* and *Users* in *Member of group*, then press *Ok*

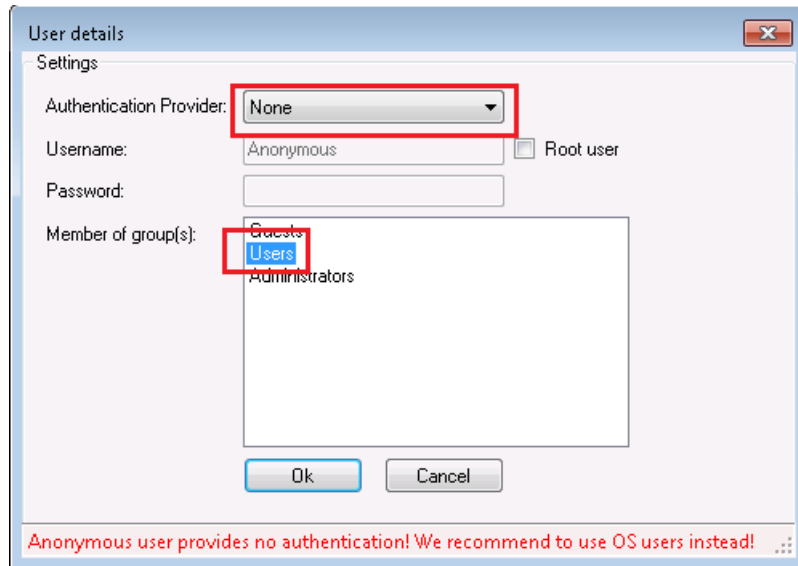


Fig. 4.17: . .

- A new user *Anonymous* appears in *Users*
- Click on the menu *Server / Activate* on *target* and select *Yes* to restart the Server.

Allow None as Security Policy

- On the TwinCAT OPC UA Configurator click on the *Server Settings* tab.

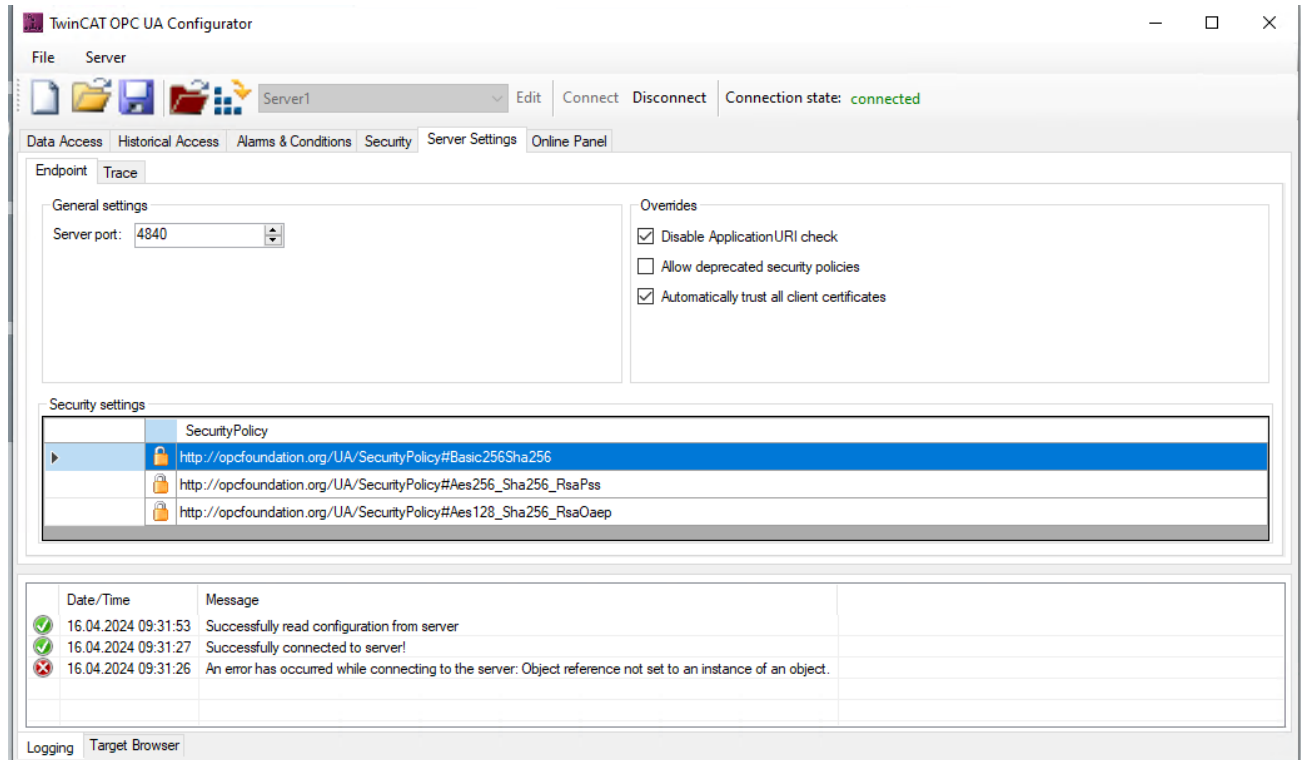


Fig. 4.18: . .

- Right-click on the *Security settings* box and click on *Add* in the popup menu.
- A *Configure endpoint security* popup emerges. Under *SecurityPolicy* select *SecurityPolicy#None* and in *MessageSecurityModes* enable *None*. Press *Ok*. This will add the *SecurityPolicy#None*.

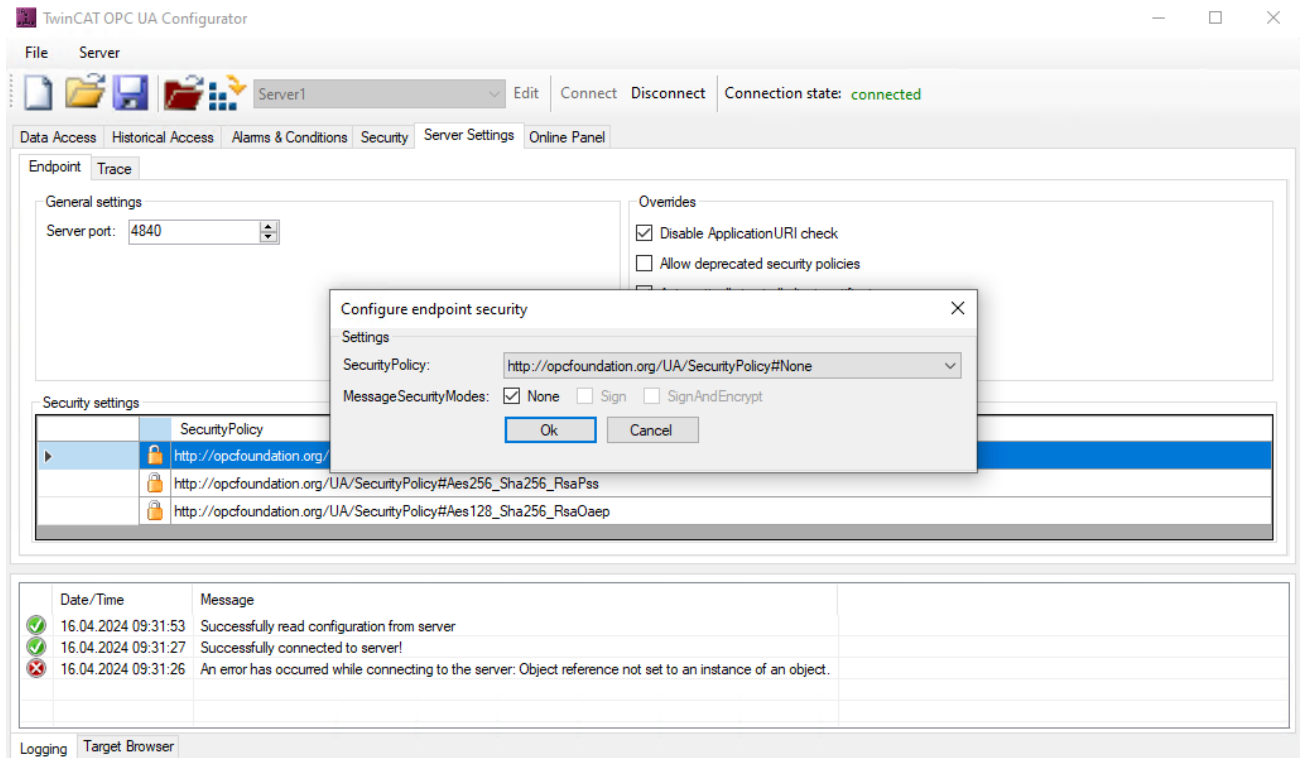


Fig. 4.19: . .

- Click on the menu *Server/Activate on target* and click *Yes* to restart the server.
- After this last step, *UaExpert* should provide a new configuration option *None – None*.
- Connect as *Anonymous* and the *Security Policy None-None*.

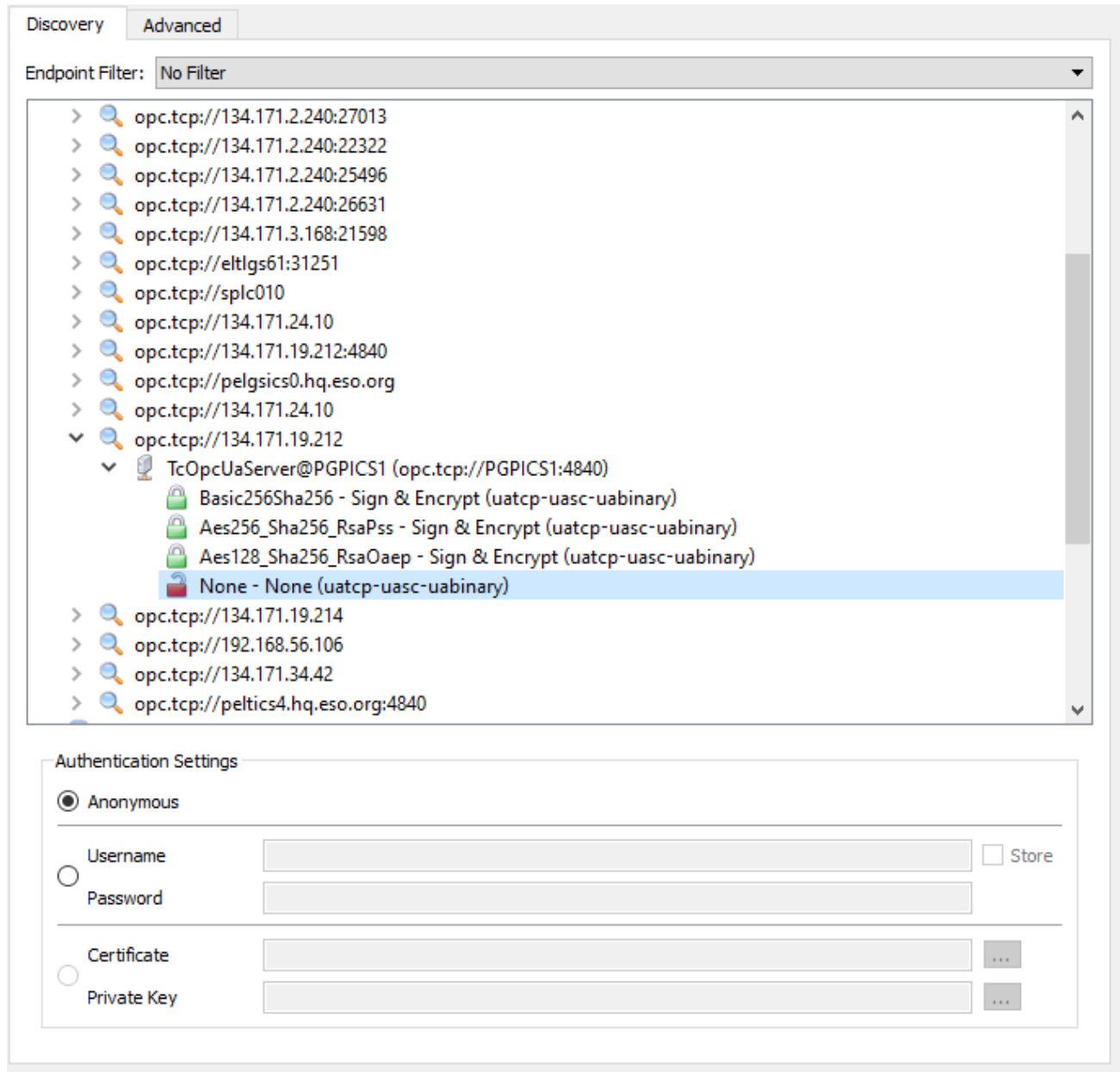


Fig. 4.20: . .

If for some reason you would like to reinstall the OPC UA Server v5, first you should uninstall it. To be able to start from scratch, the procedure described in Chapter *Uninstalling Existing OPC UA Server* should be followed.

4.8 Configure OPC UA Server v5 for solutions with multiple PLC projects

In cases where the TwinCAT solution contains more than one PLC project, the OPC UA Server requires some additional configuration to properly expose variables from all projects/ports.

- In *TwinCAT XAE Shell* confirm the port that the PLC projects are using. In the Solution Explorer double click on a particular PLC project to open the *Project* tab.

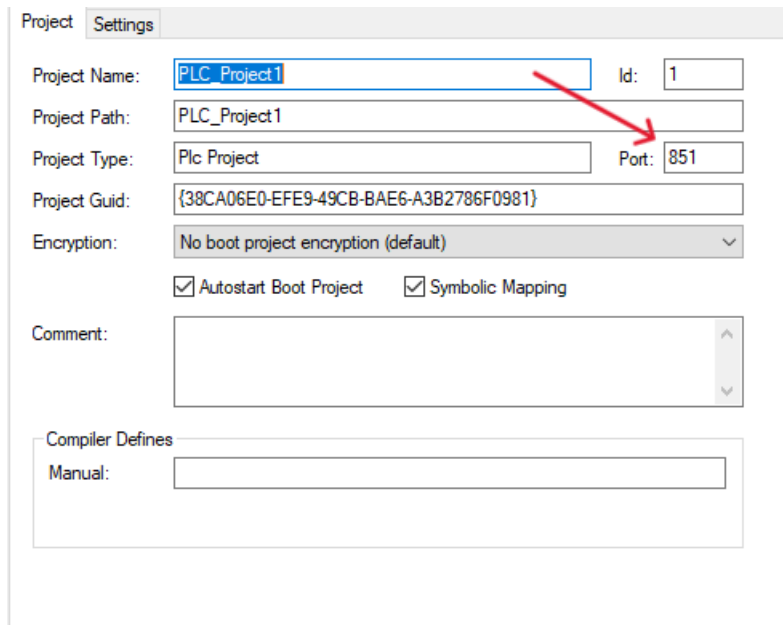


Fig. 4.21: . .

- Open the OPC UA Server *Configurator* and connect to the *OPC UA Server* as *opcua_user*. You will have to enter the password as well.
- Repeat the following for every project/port in the TwinCAT solution:
- Once connected, switch to *Data Access* tab. There should be at least one *Device* configured for the default port 851. Right-click to *Add* a new project.



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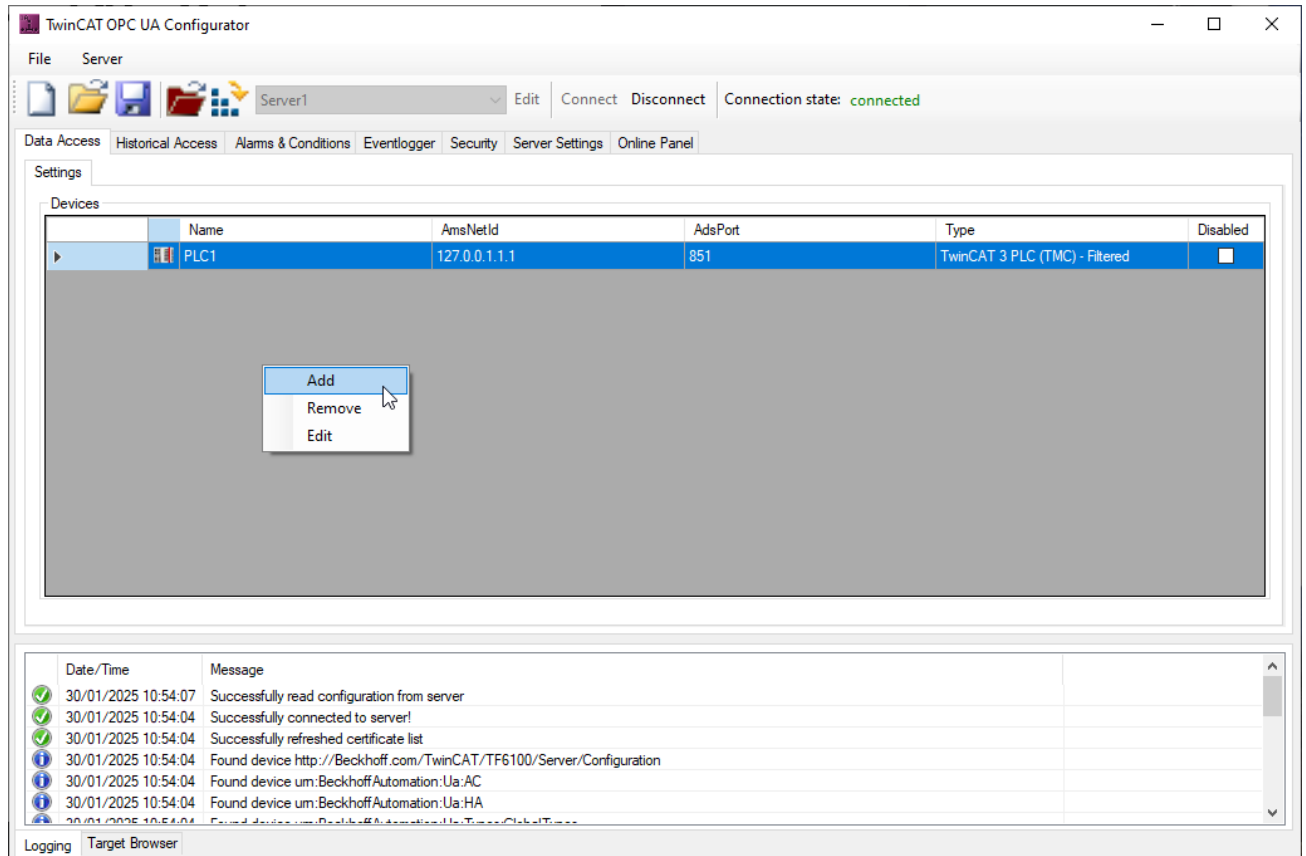


Fig. 4.22: . .

- In the popup, enter the relevant information for your project and press OK. Pay special attention to the *AdsPort* and *SymbolFile* values, that should contain the *Port* of your specific PLC Project.

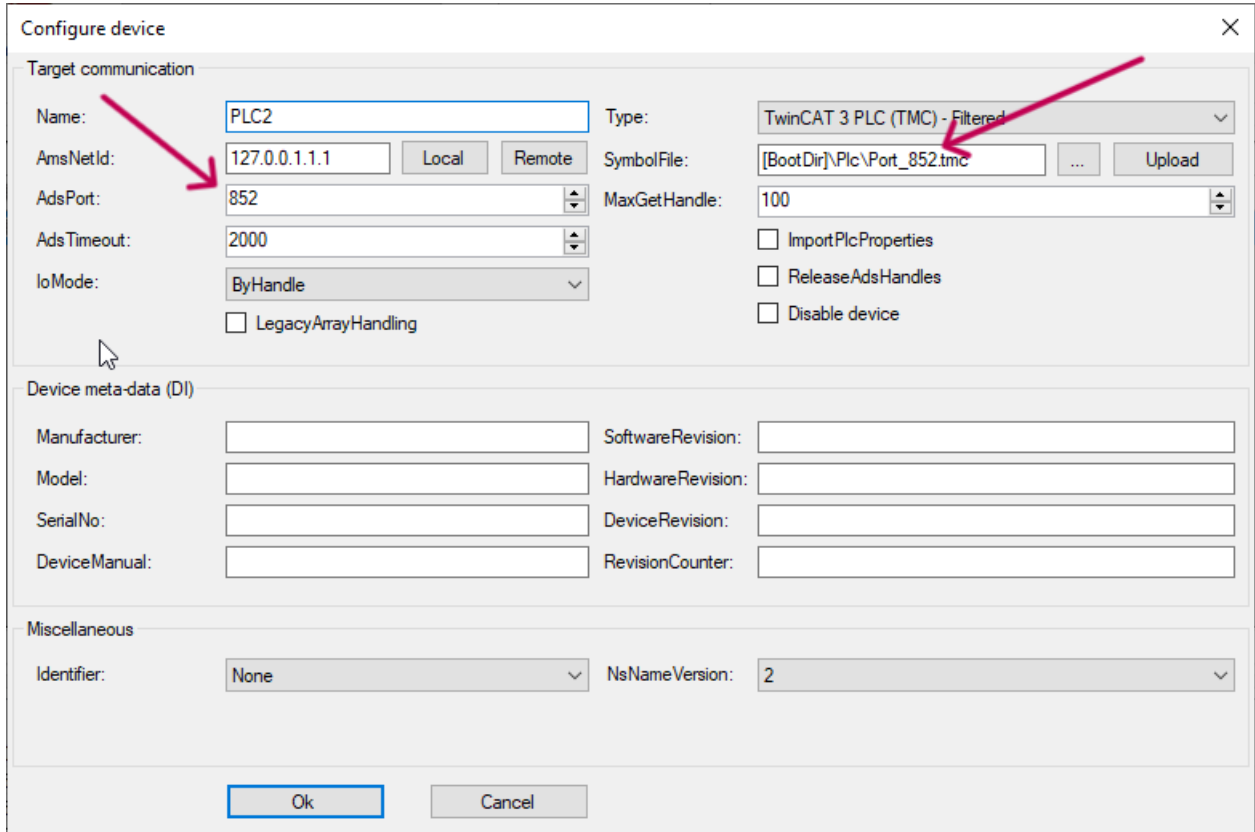


Fig. 4.23: . .

- After the devices for all project ports are added, Select *Server / Activate on target* to update the configuration and restart the OPC UA Server.
- Go to the *Security* tab and in the *Groups* window right-click on the *Users* group, then click on *Edit*.

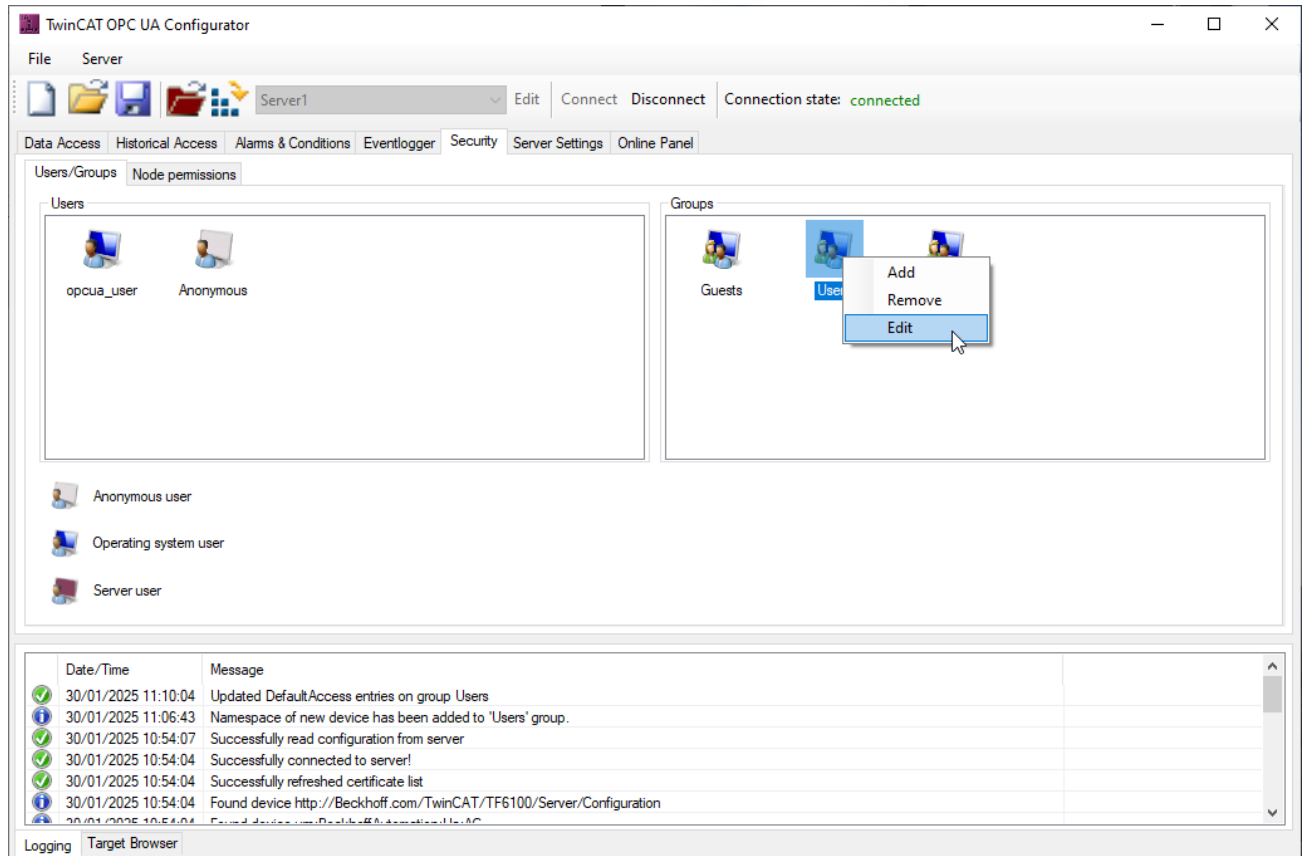


Fig. 4.24: . .

- In case the configuration has not been automatically added, right click on the *NamespaceName* table and then on Add.

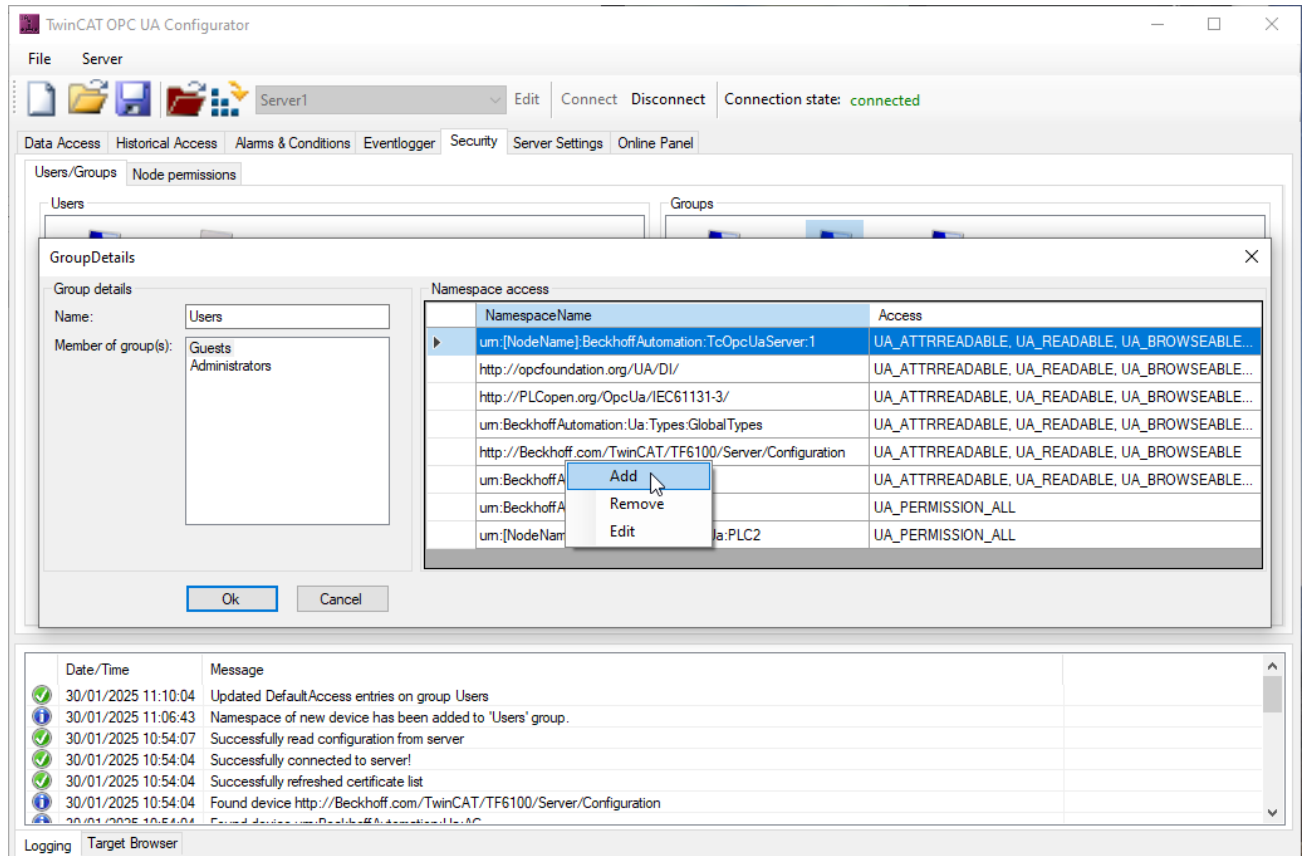


Fig. 4.25: . .

- From the *Available namespaces* menu, select the one that corresponds to the PLC project port you are configuring. Then, in the bottom frame click on *All* to give all permissions to access this namespace to the *Users* group.

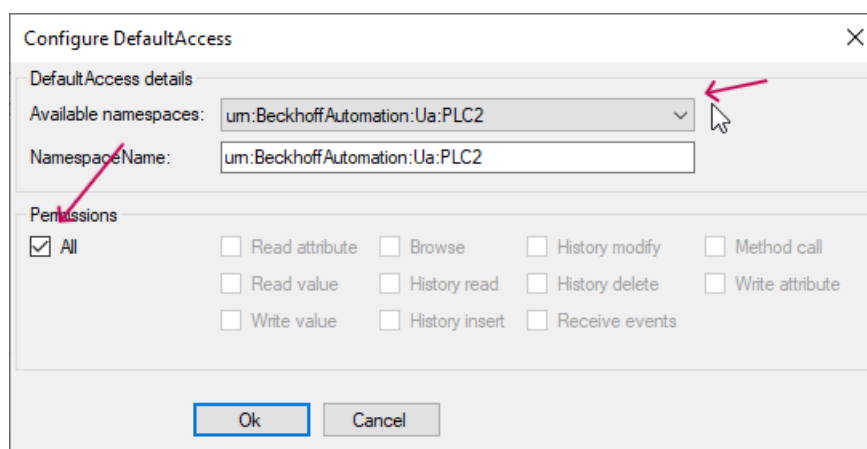


Fig. 4.26: . .



- Select *Server / Activate on target* to update the configuration and restart the *OPC UA Server*.

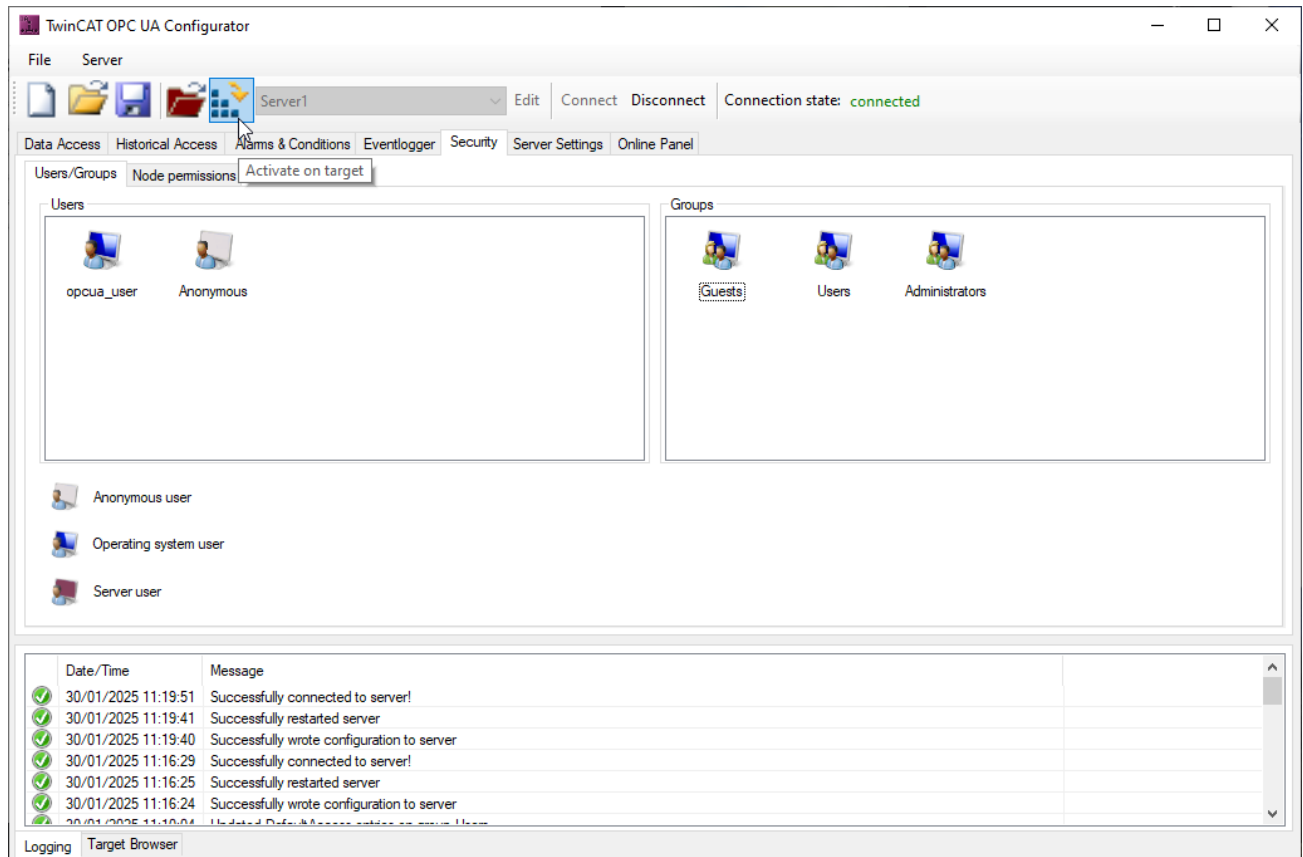


Fig. 4.27: . .

- At this point, the *OPC UA Server* should expose the data from the projects you have configured. This can be checked using *UaExpert*, as shown in Fig. 4.28.

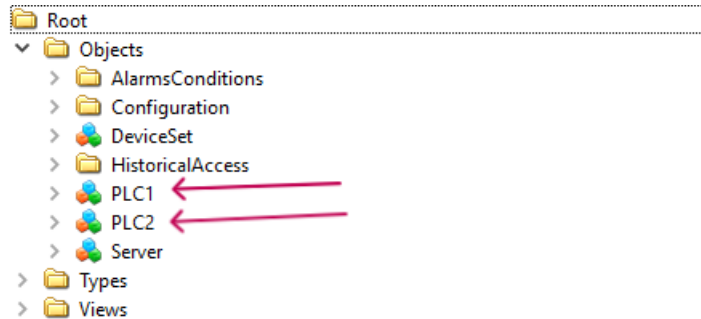


Fig. 4.28: . .

4.9 Configure OPC UA Server for TMC

The OPC UA Server Configurator program *TcOpcUaConfigurator.exe* is located under:

C:\TwinCAT\Functions\TF6100-OPC-UA\Win32\Configurator

By double-clicking on it, the configurator panel will pop up. Then one should *Connect*, click on *Server* / *Open from target*, and then double click on the PLC line. In most cases the user doesn't have to do anything since the system is already configured for the TMC notation. However, it is worth checking that everything is properly configured, as shown on Fig. 4.29.

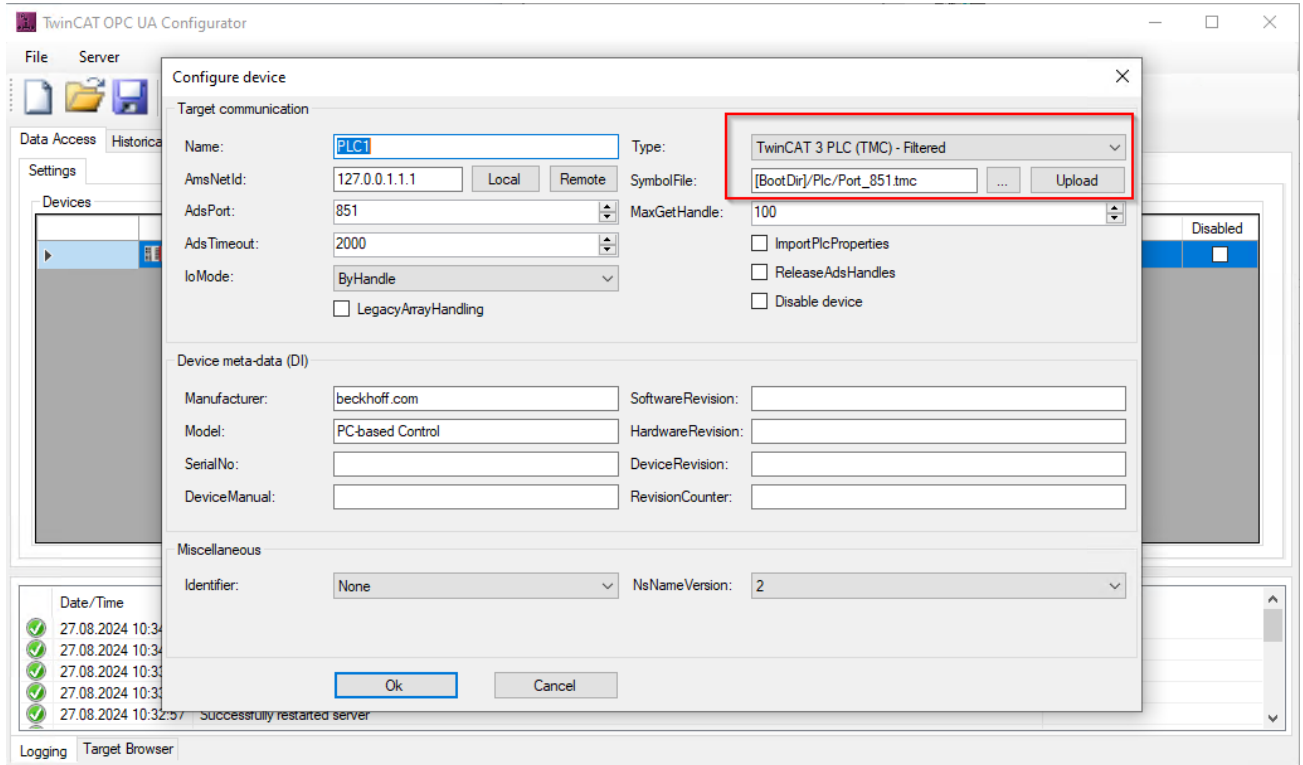


Fig. 4.29: OPC UA Server Configuration

Connecting to the Control Network

Once the PLC has been fully configured, it should be put on the control network and tested by creating a simple application with TwinCAT software.

Backup of Newly Configured System

Once it has been confirmed that the PLC is correctly configured and ready to use, it is highly recommended to do another backup of the system following the instructions given in section 4.1.

EL6688 (PTP) Configuration

This section explains how to configure terminal EL6688 in order to obtain external time references using PTP.

Assumptions:

- A PTP network connection is available and ready to use.
- The EL6688 hardware version is 10 or above.

- The EL6688 software version is 11 or above⁸.
- There is another DC-capable terminal in the EtherCAT network. This terminal is the one to be used by the EtherCAT master as a reference clock.
- EtherCAT cycle time: 1 ms recommended, with slower cycle times the synchronization becomes less exact.

The TwinCAT system does not update its internal time (Distributed Clocks time) but it delivers an offset to be used by the applications to derive the absolute time (UTC or TAI). Once the terminal EL6688 (see Fig. 4.30) has been added to the EtherCAT network, it is then possible to start its configuration following the steps described below.

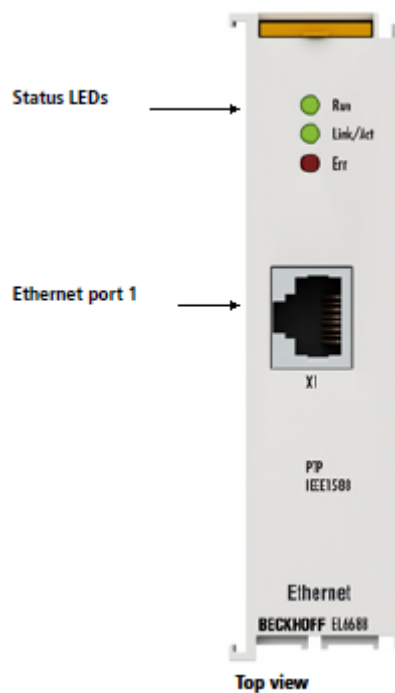
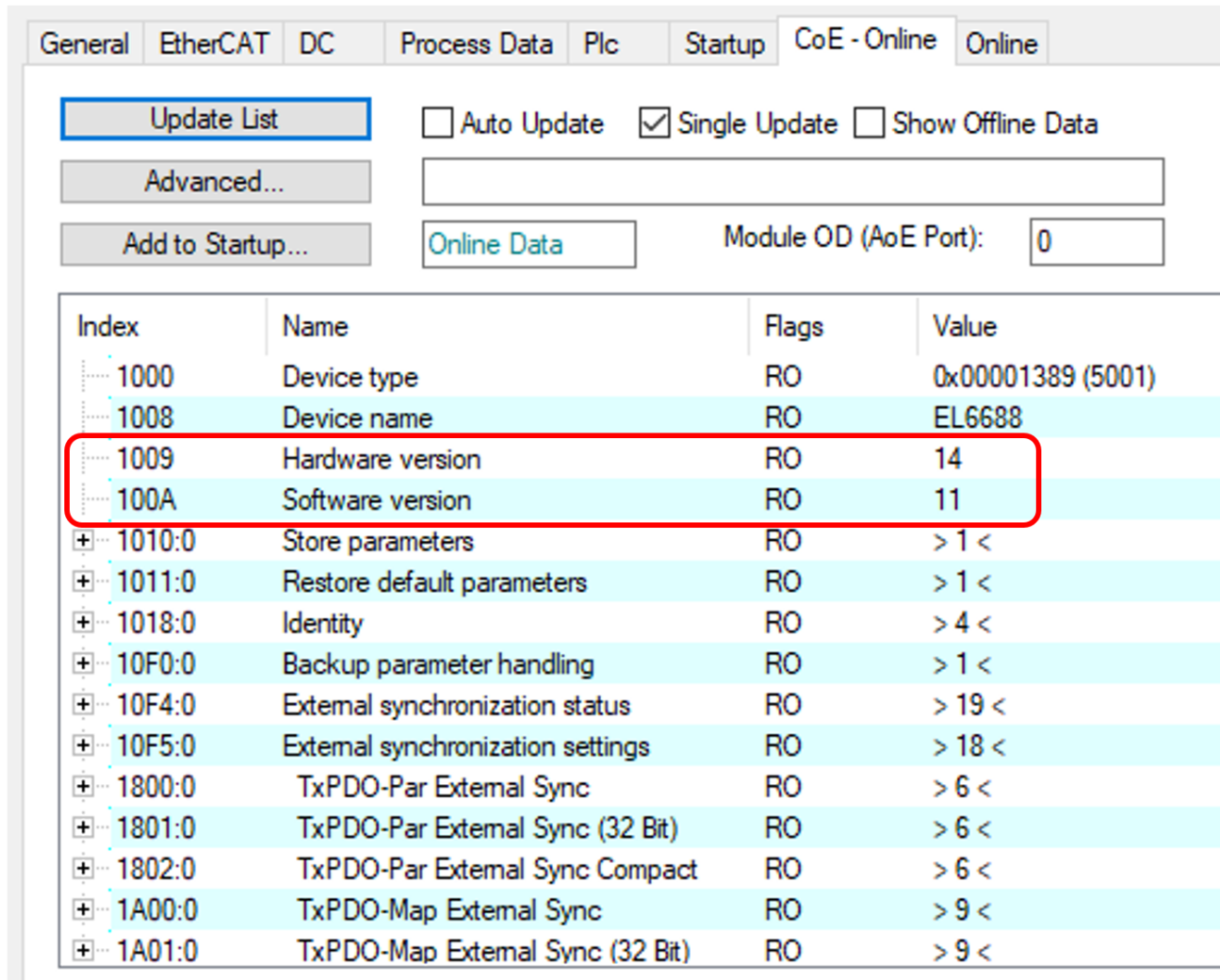


Fig. 4.30: Terminal EL6688 (PTP)

The hardware and software versions can be obtained from the terminal “CoE – Online” tab.

⁸ If these conditions are not met, the EL6688 might have problems working with switches due to a lack of support for IGMP protocol version 3. It can still be used but it requires static switch configurations.



General EtherCAT DC Process Data Plc Startup CoE - Online Online

Update List ☐ Auto Update ☒ Single Update ☐ Show Offline Data

Advanced...

Add to Startup... Online Data Module OD (AoE Port): 0

Index	Name	Flags	Value
1000	Device type	RO	0x00001389 (5001)
1008	Device name	RO	EL6688
1009	Hardware version	RO	14
100A	Software version	RO	11
+ 1010:0	Store parameters	RO	> 1 <
+ 1011:0	Restore default parameters	RO	> 1 <
+ 1018:0	Identity	RO	> 4 <
+ 10F0:0	Backup parameter handling	RO	> 1 <
+ 10F4:0	External synchronization status	RO	> 19 <
+ 10F5:0	External synchronization settings	RO	> 18 <
+ 1800:0	TxPDO-Par External Sync	RO	> 6 <
+ 1801:0	TxPDO-Par External Sync (32 Bit)	RO	> 6 <
+ 1802:0	TxPDO-Par External Sync Compact	RO	> 6 <
+ 1A00:0	TxPDO-Map External Sync	RO	> 9 <
+ 1A01:0	TxPDO-Map External Sync (32 Bit)	RO	> 9 <

Fig. 4.31: EL6688 CoE-Online tab

Changing CoE Settings

The EL6688 needs to be configured to enable the reception of PTP updates from the PTP master. Follow the steps according to what is described by the Beckhoff documentation.

1. Set EL6688 to PREOP This should be correctly reflected in the “*Current State*” field under the “Online” tab, see Fig. 4.32.

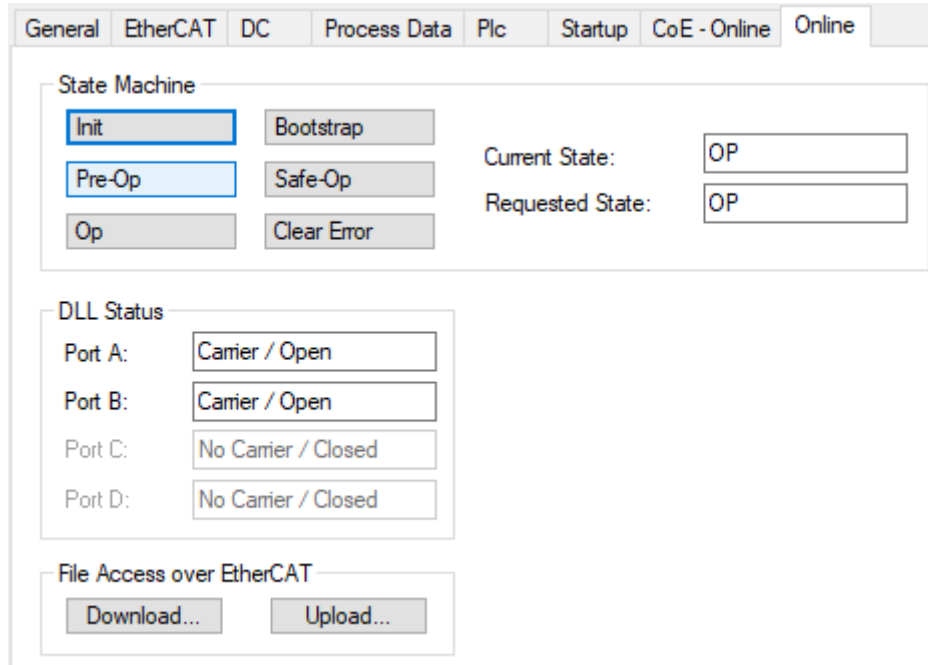


The screenshot shows the Beckhoff PLC configuration software interface. At the top, there is a navigation bar with tabs: General, EtherCAT, DC, Process Data, Plc, Startup, CoE - Online, and Online. The 'Online' tab is selected. Below the navigation bar, the 'State Machine' section is visible. It contains buttons for 'Init', 'Bootstrap', 'Pre-Op', 'Safe-Op', 'Op', and 'Clear Error'. The 'Pre-Op' button is highlighted with a blue border. To the right of these buttons, there are two text boxes: 'Current State:' and 'Requested State:', both containing the text 'PREOP'. Below the 'State Machine' section, the 'DLL Status' section is visible. It contains four text boxes labeled 'Port A:', 'Port B:', 'Port C:', and 'Port D:'. The 'Port A:' and 'Port B:' boxes contain the text 'Carrier / Open', while the 'Port C:' and 'Port D:' boxes contain the text 'No Carrier / Closed'. Below the 'DLL Status' section, the 'File Access over EtherCAT' section is visible. It contains two buttons: 'Download...' and 'Upload...'.

Fig. 4.32: EL6688 set to PREOP.

2. Set *CoE* parameters as shown in Fig. 4.34. Note that the *IP Address* in index F8E0:02 is entered as a single hex number by converting the four decimal numbers of the IP address into hex numbers. In the given example, the IP address is "192.168.1.15". The same rule is for the *Subnetmask* in index F8E0:03, in this case "255.255.0.0".
3. Enter the value 0x65766173 in index 1010:01⁶. This action will save permanently the parameters in the terminal.
4. Set EL6688 to INIT and then to OP.

⁶ http://infosys.beckhoff.com/content/1033/el6688/html/Bt_EL6688_ObjectDescription.htm



The screenshot shows the 'Online' tab of the Beckhoff PLC configuration software. The 'State Machine' section has buttons for 'Init', 'Pre-Op', 'Op', 'Bootstrap', 'Safe-Op', and 'Clear Error'. The 'Current State' and 'Requested State' are both set to 'OP'. The 'DLL Status' section shows four ports: Port A, Port B, Port C, and Port D, all set to 'Carrier / Open' or 'No Carrier / Closed'. The 'File Access over EtherCAT' section has 'Download...' and 'Upload...' buttons.

Fig. 4.33: EL6688 set back to OP.

Index	Name	Flags	Value	
F008	Code word	RW	0x00000000 (0)	
F880:0	PTP Common	RW	> 1 <	
F880:01	Precision Time Protocol	RW	IEEE1588-2008 (PTPv2) - Slave ...	Definition of the protocol. Here PTPv2 shall be selected (PTPv2 – Slave only Clock).
F881:0	PTPv1 Settings	RW	> 7 <	
F882:0	PTPv2 Settings	RW	> 9 <	
F882:01	Transport Layer	RW	LAYER 3 (PTP over UDP) (1)	Definition of the transport layer. Here PTP over UDP shall be selected.
F882:02	Domain Number	RW	0x0000 (0)	
F882:03	Sync Interval	RW	1 Second (0)	
F882:04	Delay Request Interval	RW	1 Second (0)	
F882:05	Delay Mechanism	RW	DISABLED (0)	
F882:06	Announce Interval	RW	2 Seconds (1)	
F882:07	Announce Interval Timeout	RW	3 Intervals (3)	
F882:08	Priority1	RW	0x0080 (128)	
F882:09	Priority2	RW	0x0080 (128)	
F8E0:0	Ethernet Settings	RW	> 4 <	
F8E0:01	Address Type	RW	FIXED (1)	
F8E0:02	IP Address	RW	0xC0A8010F (-1062731505)	Ethernet settings in hexadecimal.
F8E0:03	Subnetmask	RW	0xFFFF0000 (-65536)	
F8E0:04	Gateway	RW	0x00000000 (0)	
F8F0:0	Vendor data	RW	> 1 <	
FA80:0	PTP Diag	RO	> 15 <	

Fig. 4.34: EL6688 Relevant configuration parameters

After doing the above steps and if everything is connected properly, the EL6688 should start receiving packets. These can be seen in the *External Sync* parameters below the terminal in the solution



explorer, see Fig. 4.35. The “*External device not connected*” parameter shall be zero and the “*Control value update toggle*” shall toggle between 1 and 0.

Name	[X]	Online	Type	Size	>Addr...	In/Out
Sync Mode		0x2 (2)	BIT2	0.2	226.0	Input
Control value update toggle		0	BIT	0.1	227.5	Input
Time stamp update toggle		0	BIT	0.1	227.6	Input
External device not connected	X	0	BIT	0.1	227.7	Input
Internal time stamp	X	724426707148825630	ULINT	8.0	228.0	Input
External time stamp	X	724426746941825555	ULINT	8.0	236.0	Input
Control Value for DC Master Clock		999	DINT	4.0	244.0	Input

Fig. 4.35: EL6688 External Sync parameters

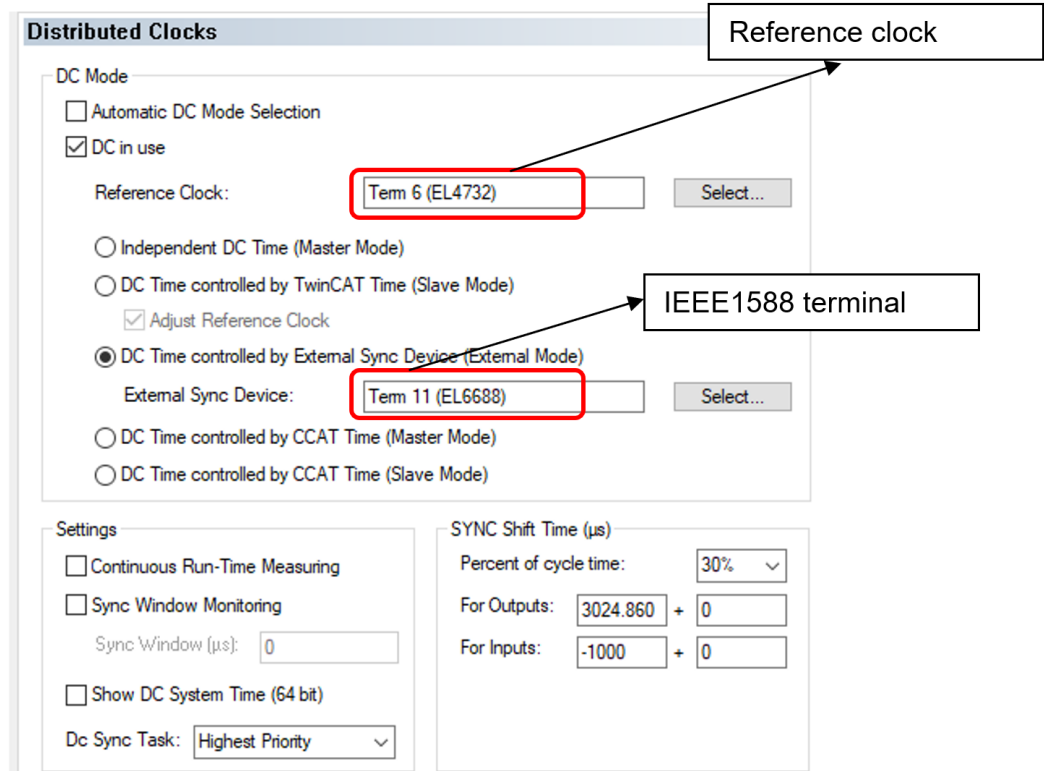
EtherCAT Configuration

In order to use the time from the IEEE1588 network, the EtherCAT master shall be configured accordingly. The above means that DC must be in use and the option ‘*DC time controlled by External Sync Device*’ must be selected. This is usually done automatically by the system which will attempt to select a DC-capable terminal as the reference clock. This terminal has to be installed before the EL6688 in the EtherCAT network. Whenever possible, it is recommended to use coupler EK1110 as a reference clock. In order to access this configuration, select the EtherCAT master (“*Device 1 (EtherCAT)*” as shown in Fig. 4.36) and then select “*Advanced Settings*” from the “*EtherCAT*” tab. Once this is done, the configuration is found under “*Distributed Clocks*”, see the example in Fig. 4.37.

Frame	Cmd	Addr	Len	WC	Sync Unit	Cycle (ms)	Utilizat
0	NOP	0x0000 0x0900	4			1.000	
0	ARMW	0xfffe 0x0910	4			1.000	
0	APWR	0xfffe 0x0910	4			1.000	
0	LRD	0x09000000	1			1.000	
0	LWR	0x01000000	127	1	<default>	1.000	

Fig. 4.36: EtherCAT master parameter window.

- State Machine
- Cyclic Frames
- Distributed Clocks**
- EoE Support
- Redundancy
- Diagnosis



Distributed Clocks

DC Mode

☐ Automatic DC Mode Selection

☒ DC in use

Reference Clock: Term 6 (EL4732) Select...

☐ Independent DC Time (Master Mode)

☐ DC Time controlled by TwinCAT Time (Slave Mode)

☒ Adjust Reference Clock

☒ DC Time controlled by External Sync Device (External Mode)

External Sync Device: Term 11 (EL6688) Select...

☐ DC Time controlled by CCAT Time (Master Mode)

☐ DC Time controlled by CCAT Time (Slave Mode)

Settings

☐ Continuous Run-Time Measuring

☐ Sync Window Monitoring

Sync Window (µs):

☐ Show DC System Time (64 bit)

Dc Sync Task: Highest Priority

SYNC Shift Time (µs)

Percent of cycle time: 30%

For Outputs: 3024.860 + 0

For Inputs: -1000 + 0

Reference clock

IEEE1588 terminal

Fig. 4.37: EtherCAT DC configuration.

EL6688 Diagnostic

Under the *CoE* parameters of the EL6688 terminal, one could find some diagnostic data that indicates how the terminal is functioning. The “*PTP State*” shall be in “SLAVE (9)” for a correct operation, see the example in Fig. 4.38.



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General EtherCAT DC Process Data Plc Startup CoE - Online Online

Update List ☐ Auto Update ☒ Single Update ☐ Show Offline Data

Advanced...

Add to Startup... [Online Data](#) Module OD (AoE Port): 0

Index	Name	Flags	Value	Unit
+ 1A02:0	TxPDO-Map External Sync Compact	RO	> 6 <	
+ 1C00:0	Sync manager type	RO	> 4 <	
+ 1C12:0	RxPDO assign	RW	> 0 <	
+ 1C13:0	TxPDO assign	RW	> 1 <	
+ 1C33:0	SM input parameter	RO	> 32 <	
+ F000:0	Modular device profile	RO	> 2 <	
F008	Code word	RW	0x00000000 (0)	
+ F880:0	PTP Common	RW	> 1 <	
+ F881:0	PTPv1 Settings	RW	> 7 <	
+ F882:0	PTPv2 Settings	RW	> 9 <	
+ F8E0:0	Ethernet Settings	RW	> 4 <	
+ F8F0:0	Vendor data	RW	> 1 <	
- FA80:0	PTP Diag	RO	> 15 <	
FA80:01	PTP Version	RO	PTPv2 (IEEE1588-2008) (32)	
FA80:02	PTP State	RO	SLAVE (9)	
FA80:03	Clock Identity	RO	00 01 05 FF FE 68 62 20	
FA80:04	Parent Port Identity	RO	BC 26 C7 FF FE 0F 6B 80 00 09	
FA80:05	Grandmaster Identity	RO	EC 46 70 FF FE 0A 9F 22	
FA80:06	Offset From Master (ns)	RO	-5	
FA80:07	Mean Path Delay (ns)	RO	128	
FA80:08	Steps Removed	RO	0x0003 (3)	
FA80:09	Sync Event Sequence Number	RO	0x0CC8 (3272)	
FA80:0A	Timescale	RO	PTP (TAI) (1)	
FA80:0B	CurrentUtcOffset	RO	37	
FA80:0C	CurrentUtcOffsetIsValid	RO	TRUE (1)	
FA80:0D	Leap61	RO	FALSE (0)	
FA80:0E	Leap59	RO	FALSE (0)	
FA80:0F	Epoch_Number	RO	0x0000 (0)	

Fig. 4.38: EL6688 Diagnostic

5 Keeping PLC Up to Date

From time-to-time Beckhoff releases new versions of TwinCAT software. It is a good practice to follow the releases and keep the PLC SW (as well as the TwinCAT SW on the PC) up to date.

If not already done, create a Data directory on the PLC. This directory can be used to store various installation files.

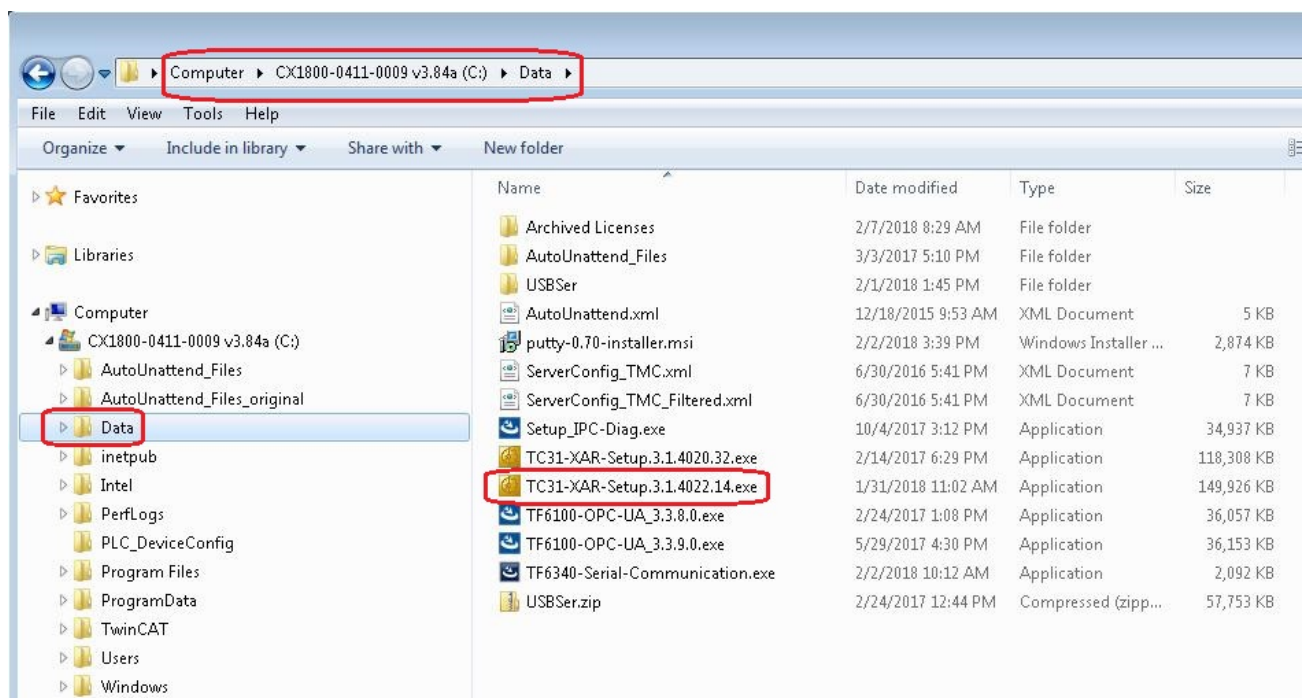


Fig. 5.1: PLC Data Directory

5.1 TwinCAT Runtime Update

To download latest TwinCAT software, go to www.beckhoff.com and navigate to: *Download/Software/TwinCAT 3/TE1xxx / Runtime* and select the latest version of *TwinCAT 3.1 – eXtended Automation Runtime (XAR)*.

After the download, unzip the file and copy it to the Data directory on the target PLC using the Remote Desktop.

Fig. 5.1 shows an example file TC31-XAR-Setup.3.1.4022.14.exe. Double-click on the file and follow the instructions. The update takes just a couple of minutes. At the end of the installation, the system will have to be rebooted.

A video showing how to install new version of TwinCAT Runtime can be found [here](https://europeansouthernobservatory-my.sharepoint.com/personal/jhaucke_eso_org/CSE/cins/cins_public/SharedDocuments/PLCMaterial/Videos/PLC_Setup__TC31-XAR_Installation.mp4)⁷.

⁷ https://europeansouthernobservatory-my.sharepoint.com/personal/jhaucke_eso_org/CSE/cins/cins_public/SharedDocuments/PLCMaterial/Videos/PLC_Setup__TC31-XAR_Installation.mp4

5.2 How to Check TwinCAT Runtime Version

To check the version of currently installed TwinCAT Runtime, firstly log into the PLC. Click on the *TwinCAT* icon in the lower right corner and select *About TwinCAT...*

A window *About TwinCAT System* will pop up showing, among the others, the version, the performance platform and the status of the licenses (see Fig. 5.2).

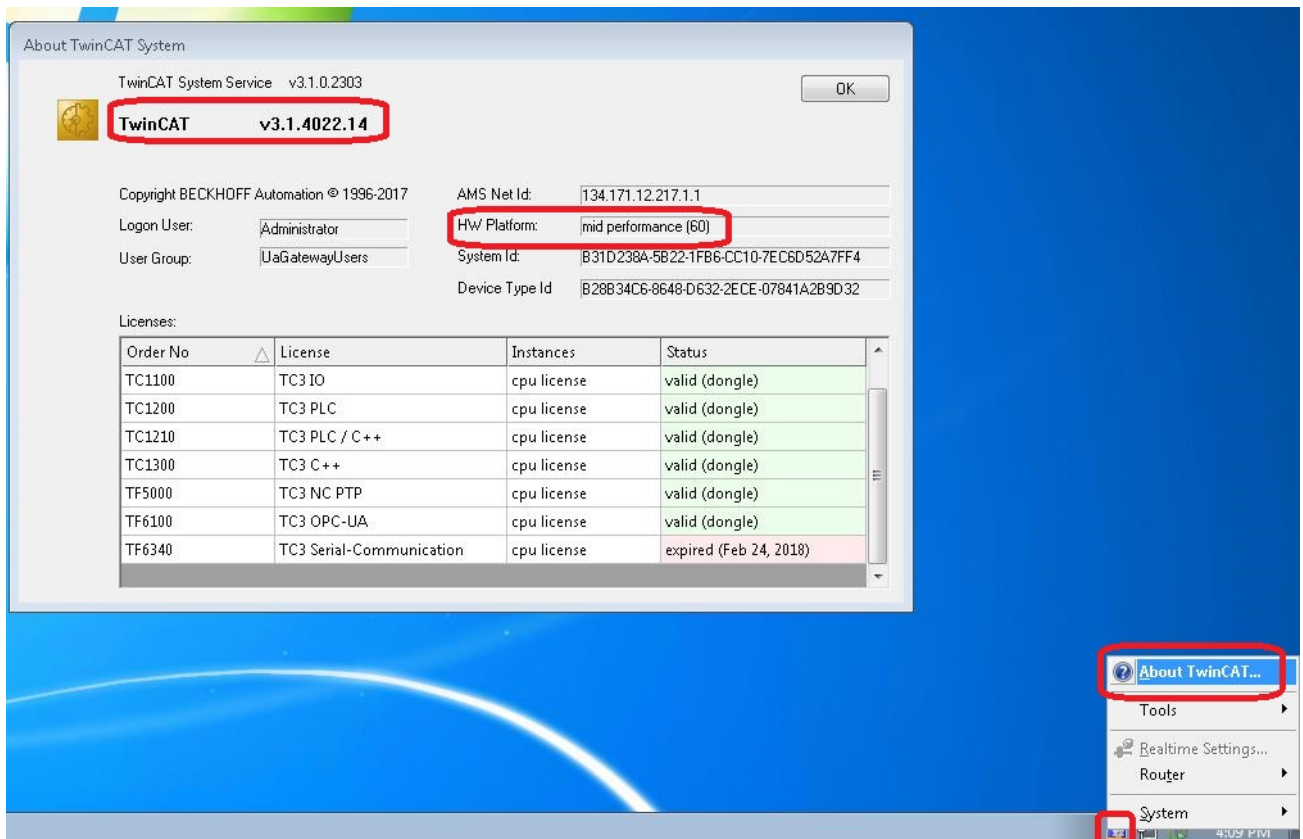


Fig. 5.2: TwinCAT Runtime Version

6 Uninstalling Existing OPC UA Server

To properly uninstall an existing OPC UA Server, several steps should be taken. This is necessary when one wants to reinstall the server to modify some of the decisions taken during the original installation, or when migrating from Servers versions prior to version 4.4.0. The process also includes the removal of the *opcua_user* user.

1. Connect to the PLC via Remote Desktop
2. In Apps & Features (or Programs and Features on some machines) uninstall *Beckhoff TF6100 OPC-UA Configurator*
3. In Apps & Features (or Programs and Features on some machines) uninstall *Beckhoff TF6100 OPC-UA Server*
4. Remove the folder: C:\TwinCAT\Functions\TF6100-OPC-UA
5. Remove the folder: C:\ProgramData\Beckhoff\TF6100-OPC-UA
6. Remove the folder: C:\ProgramData\Beckhoff\TF6100-OPC-UA-Server
7. Remove the local users *opcua_user*:
 - a. Right click on *Start*
 - b. Click on *Computer management*. The same can be achieved by right-clicking on *Computer* in the *Windows Explorer* and selecting *Manage*.
 - c. On the left pane: *Local Users and Groups > Users*
 - d. Delete the necessary users by right clicking on the name and selecting *Delete*.

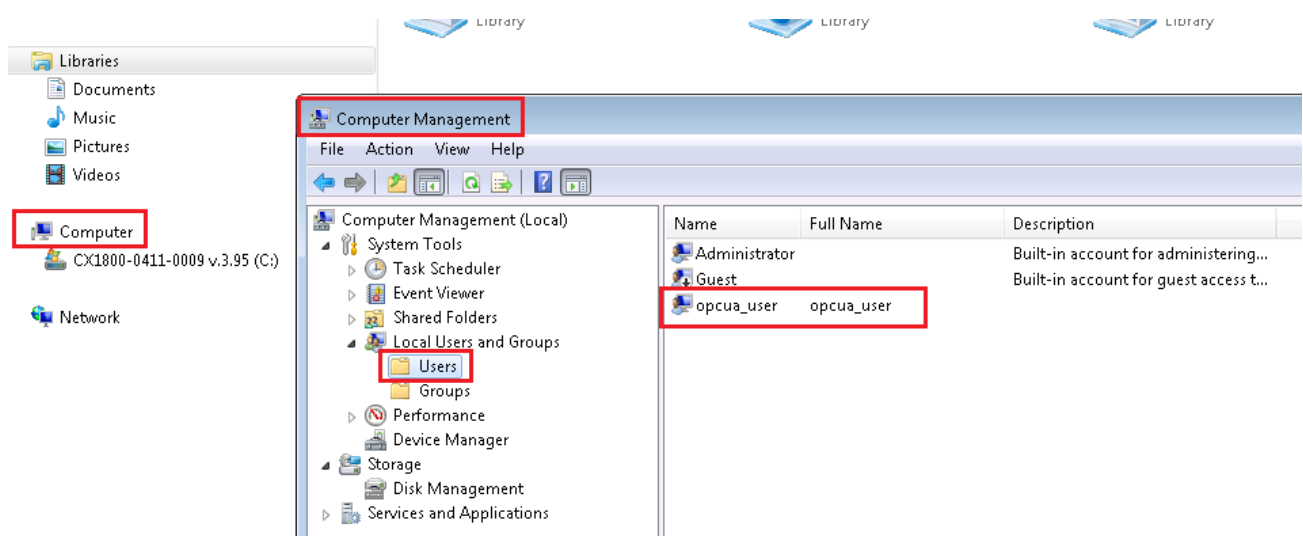


Fig. 6.1: . .

8. Reboot the PLC

7 Migration to TwinCAT Build 4026

7.1 Introduction

With TwinCAT Build 4026, Beckhoff introduces a major update to TwinCAT 3.1. Installation or migration to Build 4026 is only possible using the TwinCAT Package Manager. The TwinCAT Package Manager can be downloaded from the Beckhoff website. The general installation process for Build 4026 is the same for both an engineering PC and a target PLC system. The only differences are the packages installed using the TwinCAT Package Manager. A detailed description of the installation process using the TwinCAT Package Manager is provided in a later section. It is important to note that migration to Build 4026 and the installation of packages can be performed either with or without an Internet connection. Second case might be a common case for PLC-systems in productive systems. A documentation when working on an offline system is provided by Beckhoff: https://infosys.beckhoff.com/english.php?content=../content/1033/tc3_installation/20646399115.html&id==

This documentation first provides an overview of the general installation process with an Internet connection. It then describes the process in detail using a concrete example of an offline installation.

The tested scenarios are shown in following figure:

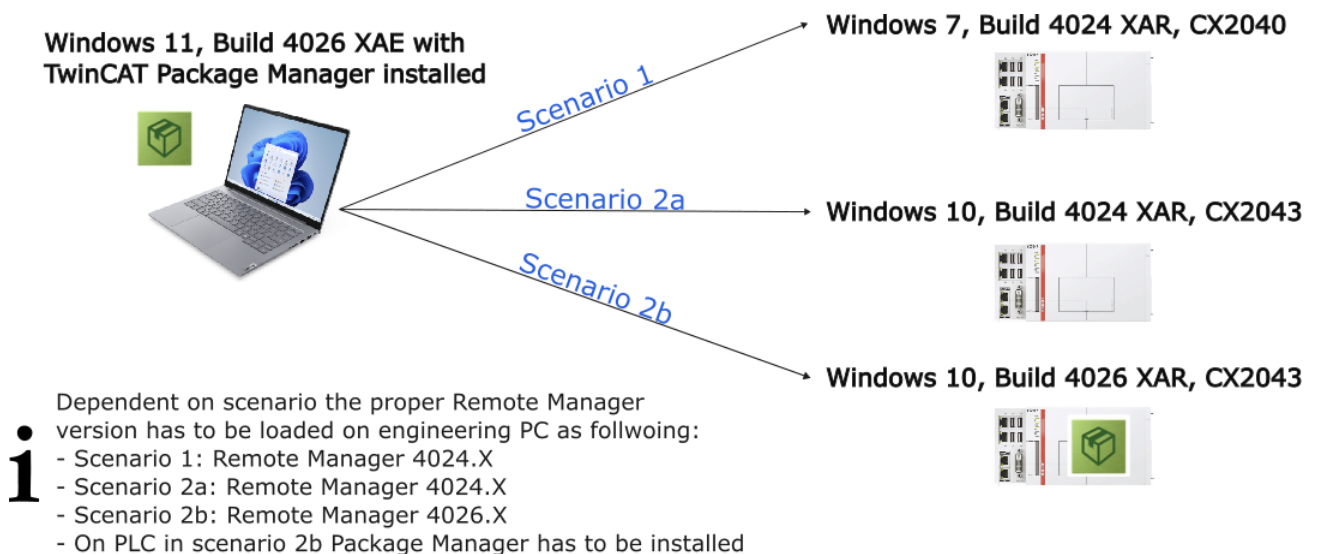


Fig. 7.1: Test scenarios

7.2 Required Base Packages for TwinCAT 4026 XAE Installation

Base packages for engineering PC applying to all scenarios:

- TwinCAT.Standard.XAE
- TwinCAT.StandardRM.XAE 4024.x

Note: Only if additional package 'TwinCAT.StandardRM.XAE 4024.x' is installed the engineering PC can connect to PLC systems with runtime < Build 4026. Via the TcXaeShell, older Remote Manager versions can be loaded by pre-selection in drop-down list.

The list of installed Remote Manager packages in this example is shown below.

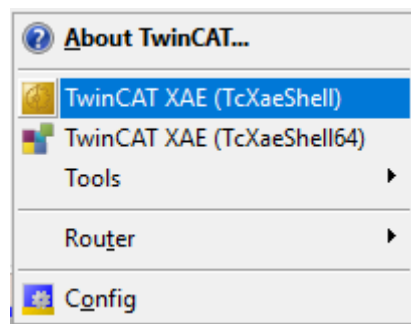


Fig. 7.2: Selection of TcXaeShell

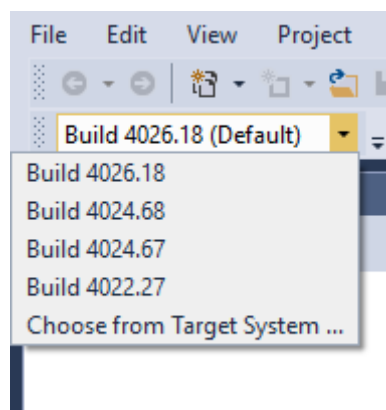


Fig. 7.3: Selection of Remote Manager version

Base package for PLCs applying for scenario 2b:

- TwinCAT.Standard.XAR



7.3 Migration from TwinCAT 4024 XAE to Build 4026 - General Steps

- Download and install the Beckhoff TwinCAT Package Manager
- Add the required feeds
- Install the migration tool as package named *TwinCAT.XAE.MigrateCli*
- Execute the migration tool *TwinCAT.XAE.MigrateCli*
- Install the package named *TwinCAT.Standard.XAE*
- Install the package named *TwinCAT.StandardRM.XAE*
- Install the package named *TwinCAT.StandardRM.XAE=4024.x* to be able to target PLCs that are running with Build 4024

7.4 TwinCAT Package Manager

The TwinCAT Package Manager (TcPkg) is a tool by Beckhoff and is used to manage software packages and extensions that integrate installed packages into TwinCAT system. TcPkg can be used with GUI or via CLI (Command Line Interface). Both provide the same core purpose. While the GUI-Version provides a user-friendly and intuitive interface, working with CLI-version is faster and ideal for automation and scalable solutions, although interfacing is less intuitive for new users than the GUI-Version.

7.5 Download and Installation of the TwinCAT Package Manager

Downloading the TwinCAT Package Manager executable file is possible from Beckhoff website. Installation process is clear, as no configurations needed to be done. TcPkg-path is added to environment variables by installation. As result commands via `tcpkg` are directly executable with PowerShell or CMD-terminal. At the time of testing and documentation TcPkg-version 2.2.101 was used.

Note: Installations of packages via `tcpkg`-command requires permissions of an administrator for PowerShell or CMD-terminal. In this documentation PowerShell is preferred compared to CMD-terminal, because of its more advanced scripting capabilities.

7.6 Adding Feeds

Feeds are package repositories that provide versioned packages to TCPKG for installation, updates, and dependency restoration.

- *Stable feed*: Open PowerShell and the following input (Please be beware of, that your individual Beckhoff login data needs to be added):



```
tcpkg source add -n="Beckhoff Stable Feed" -s= "https://public.tcpkg.beckhoff-cloud.com/api/v1/feeds/Stable" --priority= 1 -u= "[YOUR BECKHOFF LOGIN MAILADDRESS]" --password "[YOUR BECKHOFF LOGIN PASSWORD]" -y
```

- *Outdated feed* (is required to install Remote Manager 4024.X to target PLC with older runtime builds installed):

```
tcpkg source add -n="Beckhoff Outdated Feed" -s= "https://public.tcpkg.beckhoff-cloud.com/api/v1/feeds/Outdated" --priority= 2 -u= "[YOUR BECKHOFF LOGIN_MAILADDRESS]" --password "[YOUR BECKHOFF LOGIN PASSWORD]"
```

Note: With 'y'-flag at the end of line adding for 'Stable-Feed' can be confirmed directly. It is no longer possible to use this flag when adding the 'Testing-feed' or the 'Outdated-feed'.

Following table provides an overview with all available feeds:

Feed Name	URL	Notes
Stable	https://public.tcpkg.beckhoff-cloud.com/api/v1/feeds/Stable	Production-ready, stable releases
Testing	https://public.tcpkg.beckhoff-cloud.com/api/v1/feeds/Testing	Beta/preview versions for testing
Outdated	https://public.tcpkg.beckhoff-cloud.com/api/v1/feeds/Outdated	Legacy/older tools, not actively maintained

7.7 Installation and Using of the Migration Tool

Input command:

```
tcpkg install TwinCAT.XAE.MigrateCli -y
```

Input command:

```
TcMigrateCmd clean --whatIf=false -y
```

This will remove all TwinCAT Build 4024 files.

Note: If on your system already TwinCAT Build 4026 packages are installed, migration tool will exit with an error. With **TcMigrateCmd clean** command, cleaning can be simulated before and checked, if command works without errors.



7.8 Installation of the Engineering Package XAE

Input command:

```
tcpkg install TwinCAT.Standard.XAE -y
```

7.9 Installation of the Remote Manager

Input command:

```
tcpkg install TwinCAT.StandardRM.XAE -y
```

Install the package named 'TwinCAT.StandardRM.XAE=4024.X' to be able to target PLCs with < Build 4026

Input command with concrete example for minor revision X=68.1:

```
tcpkg install TwinCAT.StandardRM.XAE=4024.68.1 -y
```

7.10 Migration to Build 4026 in Scripted Version (dev)

To automatically start all commands, the PowerShell ISE (Integrated Scripting Environment) can be used. Open it with administrator permissions. The following script is tested a few times, but includes no error handling or error logging. It needs more extensions and is not supposed to use in productive systems.

Note: At the time of documentation and testing downloading of TwinCAT Package Manager needs to be done manually before executing the script. Also adding the 'Outdated' feed must be done manually, because confirmation of disclaimer at adding feed process is no longer possible with 'y'-flag.

```
tcpkg source add -n="Beckhoff Stable Feed" -s= "https://public.tcpkg.beckhoff-cloud.  
com/api/v1/feeds/Stable" --priority= 1 -u= "[YOUR BECKHOFF LOGIN MAILADDRESS]" --  
password "[YOUR BECKHOFF LOGIN PASSWORD]" -y  
tcpkg install TwinCAT.XAE.MigrateCli -y  
TcMigrateCmd clean --whatIf=false -y  
tcpkg install TwinCAT.Standard.XAE, TwinCAT.StandardRM.XAE -y  
tcpkg install TwinCAT.StandardRM.XAE=4024.68.1 -y
```

Processing the script took 14 to 15 minutes on test computer [(Intel(R) Core(TM) Ultra 5 238V (2.10 GHz)].



7.11 Installation of the TwinCAT 4026 XAR Using NC PTP, Tcp IP and OPC UA Packages as Example

Prerequisites

- Access to the PLC via Remote Desktop
- Administrator privileges on the PLC PC
- Folder containing the installation packages. In the following example, C:\TC_Packages is used.

Required Packages in this Example (Dependencies not listed)

- TwinCAT-Package-Manager-GUI-Setup.exe
- TwinCAT.XAE.MigrateCli.1.0.860.nupkg
- TwinCAT.Standard.XAR.4026.22.0.nupkg
- TwinCAT.XAR.OpcUaClient.2.2.36.nupkg
- TF5000.NCPTP.XAR 3.1.5049
- TF6100.OpcUaServer.XAR.5.4.6.nupkg
- TF610x.OpcUaClientPubSub.XAR.2.0.2.nupkg
- TF6310.TcpIp.XAR.3.3.24.nupkg

Installation Procedure

1. Connect to the PLC: Connect to the target PLC using the Remote Desktop.
2. Download the *TwinCAT Package Manager* and copy the executable file to the desktop of the PLC.
3. Create the following directory on the PLC PC: C:\TC_Packages.
4. Copy the TwinCAT packages to be installed to C:\TC_Packages.

Note: The packages share common dependencies. Replace duplicate files if prompted during the copy process.

5. Run the installer *TwinCAT-Package-Manager-GUI-Setup.exe*. Follow the installation wizard and complete the installation.
6. Wait until the installation is complete and click 'Close'.
7. Open a PowerShell terminal with Administrator permissions.
8. Execute the following command to add the local package feed:

```
tcpkg source add -n="Local Feed" -s="C:\TC_Packages" --priority=1
```

After executing the command, PowerShell may display a confirmation prompt like the example shown in the picture.

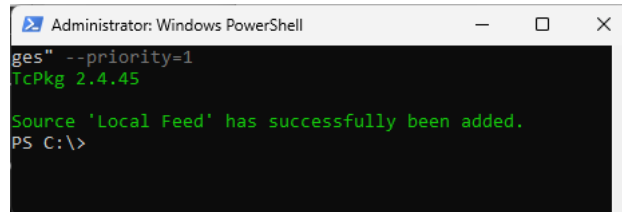


Fig. 7.4: PowerShell Output

9. Check whether the packages are detected correctly:

```
tcpkg list
```

10. Install the migration tool using:

```
tcpkg install TwinCAT.XAE.MigrateCli -y
```

11. Close PowerShell.

Note: The migration tool will not be recognized until PowerShell is restarted.

12. Open PowerShell again with administrator privileges.
13. Start migration tool by executing following command:

```
TcMigrateCmd clean --whatIf=false -y
```

14. Wait until TwinCAT Build 4024 has been completely uninstalled. After the migration process, the PLC will automatically restart and finalize the migration procedure.
15. After the PLC has restarted, open PowerShell as Administrator again and install the required packages:

```
tcpkg install TF5000.NCPTP.XAR, TF6100.OpcUaServer.XAR, TF610x.
→OpcUaClientPubSub.XAR, TF6310.TcpIp.XAR, TwinCAT.Standard.XAR -y
```

During the installation process, a Windows Security dialog box may appear asking for confirmation to install driver software.

16. If the command prompt returning (e.g., PS C:>) appears again, then TwinCAT Build 4026 XAR is successfully installed.